Very-long-period seismicity over the 2008-2018 eruption of Kīlauea Volcano

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Key Points:

- Developed workflow for cataloging VLP volcano seismicity with wavelet transforms
- Timeline of 2008-2018 Kīlauea Volcano magma resonance shows variability over hours to years
- Identified variable correlations between VLP seismicity, ground deformation, and lava-lake elevation at Kīlauea Volcano

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Abstract

Very-long-period (VLP) volcano seismicity often represents subsurface magma movement, and thus provides insight into magma system geometry and magma properties. We develop a fully automated signal processing workflow using wavelet transforms to detect and assess period, decay rate, and ground motions of resonant VLP signals. We then generate and analyze a catalog of VLP seismicity over the 2008-2018 open-vent summit eruptive episode at Kīlauea Volcano, Hawaii USA. VLP seismicity occurred throughout this eruption that involved a persistent lava-lake, multiple intrusions and rift zone eruptions, and a climactic caldera collapse. We characterize trends in two dominant magma resonances: the fundamental eigenmode of the shallow magma system is a vertical oscillation of the magma column in the conduit and lava-lake, and higher frequency eigenmodes largely consist of lateral lava-lake sloshing. VLP seismicity was mainly triggered by lava-lake surface perturbations, and less commonly from depth. Variation in periods and quality factors occurred on timescales from hours to years. VLP seismicity exhibited varying correlations over time with other datasets such as ground tilt, SO_2 emissions, and lava-lake elevation. Variation in VLP properties also occurred over days to months preceding and following intrusions and rift zone eruptions. Changes in VLP ground motions over various timescales indicate evolution of shallow magma system geometry, which contributed to the variation in resonance. However much of the variation on timescales less than months is likely from changing magma density and viscosity, reflecting a variable shallow magmatic outgassing and convective regime within the open conduit over the ten year eruption.

1 Introduction

Volcano seismicity provides vital information for studying processes inside volcanoes and for monitoring changes in volcanic activity that inform hazards (e.g., Chouet & Matoza, 2013; Ripepe et al., 2015; McNutt & Roman, 2015). Amongst the rich variety of seismic signals that are commonly observed at volcanoes, so-called very-long-period (VLP) seismic events are of particular interest for magmatism as they likely represent fluid movement and/or resonance in magmatic transport structures (e.g., Chouet & Matoza, 2013; Jolly et al., 2017; Cesca et al., 2020). This type of seismicity can provide otherwise unobtainable in situ insight into magma properties and magma plumbing system geometry, and can be sensitive to different properties of the system than the longer timescale deformation observed with geodesy (e.g., Kumagai, 2006; Chouet et al., 2008; Dawson et al., 2011).

VLP seismicity is typically defined as having a disproportionate amount of energy at periods greater than ∼2 s (Chouet & Matoza, 2013). VLP seismicity can occur as isolated impulses, oscillations persisting for multiple cycles (often exhibiting roughly exponential decay over time), or tremor that can persist for hours-days or longer; and waveforms can be either periodic (with energy focused into discrete spectral peaks including harmonics), exhibit 'gliding' frequencies that change smoothly over time, or irregular (e.g., Aster et al., 2008; Arciniega-Ceballos et al., 2008; Haney et al., 2013; Chouet & Matoza, 2013). VLP seismicity at volcanoes has been proposed to represent various processes including magma transport through constrictions, bubble slug ascent, pressure changes in hydrothermal systems, or resonant oscillations of magma flowing within plumbing system components (e.g., Kumagai et al., 2003; Aster, 2003; Lokmer et al., 2008; Nakamichi et al., 2009; Chouet & Matoza, 2013; Dawson & Chouet, 2014; Cesca et al., 2020). Signals in volcanic settings that have been proposed to represent resonance of either magma or hydrothermal fluids often also occur in the so-called long-period (LP) band (typically 0.2-2 s) (e.g., Chouet & Matoza, 2013; Chouet & Dawson, 2016), and some can also be detected in infrasound data (e.g., Garcés et al., 2009; Fee & Matoza, 2013; Matoza et al., 2018). Isolated VLP events have been documented to be triggered by a variety of processes including eruptions, gas slug release, rapid depressurization of magmatic or hy-

drothermal features, rockfalls into a lava-lake, or tectonic events (e.g., Lyons & Waite, 2011; Maeda & Takeo, 2011; Orr et al., 2013; Chouet & Matoza, 2013). Persistent forcing could be caused by repeating discrete triggers or processes such as magma flow through irregular channels, bubble-cloud oscillations, or turbulence (e.g., Julian, 1994; Hellweg, 2000; Matoza et al., 2010; Unglert & Jellinek, 2015).

Here we develop an automated signal processing workflow for cataloging VLP seismic events from continuous seismic data, then apply this workflow to generate and analyze a catalog of VLP seismicity at Kīlauea Volcano from 2008-2018. We focus on classifying signals that consist of periodic oscillations with impulsive onsets and monotonic decays in amplitude over time, as are produced by damped magma resonance. Our methods yield more robust and precise estimates of quality factors than previous approaches and are readily applicable to near-real-time monitoring and/or to other volcanic settings. Our catalog reveals the rich dynamics of Kīlauea VLP seismicity, which we contextualized by comparing to other geophysical data and observed volcanic activity. We argue that this catalog informs the evolution of the Kīlauea shallow magma system over 10 years, representing a unique window into the dynamics of a long-lived open-system eruption.

1.1 Cataloging VLP seismicity

Numerous studies have created catalogs of long-period and very-long period volcanic seismicity (e.g., Battaglia, 2003; Aster et al., 2008; Dawson et al., 2010; Zuccarello et al., 2013; Dawson & Chouet, 2014; Knox et al., 2018; Wech et al., 2020; Park et al., 2020). These signals can require different detection approaches than tectonic earthquakes, and all the previously used approaches have some limitations that motivate development of a new workflow for cataloging the resonant signals of interest here.

Time-domain moving short-term-average/long-term-average (STA/LTA) detectors will miss many events with small signal/noise ratios (Schaff, 2008). Correlation-based template matching can be much more sensitive (Schaff, 2008) and has been used to detect long-period seismicity (e.g., Aster et al., 2008; Wech et al., 2020; Park et al., 2020), but is better suited to detecting repeating events than signals that exhibit a continuum of variation (i.e., in periods, decay rates, and trigger mechanisms) and is computationally slow (Yoon et al., 2015). Approaches using feature-extraction to create and cluster waveform 'fingerprints' thus far are also best suited to detecting repeating events (Yoon et al., 2015). Supervised machine learning approaches can be effective for detecting earthquakes (e.g., Perol et al., 2018; Jennings et al., 2019; Bergen & Beroza, 2019) and very-long-period seismicity (Dawson et al., 2010), but can require lots of pre-selected training examples, may not detect new types of signals robustly, will generally need at least partial re-design and/or re-training to be applied to new networks/volcanoes, and their 'black box' nature can make predicting when or why they fail difficult (e.g., Bell, 2014; Goodfellow et al., 2016). Unsupervised learning methods have been used to cluster seismic data (Kohler et al., 2010; Mousavi et al., 2019), but have not yet been demonstrated to generate accurate or comprehensive event catalogs.

Accurately categorizing resonant VLP signals is also important, since the dominant periods, decay rates (quantified by quality factor Q, a ratio of energy stored to energy lost per cycle), and source motions (from ground motion patterns) can encode the underlying mechanism (e.g., Kumagai & Chouet, 2000; Kumagai et al., 2010). Several methods have previously been used to estimate Q. The simplest is to calculate the full width at half the maximum amplitude (FWHM) of peaks in the power spectrum. This technique is often inaccurate in the presence of noise, complicated signal shapes, or multiple signals with similar frequency components (e.g., Kumazawa et al., 1990; Zadler et al., 2004). To overcome this limitation, autoregressive (AR) methods that fit decaying sinusoids to the coda of signals were developed (Kumazawa et al., 1990; Nakano et al., 1998; Lesage et al., 2002). When the coda of a signal can be appropriately isolated these

methods work well for classifying dominant resonant oscillations. However, they often do not accurately detect or estimate Q of secondary oscillations or oscillations with coda interrupted by other signals (Fig. S1). Bandpass filtering can help isolate signals, but often a narrow passband is required which artificially increases Q (Kumazawa et al., 1990).

We use continuous wavelet transforms (CWTs) to detect and classify T, Q, and ground motion patterns of resonant VLP seismic signals. CWTs are a method for determining the frequency content of signals over time (e.g., Alsberg et al., 1997; Selesnick et al., 2005) that have been previously used to analyze volcano seismicity and suggested as a means for automated signal detection and classification (Lesage, 2009; Lapins et al., 2020). Our methods can robustly determine T and Q in the presence of high noise, multiple resonant frequencies, and overlapping signals. These methods are also readily extendable to characterizing resonant signals in the LP band and in infrasound data, as well as some periodic tremor and gliding-frequency signals, but are likely not the optimal approach for analyzing signals that are not periodic. Our approach does not depend upon training data or templates, and thus can be applied to any instrument network or volcano with minimal configuration.

1.2 The 2008-2018 eruption of Kīlauea Volcano

We examine the 2008-2018 summit eruptive episode of Kīlauea Volcano, a basaltic shield volcano on the island of Hawaii. This was the most recent period of continuous summit activity following decades of quiescence or sporadic events largely focused along the East Rift Zone (ERZ) (e.g., Wright & Klein, 2014). Over this timespan a summit lava-lake persisted at the surface, then drained as part of a caldera collapse eruption sequence in May-August 2018 (e.g., Neal et al., 2019; Patrick, Orr, et al., 2019; Patrick, Swanson, & Orr, 2019). Kīlauea is one of the best monitored volcanoes in the world, with abundant data on ground deformation (from tilt-meters, GPS/GNSS stations, and InSAR), gas flux, magma composition, and lava-lake activity (e.g., Edmonds et al., 2015; Elias et al., 2018; Patrick, Swanson, & Orr, 2019) that can contextualize VLP seismicity.

The U.S. Geological Survey Hawaii Volcano Observatory operates a dense broadband seismic network at Kīlauea Volcano. VLP seismicity at Kīlauea has previously been cataloged up to 2013 using a hidden Markov model to detect events and the Sompi AR method to determine T and Q of these events (Dawson et al., 2010; Dawson & Chouet, 2014); this existing catalog provides an important benchmark for our methods. We find prevalent VLP seismicity over the 2008-2018 timespan, representing a rich probe of changes within the shallow subsurface magma system of Kīlauea Volcano on a variety of timescales.

2 Methods

2.1 Seismic data

The first step in our workflow is selecting and processing seismic data (Fig. 1). We use waveforms from 3-component broadband seismometers in the Hawaii Volcano Observatory (HVO) network (USGS, 1956) that are within ∼3 km of the vent. We use available data from the following stations: NPB, NPT, SRM, OBL, WRM, SDH, UWE, UWB, SBL, KKO, and RIMD (Fig. 2, 3). Some other stations in the area were not used due to low signal/noise ratios. Seismic data from 2008-2011 was obtained from the USGS, subsequent data is publicly available from IRIS (Incorporated Research Institutions for Seismology). We download and process data in 6 hr time windows and discard waveforms with data gaps longer than 2 s.

We deconvolve the instrument responses to facilitate stacking of data from different instruments (Fig. S2). A standard 'water level' is first applied to these instrument

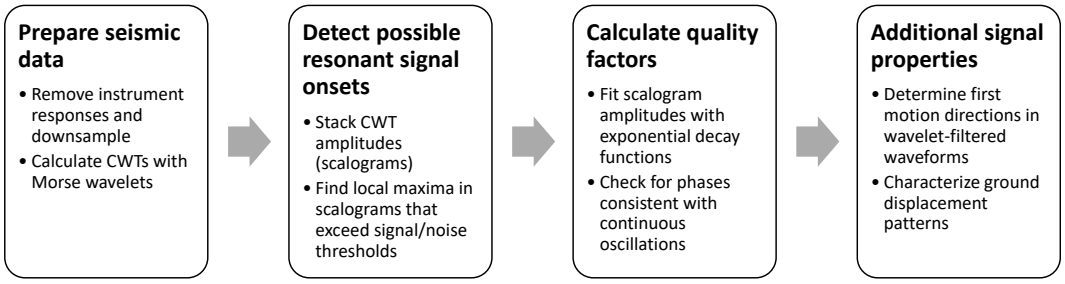

Figure 1. Signal processing workflow for VLP detection and characterization.

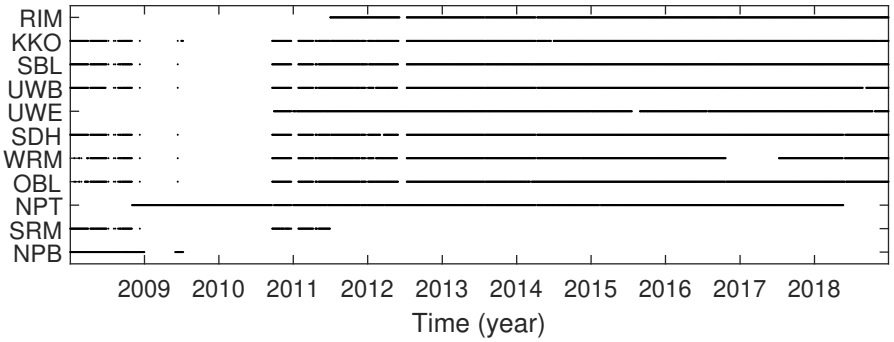

Figure 2. Timeline of data availability at the HVO broadband seismic stations used in this study.

responses so that the maximum amplification is 10 times the base amplification. This prevents over-magnification of noise at periods outside of the instrument sensitivity range. We note that this process is not causal and can introduce artificial tapers around discontinuities (e.g., step functions); an effect included in the synthetic seismograms we use to test our methods (Appendix A). All waveforms are then smoothed and resampled at 6 Hz (much higher than the signal frequencies of interest).

2.2 Continuous wavelet transforms

The second step (Fig. 1) in our method involves calculating time-frequency representations of the seismic data, which are well suited to identifying resonant signals (e.g., Köcher et al., 2014). We use continuous wavelet transforms (CWTs), which offer several advantages over standard short-time Fourier-transforms (STFTs). CWTs involve specifying a base wavelet that can be stretched or 'scaled' to different frequencies and cross-correlated with data to determine frequency content as a function of time (e.g., Alsberg et al., 1997; Selesnick et al., 2005). Plots of CWT amplitudes are termed scalograms. For a given wavelet CWTs provide increasing temporal resolution with increasing frequency; this is a primary advantage over STFTs which have the same temporal resolution for all frequencies (e.g., Lapins et al., 2020).

Useful wavelets for time-frequency analysis are often sinusoids scaled by some function with symmetric, compact support that decays in both directions from a central point

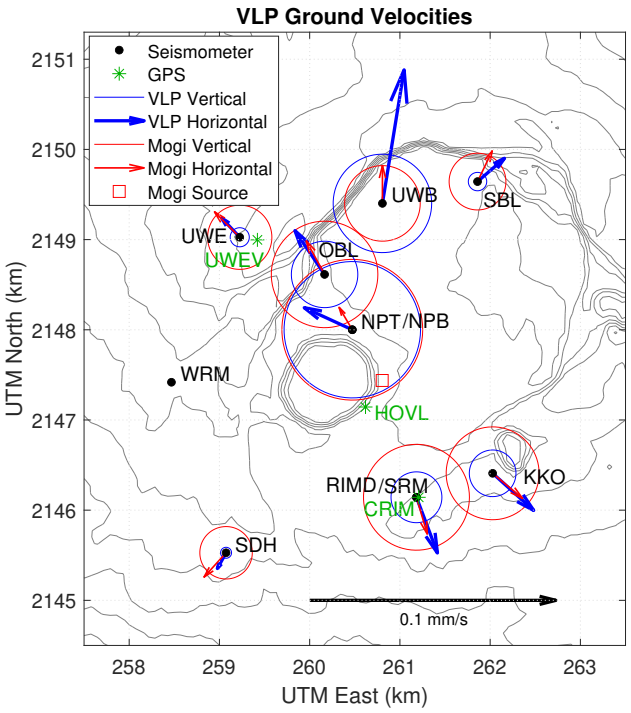

Figure 3. Map of seismometers and GPS stations also showing ground velocities and Mogi inflating spherical reservoir source inversions results for an example conduit-reservoir event on 2017-5-21 (plotted at the time of peak vertical velocity at station NPT). Horizontal velocities (arrows) and vertical velocities (circles, all positive/upward) are shown at the same scale. Horizontal components in the data and source inversion include both tilt and translation effects. UTM zone 5Q.

(Fig. 4). We use Morse wavelets which are given in the spectral domain (for angular frequency ω) by:

$$\Psi_{\beta,y}(\omega) = U(\omega) a_{\beta,y} \omega^{\beta} e^{-\omega^{\gamma}} \tag{1}$$

where $U(w)$ is the Heaviside step function, β governs wavelet duration (or decay rate), γ governs wavelet symmetry, and $a_{\beta,y}$ is a normalizing constant (Lilly & Olhede, 2009). We set $\gamma = 3$ which yields wavelets that are symmetric in the frequency domain (Lilly & Olhede, 2009).

Increasing wavelet duration (i.e., decreasing decay rate) will provide better frequency resolution but worse temporal resolution (Fig. 4), analogous to increasing window length in a STFT. An arbitrary number of 'stretches' of a wavelet can be used to sample at any desired frequencies, though there is a limit to the effective frequency resolution possible with a given wavelet (Fig. 4). The gradual onset of wavelets introduces less artificial temporal 'jaggedness' than a standard STFT (where sinusoids truncate abruptly at the edges of each window) which allows for more accurate determination of signal decay rates. The convolution between a wavelet and an impulsive signal (such as a single peak or step function) will have a duration and decay rate similar to the wavelet itself (Fig. S3). This is analogous to temporal smearing of impulsive signals in STFTs over the window length used. Thus, wavelet duration determines the minimum signal duration that can be distinguished from an impulsive signal, so narrower wavelets can resolve lower Q oscillations.

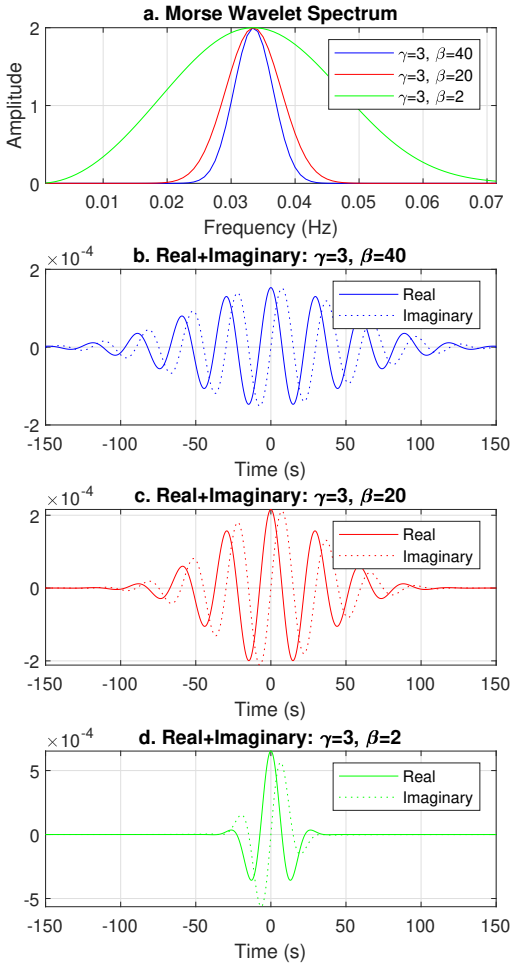

Figure 4. Morse wavelets used in this study (in this case scaled to a period of 30 s). (a) Amplitude spectra. (b) $\beta = 40$ wavelet used to make combined scalograms from which potential VLP signals are detected. (c) $\beta = 20$ wavelet used to make combined scalograms from which potential VLP signals are detected and for calculating Q of signals. (d) $\beta = 2$ wavelet used for detecting first motions of signals.

2.3 Detecting potential resonant signal onsets

To mitigate the inherent trade-off between spectral and temporal resolution we make combined scalograms using wavelets with two different values of β, 40 and 20 (Fig. 4). The higher frequency resolution of the $\beta = 40$ wavelet helps more accurately determine resonant signal period. The $\beta = 20$ wavelet still provides enough frequency resolution to isolate typical Kīlauea VLP signals (Fig. S4), but its increased temporal resolution helps reveal gaps that could indicate whether a signal is a continuous oscillation (Fig. S5) and helps resolve signals with lower Q (Fig. S3). We exclude periods less than 10 s in this study because of the strong oceanic microseism at these periods over the Kīlauea seismic network (e.g., Berger et al., 2004; Dawson & Chouet, 2014). We stack the scalo-

grams from all available stations to increase the signal/noise ratio. Given the proximity of our stations, travel time effects from seismic waves are negligible at periods of interest. For shear wave speeds of 1800 m/s (e.g., Dawson et al., 1999; Lin et al., 2014), the wavelength of a 10 s period wave will be 18 km, roughly four times the distance across our ∼5 km wide array. There is also no concern about destructive interference from stacking scalograms since they contain no phase information. For applying our workflow to shorter period resonant signals (e.g., some LP events), more expansive instrument arrays, or infrasound data travel time effects may need to be considered.

To detect potential resonant signal onsets in a stacked scalogram, we first calculate moving long-term averages (LTA) and moving standard deviations of each frequency component with 200 s windows (Fig. 5). We then introduce a frequency-dependent delay of four cycles to the LTA and standard deviation to account for non-causality in the scalogram. Next, in each frequency band of the stacked scalogram we identify all points that are local maxima, have amplitudes that are above some chosen multiple of the LTA (which we term the STA/LTA threshold), and are also more than some threshold number of standard deviations above the LTA (Fig. 5). We select a value of 3 for both thresholds; chosen to minimize false detections while keeping most desired signals in both synthetic tests and real data (Fig. S6, S7, S8). Finally, where local maxima are separated by both less than a ratio of 1.07 in period (the minimum separation that can be robustly resolved with the wavelets we use) and less than 200 s in time, we keep the maxima corresponding to the highest energy integrated over the following two cycles. This is more robust than just keeping the highest maxima.

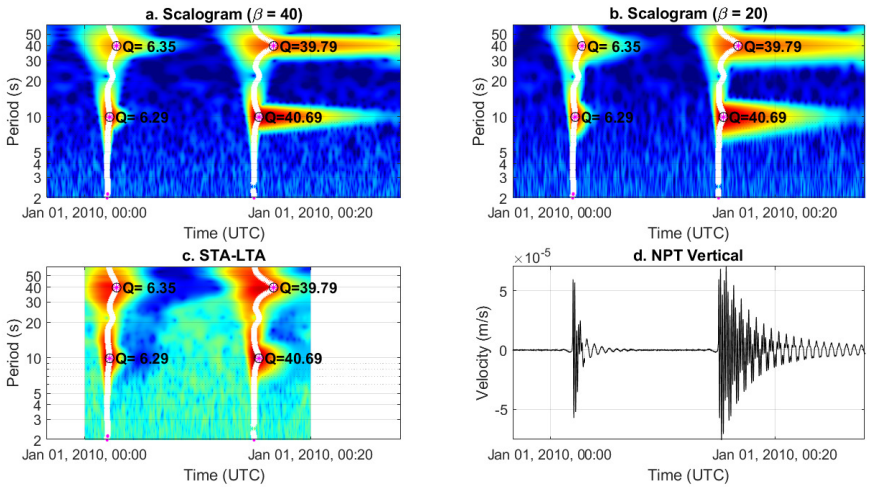

Figure 5. Example scalograms and cataloged events from a synthetic seismogram consisting of four VLP signals with [start time, T, Q] = [00:05, 40, 6], [00:05, 10, 6], [00:15, 40, 40], [00:15, 40, 40], plus white noise from a standard normal distribution scaled by 0.1% of the signal amplitude (Appendix A). Here T and Q of all resonant signals are recovered accurately. (a) $\beta = 40$ scalogram. White dots indicate temporal local maxima that meet the minimum STA/LTA criteria, and magenta dots indicate points that are spectral local maxima (integrated over two cycles). Black circles and text indicate the final selected event onsets and corresponding calculated Q. (b) $\beta = 20$ scalogram. (c) Frequency-dependent STA/LTA. (d) Synthetic seismogram. We note that the slight precursory oscillations arise from removing the instrument response.

2.4 Calculating quality factor (Q)

The third step (Fig. 1) in our workflow is calculating Q by fitting decaying exponentials to stacked scalogram amplitudes following each detected potential resonant signal onset (Fig. 6). We use only the narrower $\beta = 20$ CWTs that have better temporal resolution (Fig. 4); the minimum Q that this wavelet can robustly resolve is around 6. Lower β values could be used to resolve lower Q events at the expense of worse frequency resolution. We extract scalogram amplitudes at the target frequency over one to eight cycles after the identified signal onset. The one cycle delay avoids the region near the onset of an impulsively initiated signal where amplitudes will be inherently underestimated since part of the wavelet will not be overlapping the signal (Fig. 6), and helps avoid artifacts that might be present from a trigger mechanism. Delays between 0.5 and 1.5 cycles yield negligibly different results. Eight cycles was found to be a sufficient duration for robustly capturing signal decay rates; increasing this duration further will not affect the accuracy of our fitting method.

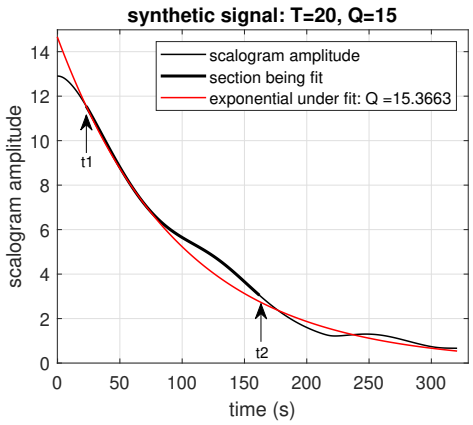

Figure 6. Example estimation of Q by scalogram exponential fit from a synthetic seismogram. This seismogram consists of a VLP signal with [T, Q] = [20 s, 15], plus white noise from a standard normal distribution scaled by 1% of the signal amplitude. The bold part of the black line shows the part of the scalogram data that is being fit (from t_1 to t_2), and the red line shows the exponential 'under fit' (Eq. 2).

Standard least-squares exponential regressions can underestimate decay rate in the presence of noise or where another signal starts within the fitting window, thus overestimating Q (Fig. S9). We tested a variety of different exponential fitting approaches with varying fit timespans, maxima/minima, weighting schemes, outlier exclusion methods, and goodness of fit thresholds. An 'under-fit' is the most robust (Fig. 6, S10), involving an exponential fit with initial amplitude fixed to the initial scalogram amplitude $A(t_1)$ and with the slowest decay rate α that remains bounded from above by scalogram amplitudes in the timespan being fit (t_1 to t_2) (Fig. 6, S9):

$$\alpha = -\min_{t=t_1}^{t_2} \left[\frac{\ln\big(A(t)\big) - \ln\big(A(t_1)\big)}{t - t_1} \right] \tag{2}$$

which then yields quality factor: $Q = \pi/(T\alpha)$. This fitting method is less sensitive to the choice of fitting timespan than least-squares regressions, since extending the timespan will have no effect unless the added amplitudes fall beneath the current fit. Additionally, other signals interrupting the coda of the target signal are less likely to affect this fitting method. The estimates from this method have a slight negative bias (<10%

even for very high noise levels, Fig. S10). However, this method has lower bias and higher overall accuracy than other regression methods (Fig. S10) and outperforms the Sompi AR method which fails to detect the signals of interest in many of our tests.

Signals that are not a single continuous periodic oscillation could create a contiguous band of elevated energy in a scalogram that appears like a decaying resonant signal. To mitigate this, we also extract the phases of the $\beta = 20$ CWTs at each channel and check for consistent trends over the timespan being fit. For a continuous periodic oscillation, the phase $\theta(t)$ of a wavelet stretched to the oscillation frequency f will increase steadily as it is convolved with the signal (Fig. 7, S11):

$$\theta(t) = 2\pi f t + \theta(0) \tag{3}$$

A signal that is not a continuous periodic oscillation can exhibit deviations from this expected phase (Fig. 7). To quantify how 'continuous' a signal is, we calculate the mean phase deviation (E_θ) from the expected phase over the timespan being fit ($t_2 - t_1$) and over all N channels:

$$E_\theta = \frac{1}{N}\frac{1}{t_2 - t_1}\sum_{n=1}^{N}\int_{t_1}^{t_2}\left|2\pi f t + \tilde{\theta}_n - \theta_n(t)\right|dt \tag{4}$$

where $\tilde{\theta}_n$ is the constant phase offset that minimizes phase deviation at channel n. We use this phase offset instead of the actual initial phase $\theta_n(t_1)$ since there may be effects from the signal onset present at the start of the timespan. We then keep only signals with a mean phase deviation of less than a threshold value of 0.1 radians. This threshold minimizes inclusion of noise or non-continuous oscillations while keeping most continuous periodic oscillations in tests on both synthetic and real data (Fig. 7, S11).

2.5 Determining first motions

First motions (polarities) are not well defined for signals without impulsive onsets. Even for impulsive onsets, picking first motions for a particular frequency component is difficult to do robustly because band-pass filtering a signal will distort the onset of that signal regardless of the filter used (i.e., causal or acausal, FIR or IIR) (Fig. 8). To partly mitigate this issue, we use a 'wavelet filter': we compute the CWT of a signal, then reconstruct the signal using an inverse CWT but keeping only the period of interest. This still produces artificial precursory oscillations in front of signals with impulsive onsets (Fig. 8), but the size of these oscillations is predictable for a given wavelet. We use a very narrow Morse wavelet ($\beta = 2$) which will produce only one appreciable precursory oscillation that will be less than half of the signal amplitude, though such a narrow wavelet will be sensitive to a wider frequency range (Fig. 4).

We then stack the amplitudes of the wavelet-filtered signals from all channels and identify local maxima around the signal onset time that exceed the thresholds for both STA/LTA and number of standard deviations above the LTA (Fig. 8). We discard local maxima that are less than half of the global maximum, which for impulsive onset signals will exclude precursory oscillations caused by the wavelet filter. If no local maxima remain, which will occur either if the signal has a gradual onset or is too contaminated by other signals/noise, we consider the first motions undetermined. If one or more maxima remain, we select the first of these as the first motion time and then obtain corresponding first motion directions at each channel from the wavelet filtered waveforms (Fig. 8). We store the STA/LTA ratio, standard deviations above the LTA, and fraction of the global maximum for this local maximum as indicators of pick confidence.

2.6 Comparison with previous Kīlauea VLP catalog

We compare our catalog to one produced using the methods from Dawson and Chouet (2014) extended through 2018: automated detection via a hidden Markov model trained

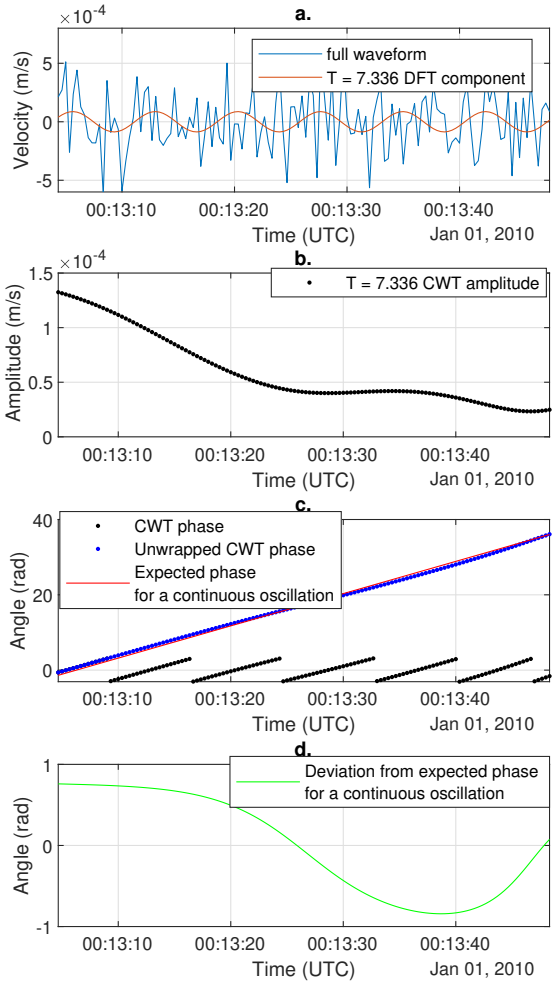

Figure 7. Example phase continuity from a spectral peak in synthetic random noise, where the high phase deviation correctly indicates that this is likely not a continuous oscillation. (a) Synthetic seismogram and 7.336 s DFT component. In a scalogram (or frequency spectrum) this signal exhibits a local maximum at this period. (b) CWT amplitude of the 7.336 s signal, which exhibits a roughly exponential decay. (c) CWT phase of the 7.336 s signal and expected phase for a continuous oscillation. (d) Difference between CWT phase and expected phase for a continuous oscillation.

on example events (Dawson et al., 2010) and estimation of T and Q via the Sompi AR model (Kumazawa et al., 1990). For both catalogs adjustment of various threshold parameters is required to minimize false picks and poorly constrained events. In the catalog extended from Dawson and Chouet (2014) the most useful parameters to threshold are event amplitude at station NPB or NPT and the standard deviation of Q from Sompi cluster fits. We set these thresholds to 325 counts and 0.275 respectively, which results in a similar number of events in both catalogs (∼3200). In both catalogs chang-

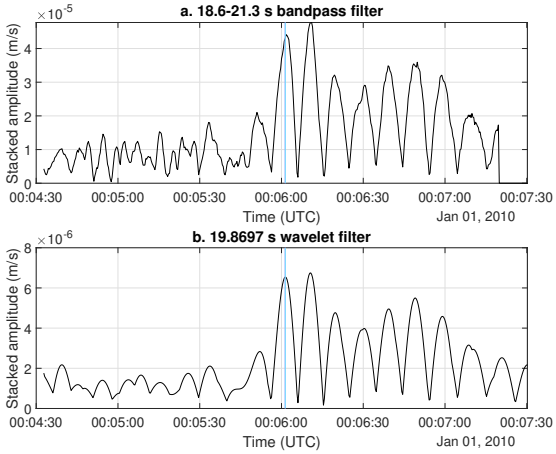

Figure 8. Example correct first motion pick from a synthetic seismogram for an impulsive onset oscillation with [start time, T, Q] = [00:06, 20, 20], plus a step displacement (velocity spike) at time 00:06, plus two other equal-amplitude oscillations with [start time, T, Q] = [00:05, 80, 20] and [00:05, 5, 20], and plus white noise from a standard normal distribution scaled by 0.1% of the signal amplitude. (a) Stacked amplitudes from waveforms filtered with an FIR bandpass filter. This is just shown for comparison and not used in picking first motions. The cyan line is the algorithm's first motion pick. (b) Stacked amplitudes from waveforms filtered with the wavelet filter we use for picking first motions.

ing these thresholds will greatly vary the number of events included, and less strict thresholds will include tens of thousands of additional events (Fig. S7, S8).

For the thresholds shown the two catalogs include around 1000 overlapping events, most of which are part of a dominant trend of events that spans most of the timeline with periods varying from about 15-40 s (Fig. 9). There are more total events in this main event trend in the catalog extended from Dawson and Chouet (2014) than in ours, but there are also many events unique to our catalog both in this main event trend and forming additional event groups. Using less strict thresholds on both catalogs results in a larger number overlapping events, primarily in the main event trend, but there are still many events unique to each catalog. Based on visual inspections of outlier events and a random subset of all events, at the thresholds shown both catalogs include on the order of 100 events that are likely bad detections. For this purpose we consider bad detections either signals with estimates of T that appear inaccurate by more than ∼25% or signals that do not appear to be continuous periodic oscillations (e.g., noise or tectonic earthquakes).

Accurate estimates of T and Q will be more valuable than total event counts for inferring properties of the magmatic system. Our catalog generally includes less scatter in both T and Q for the main event trend (most of the apparent Q outliers in Fig. 9 plot b are not from the main event trend). The lower scatter in our catalog is also present when only comparing matching events (Fig. 9) and is present over a range of reasonable event thresholds for both catalogs. As discussed in section 2.3, our method cannot robustly detect events with $Q < 6$ given the wavelets we are using. The catalog extended from Dawson and Chouet (2014) extends to lower Q, though the accuracy with which low-Q events can be characterized will be inherently limited as indicated by the large scatter in T from late 2011-early 2012. Where the two methods estimate appreciably different values of Q we find that there is often some complication (such as overlapping sig-

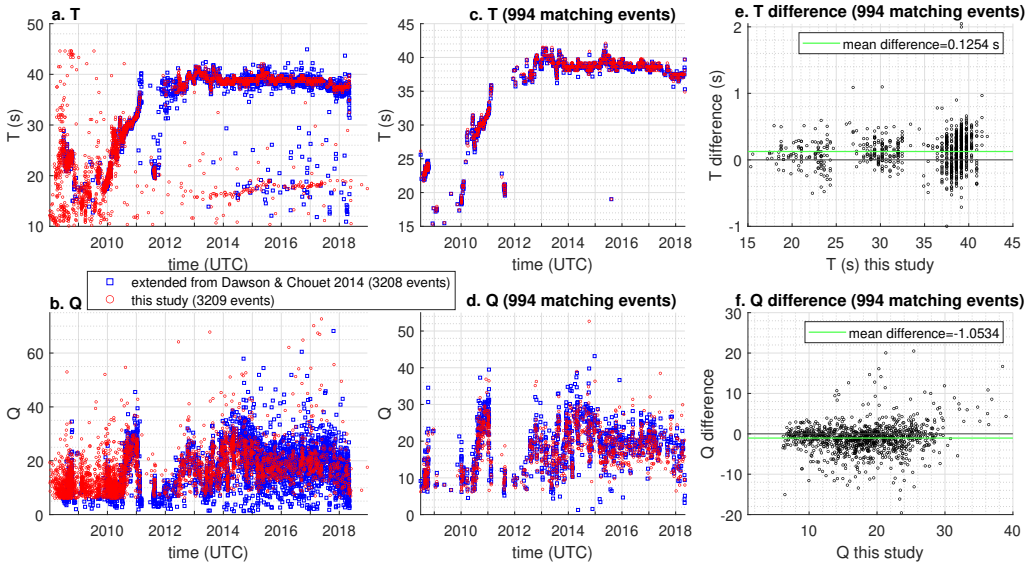

Figure 9. Comparison of detected VLP events from this study with a catalog extended from Dawson and Chouet (2014). Event detection thresholds were chosen to produce a similar number of events in both catalogs (section 4.1). (a and b) T and Q over time in both catalogs. (c and d) T and Q over time from corresponding events that have start times within 3 minutes of each other and T ratios within 4/5-5/4 of each other between the two catalogs. (e and f) Values of T and Q in our catalog minus values in the catalog extended from Dawson and Chouet (2014) for corresponding events.

nals or strong noise) that causes the Sompi AR method to be inaccurate where our method still produces reasonable estimates. Q estimates in our catalog are very slightly lower on average (by ~ 1) than those of matching events in the catalog extended from Dawson and Chouet (2014) (Fig. 9). This is consistent with the bias our exponential fitting method exhibits for noisy synthetic signals (section 2.4, Fig. S10) which we expect is a beneficial trade-off for increased precision and robustness.

Most prominent among the groups of events unique to our catalog is a trend of events with T ranging from 10-20 s between 2010 and 2018 (Fig. 9). The Sompi AR method can detect and provide accurate estimates of T for many of these events (Dawson & Chouet, 2014), but often does not produce accurate estimates of Q even with manual examination of the algorithm output. Our methods generally provide accurate estimates of Q for these events, but still exclude many real events in this band when strict enough thresholds are used to minimize bad detections in the catalog as a whole. Our catalog also includes a clear event group with T around 15 s in early 2009, and some other more isolated clusters between 2008 and 2010 (Fig. 9). Our catalog shows large scatter in T prior to 2010, but many of these values do likely represent real VLP oscillations. Both catalogs show multiple isolated events after 2012 with T from $\sim$10-15 and $\sim$20-35 s. Most of these detections in our catalog are gliding-frequency VLP events; some in the catalog extended from Dawson and Chouet (2014) are also gliding-frequency VLP events whereas others do not appear to be coherent VLP oscillations.

In summary, both detection methods produce incomplete catalogs, particularly for the secondary group of events with 10-20 s periods, and both involve trade-offs between missing real events and including too many bad detections. The two catalogs contain many non-overlapping events, so to obtain a maximally complete catalog there would be value

in combining both detection methods. However, since our detection method does not require labeled training data and has demonstrated performance that is comparable overall and better in some respects than existing approaches for detecting resonant VLP seismicity, we expect it will be a useful tool in various volcanic settings. Additionally, we expect our method for estimating Q will be valuable, even if applied to events detected via other methods, since it is demonstrably robust which should facilitate better inference of magma system properties.

2.7 Characterizing ground motion patterns

Our goal in this study is not to conduct detailed source inversions for every event, but rather to quantitatively characterize when changes in ground motion patterns occur. Average phases and amplitudes at each channel are obtained using the Goertzel DFT algorithm (Proakis & Monolakis, 1990) over a time window between one and five cycles after each event onset. We then compute the average vertical/horizontal velocity ratio R_{vh}, defined for the target frequency component f as:

$$R_{vh} = \sum_{m=1}^{M} \frac{|\dot{\mathbf{u}}_{Z,m}(f)|}{|\dot{\mathbf{u}}_{E,m}(f) + \dot{\mathbf{u}}_{N,m}(f)|} \tag{5}$$

for vertical (Z), east (E), and north (N) velocities ($\dot{\mathbf{u}}$) at all M stations. This metric requires no assumptions of source location or mechanics, but it is sensitive to tilt which will increase the apparent amplitude of horizontal components at increasing T.

We also quantify how radially oriented horizontal motion vectors are by calculating the angles from the direction to an inferred source location, similar to 'semblance' (e.g., Legrand et al., 2000). We set this source location based on a previous geodetic (InSAR, GPS, and tilt) inversion for the shallow ground deflation source in early 2018 (Anderson et al., 2019) (Fig. 3), which is similar to the centroid location inferred by other seismic and geodetic inversions over the past decade (Chouet et al., 2010; Chouet & Dawson, 2011; Anderson et al., 2015; Anderson & Poland, 2016; Liang, Crozier, et al., 2020). We then calculate radial misfit E_{radial} as the mean angle between the target frequency component of observed $\dot{\mathbf{u}}$ and predicted $\dot{\mathbf{w}}$ (perfectly radial) velocity vectors:

$$E_{radial} = \frac{1}{MT} \sum_{m=1}^{M} \int_0^T \left| \arccos\left(\frac{\dot{\mathbf{u}}(t) \cdot \dot{\mathbf{w}}(t)}{|\dot{\mathbf{u}}(t)||\dot{\mathbf{w}}(t)|} \right) \right| dt \tag{6}$$

The final method we use to quantify ground motion patterns is conducting source inversions for an inflating/deflating spherical reservoir using a 'Mogi' model for a point source in an elastic half-space (Mogi, 1958). The quasi-static elasticity used in the Mogi model should be approximately valid for the long period signals and short distances considered here (see section 2.3). Due to their simplicity, these inversions are most useful as an indicator of relative changes in source centroid depth rather than as a probe of detailed reservoir geometry. For example, changes in Mogi centroid depth could represent changes in the vertical extents of an ellipsoidal reservoir, and/or changes in the geometry or activation of any secondary dikes or sills that may also be contributing to the ground motions. Additionally, the misfit from Mogi inversions provides a second metric for the radial symmetry of ground motions.

We fix the east and north Mogi source location based on previous geodetic inversions to simplify the inversion results and reduce noise-induced scatter (Anderson et al., 2019) (Fig. 3). We assume a shear modulus of 10 GPa and Poisson's ratio of 0.25. We include ground tilt (detected as horizontal acceleration by broadband seismometers) in the Green's functions (Maeda et al., 2011) to predict displacements $\mathbf{w}$ as:

$$\mathbf{w}(f) = \left(\mathbf{G}_t + \mathbf{G}_r \frac{g}{(2\pi i f)^2} \right) P(f), \tag{7}$$

where $\mathbf{G}_t$ and $\mathbf{G}_r$ are the translation and tilt Green's function matrices from a Mogi source at a given depth, g is gravitational acceleration, and P is forcing pressure. We solve for the P that results in minimal misfit between $\mathbf{w}$ and observed displacements $\mathbf{u}$ for given Green's functions using a linear least-squares inversion. We then conduct a grid search to find the Mogi source depth that minimizes misfit E between the target frequency component of $\mathbf{w}$ and $\mathbf{u}$ according to:

$$E = \frac{\sum_{n=1}^{N} |\mathbf{u}_n(f) - \mathbf{w}_n(f)|}{\sum_{n=1}^{N} |\mathbf{u}_n(f)|} \tag{8}$$

for all N channels, with source depth bounded between 500 m and 2500 m beneath the caldera floor.

2.8 Other geophysical data and observations

To interpret the timeline of VLP seismicity cataloged in this work, we rely on a series of touchstone events that characterize the progression of the 2008-2018 Kīlauea eruptive episode. ERZ eruptions prior to 2018 have been compiled in Patrick, Swanson, and Orr (2019): the March 2011 Kamoamoa fissure eruption (Orr et al., 2015), August 2011 Pu‘u ‘Ō‘ō vent opening, September 2011 Pu‘u ‘Ō‘ō vent opening, June 2014 Pu‘u ‘Ō‘ō vent opening (Poland et al., 2016), and May 2016 Episode 61g Pu‘u ‘Ō‘ō vent opening (Chevrel et al., 2018). Timing of the 2018 eruption is given in Neal et al. (2019). Documented summit intrusions have been compiled in Patrick, Swanson, and Orr (2019): October 2012, May 2014, and May 2015 (Johanson et al., 2016). Regional slow-slip events (SSEs) have been compiled in Montgomery-brown et al. (2015) and Wang et al. (2019): February 2010, May 2012, and October 2015.

To indicate long-term ground deformation we use near-field (within ∼2 km of the vent) geodetic data: vertical displacements from GPS station HOVL, horizontal line-lengths between GPS stations UWEV and CRIM, and east and north tilt from tilt-meter UWE (Miklius, 2008; Johanson, 2020) (Fig. 3). We also use smoothed stacks of these four datasets to infer times of inflation and deflation. For this we smooth all four datasets with 30-day moving average filters and scale them to have a unit range, then flip the sign of UWE east tilt-meter data so that increasing values indicate inflation, and then stack the four datasets. We consider any time when the stacked geodetic data is increasing to indicate long-term inflation.

We use lava-lake elevation and surface area data from Patrick, Swanson, and Orr (2019) (data extended through 2018 was obtained from the USGS HVO via Matt Patrick). This data is obtained from a combination of webcam images, thermal images, and laser rangefinders. SO_2 gas flux data from various monitoring stations for the whole timespan does exist (Whitty et al., 2020), but we only consider data from published studies using direct measurements of the summit plume. We use SO_2 emission data collected by a vehicle-based FLYSPEC UV spectrometer from 2007-2010 (Elias & Sutton, 2012). We also use SO_2 emission data collected by an array of FLYSPEC UV spectrometers from 2014-2017 (Elias et al., 2018). Both datasets have large uncertainties (Fig. 10, 11) due to spectral fitting limitations and uncertainty in plume speed and location (Elias & Sutton, 2012; Elias et al., 2018).

3 Results

3.1 Types of VLP seismicity at Kīlauea from 2008-2018

We will introduce the common types of VLP signals present in the catalog.

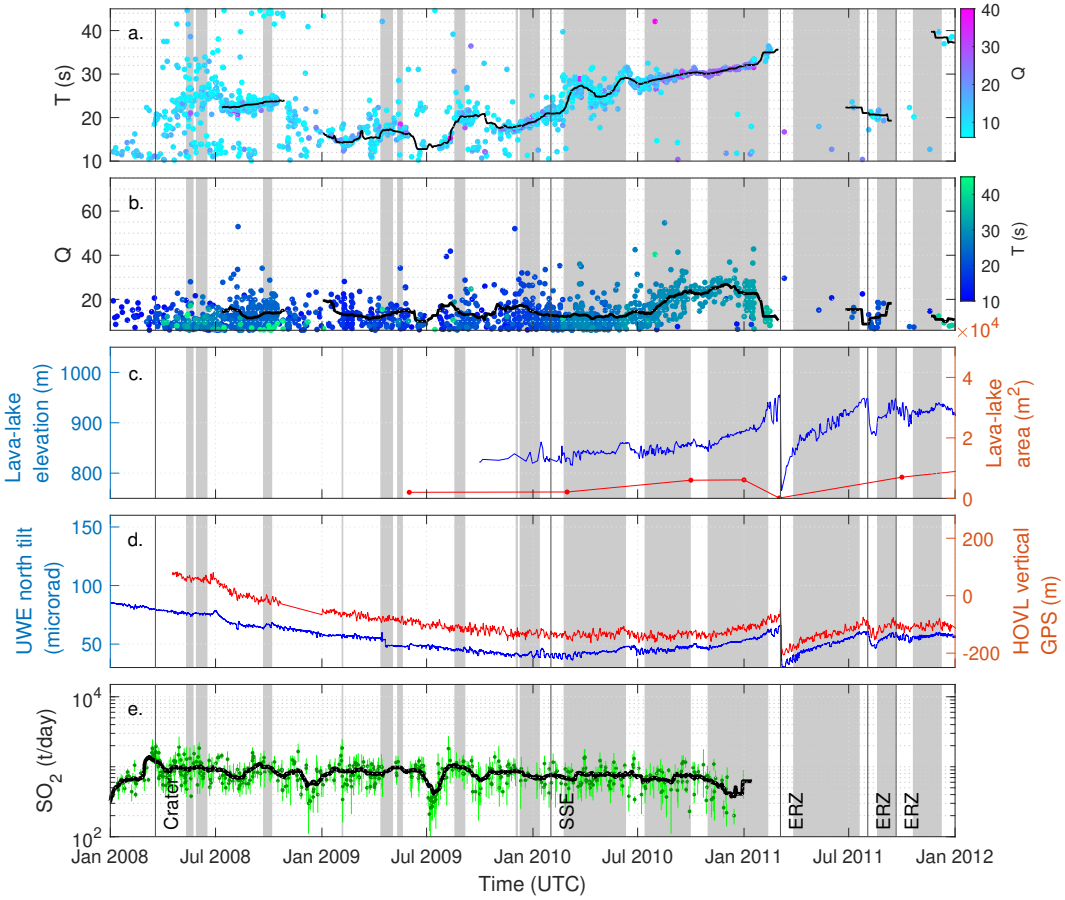

Figure 10. Section of the VLP catalog from 2008-2011. (a and b) Period and quality factor over time. Black lines show 30-day moving averages over the events we have labeled as potential conduit-reservoir oscillations, neglecting outliers or events from times with no consistent dominant period. (c) Lava-lake surface elevation and surface area. (d) UWE north tilt and HOVL vertical GPS. (e) Average daily SO_2 (dark green dots) and standard deviations (light green lines). The black line is a 30-day moving average. 'Crater' indicates where the Halema'uma'u crater first formed, 'SSE' indicates slow slip events, 'Int' indicates documented summit intrusions, and 'ERZ' indicates eruptions along the East Rift Zone. Grey bars in all plots indicate times of long-term ground inflation (section 2.8).

3.1.1 Conduit-reservoir resonance

The first category of signals we term 'conduit-reservoir oscillations'. These constitute the main trend of VLPs starting at T ~20 s in 2010, increasing to ~40 s in early 2011, and fluctuating between 35-43 s from 2012 until the caldera collapse onset in May 2018 (Fig. 10, 11). Some other events prior to 2010 and during the series of lava-lake draining events in 2011 may also fit into this category. The conduit-reservoir oscillation is the fundamental resonant eigenmode of the coupled conduit and shallow magma reser-

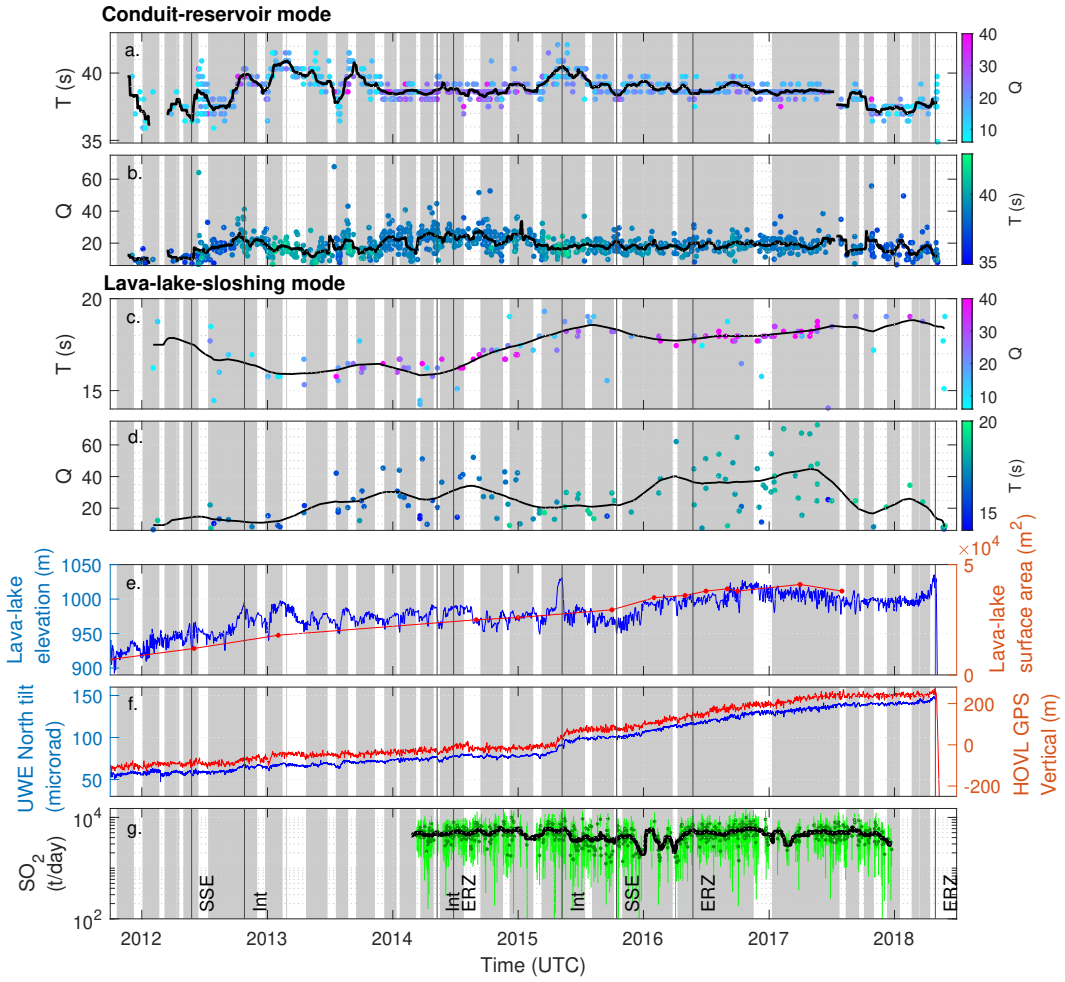

Figure 11. Section of the VLP catalog highlighting conduit-reservoir and lava-lake sloshing resonance from 2012-2018. (a and b) Period and quality factor of conduit-reservoir events over time. Black lines show 30-day moving average. (c and d) Period and quality factor of lava-lake sloshing over time. Black lines show 120 day moving average. (e) Lava-lake surface elevation and surface area. (f) UWE north tilt and HOVL vertical GPS. (g) Average daily SO_2 (dark green dots) and standard deviations (light green lines). The black line is a 30-day moving average. 'SSE' indicates slow slip events, 'Int' indicates documented summit intrusions, and 'ERZ' indicates eruptions along the East Rift Zone. Grey bars in all plots indicate times of long-term ground inflation (section 2.8).

voir system, in which the magma column in the conduit and lava-lake oscillates vertically and pushes magma in and out of the underlying reservoir (Chouet & Dawson, 2013; Liang, Crozier, et al., 2020). Other resonances such as from Krauklis (crack) waves or acoustic waves (organ pipe eigenmodes) are predicted to generally have higher frequencies and lower amplitudes (Karlstrom & Dunham, 2016; Liang, Karlstrom, & Dunham, 2020). Restoring forces for the conduit-reservoir oscillation come from magma reservoir compressibility (combined wall rock elasticity and multiphase magma compressibility)

and gravity/buoyancy, while damping primarily comes from viscous dissipation along the conduit walls. Ground deformation during these events is primarily from uniform inflation/deflation of the magma reservoir; deformation from the conduit is small by comparison.

Conduit-reservoir oscillations can be triggered/driven by a variety of different mechanisms, producing signals with different onset characteristics. We term conduit-reservoir oscillations with abrupt onsets and inflationary first motions 'Normal'; this category includes rockfall or lava-lake surface explosion triggered events and is analogous to 'type 2' events in Dawson and Chouet (2014). There is often high-frequency or broadband energy present at the onset of Normal events, as well as inflationary steps in tilt data (Chouet & Dawson, 2013; Orr et al., 2013; Dawson & Chouet, 2014) (Fig. 12, S12, S13). We term conduit reservoir oscillations with abrupt onsets and deflationary first motions 'Reverse'; analogous to 'type 3' events in Dawson and Chouet (2014) (Fig. 12). These events often do not have obvious high frequency triggers, and some exhibit deflationary tilt steps. The trigger for Reverse events is not known, but has been proposed to involve impulsive magma movement at depth due to flow transients or fracture/dike opening (Dawson & Chouet, 2014). Some conduit-reservoir events do not fit very clearly into either category, for example those with gradual onsets or multiple step increases in oscillation amplitude (S12, S14).

Our first motion algorithm classifies 77% of conduit-reservoir events after 2012 as Normal, 17% as Reverse, and the remaining 6% as undetermined (Fig. 13). Prior to 2012 our classifications are less reliable due to the prevalence of VLP tremor and shorter resonant periods (which makes phase offsets between stations less negligible). The mean and median amplitudes of Normal events are both about twice as large as those of Reverse events, though both types of events exhibit variation in amplitude over orders of magnitude (Fig. S15). We do not find any appreciable differences in distributions of T or Q, or different correlations with other datasets such as tilt and lava-lake elevation between Normal and Reverse events (Fig. S15).

3.1.2 Lava-lake sloshing

The second category of signals we term 'lava-lake sloshing'. These have T of 10-20 s and are recognizable from 2010-2018 in our catalog (Fig. 10, 11). Inversions of select lava-lake sloshing events by Liang and Dunham (2020) supports suggestions by Dawson and Chouet (2014) that they are likely caused by lateral surface gravity wave resonance in the lava-lake (i.e., 'sloshing'). The sloshing could induce pressure perturbations at the top of the conduit causing a forced oscillation of the conduit-reservoir system, so ground motions could be from a combination of pressure against the lava-lake walls and reservoir inflation/deflation. There are some times where two distinct lava-lake sloshing signals occur with slightly different periods (Fig. 12, S12), likely representing sloshing along different axes of the lava-lake (Dawson & Chouet, 2014; Liang & Dunham, 2020). These are not very prevalent in our catalog at the thresholds shown, which may be partly because often one of the two signals will be too close in period to a larger lava-lake sloshing signal or have too low of a signal/noise ratio to be included.

Around 75% of lava-lake sloshing events in our catalog appear alongside Normal conduit-reservoir oscillations; the rest appear in isolation (Fig. 12, 13, S12, S16). That none appeared alongside Reverse oscillations is consistent with the idea that Reverse oscillations are triggered from depth (Dawson & Chouet, 2014) and so the lava-lake is not directly perturbed. It also indicates that the magma flowing in/out of the top of the conduit during Reverse conduit-reservoir oscillations does not induce appreciable lava-lake sloshing, which could be due to the small volumes of magma involved and/or to the top of the conduit not being laterally offset from the center of the lava-lake.

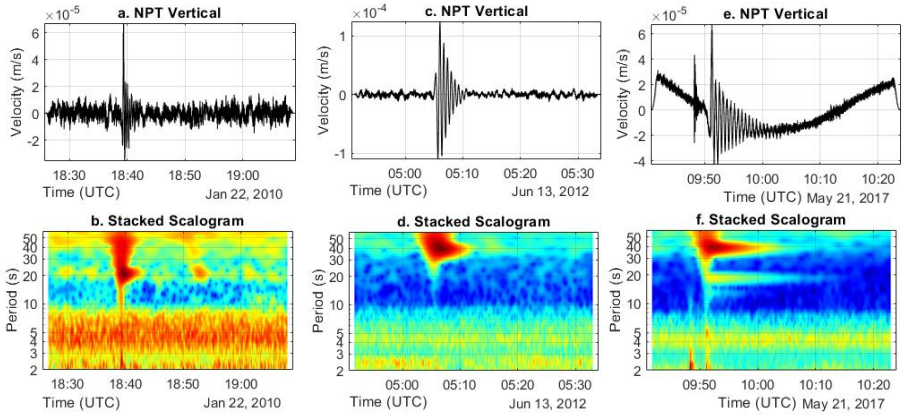

Figure 12. Example VLP events. (a and b) Normal conduit-reservoir oscillation event along with background VLP periodic tremor from January 2010, when the lava-lake became persistent (Patrick, Swanson, & Orr, 2019). The event had an impulsive broadband onset and inflationary first motions, indicative of a rockfall trigger. The background VLP periodic tremor had the same dominant period as the impulsively triggered VLP event, but often unclear onsets and no higher frequency triggers. (c and d) Reverse VLP event from June 2012, shortly after the May 2012 SSE. This event had an impulsive onset but no high frequency trigger. There was a small initial inflationary motion but the first large oscillation was deflationary. (e and f) Normal conduit-reservoir event with two lava-lake sloshing events from May 2017. A higher frequency impulsive signal occurred about 2 minutes before these events that may have been related to their triggering.

3.1.3 Other VLP seismicity

We will use the term 'periodic tremor' to refer to signals with clearly elevated energy in one or more relatively focused periods, but that are not obviously isolated in time and lack clear onsets and/or exponential decays. Our method will not return detections if periodic tremor amplitude is constant, but where amplitude is variable our method will consider any local amplitude maxima above the set detection thresholds. For such local maxima the apparent decay rate could be controlled by the forcing time-function rather than the inherent damping of the resonator, so estimates of Q returned by our method might not reflect the same physical properties as for impulsively triggered resonance. Periodic tremor occurs throughout the study timespan (Fig. 12, S17, S18, S19, S20, S21, S22), often with the same dominant periods as impulsively triggered conduit-reservoir or lava-lake sloshing oscillations. We thus hypothesize that the periodic tremor often represents these same resonant mechanisms with continuous rather than discrete forcing.

Our catalog includes some VLP oscillations that exhibit gliding-frequencies over the duration of a single event (Fig. S23, S24). These constitute many of the events in our catalog with outlier values of T (Fig. 9) and are more prevalent when a higher phase deviation threshold is used. The values of T and Q returned by our methods will not be representative of the whole signals, but visual inspection reveals that gliding-frequency VLP oscillations are present at various times throughout the studied timespan and with various starting and ending periods and durations. Gliding-frequencies have been pre-

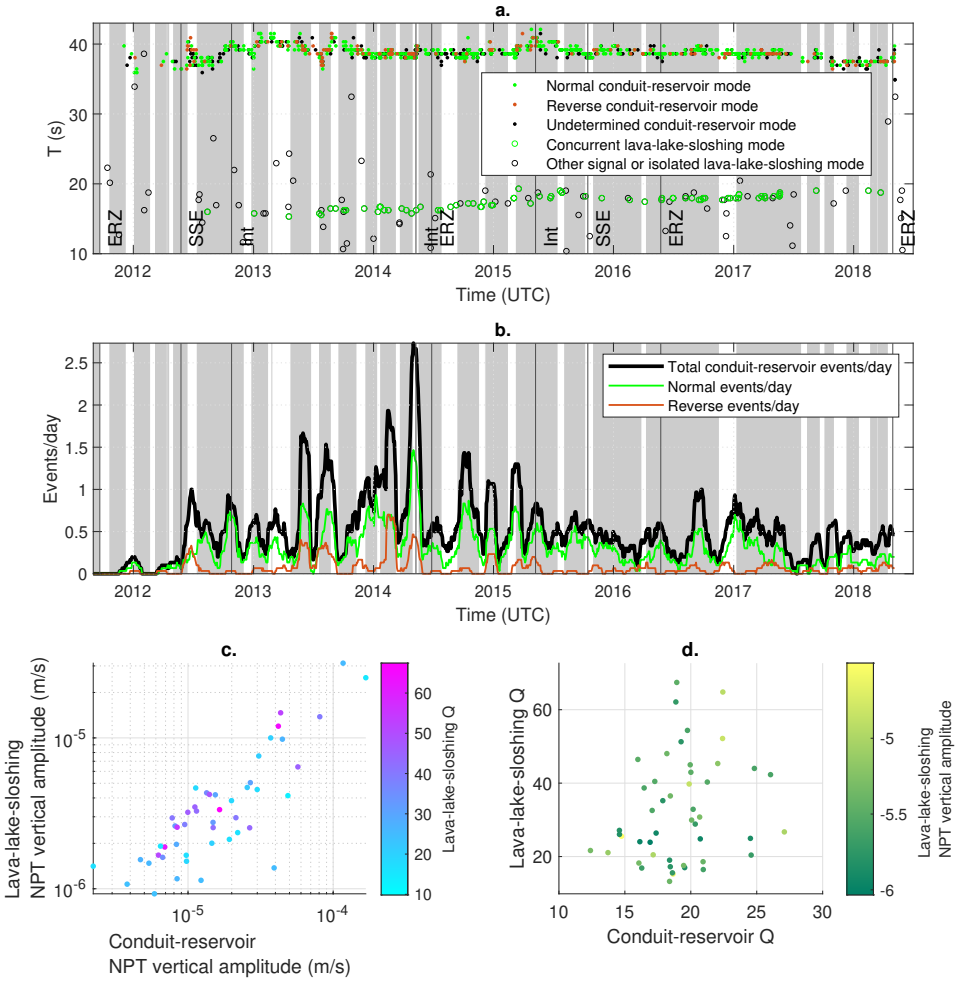

Figure 13. (a) Onset polarity (Normal or Reverse) of conduit-reservoir oscillations and lava-lake sloshing that occurred alongside a detected conduit-reservoir event. (b) Conduit-reservoir event density calculated over 30-day windows. We note that event density will vary by orders-of-magnitude depending upon the event detection thresholds used (section 2.6), so is most useful for comparing relative event densities through time. 'Crater' indicates where the Halema'uma'u crater first formed, 'SSE' indicates slow slip events, 'Int' indicates documented summit intrusions, and 'ERZ' indicates eruptions along the East Rift Zone. Grey bars in plots a and b indicate times of long-term ground inflation (section 2.8). (c) amplitudes (from vertical velocity at station NPT) of conduit-reservoir oscillations vs corresponding lava-lake sloshing. (d) Quality factor of conduit-reservoir oscillations vs corresponding lava-lake sloshing.

viously identified in tremor at Kīlauea, but at much higher frequencies (0.6-6 Hz) and with gliding occurring over hours-days (Unglert & Jellinek, 2015). In some cases, the gliding-frequency VLP oscillations appear to start or end at similar periods to non-gliding conduit-reservoir or lava-lake sloshing oscillations, indicating that at least some of them may be related to these other oscillations. Some may represent rising bubble slugs, which could create a varying oscillation period during ascent and then possibly trigger standard de-

caying conduit-reservoir resonance after bursting at the surface (e.g., James et al., 2008; Chouet et al., 2010). Alternately, some may represent examples of either conduit-reservoir or lava-lake sloshing resonance where magma properties change over the course of the resonance. This could occur if the perturbation that induces resonance destabilizes some aspect of the shallow magma system, such as by causing collapse of a foam layer in the lava-lake or upward movement of a bubble slug or bubble cloud.

3.2 Correlations among datasets

Here we analyze correlations between the various geophysical datasets, conduit-reservoir oscillation properties, and lava-lake sloshing properties. Fig. 14 shows correlations over the 2008-2018 timespan (see Fig. S25 for just the 2012-2018 timespan). When looking over such long timescales only a few strong correlations are apparent. Fig. 15 shows moving 90-day correlations, which reveals more correlations between datasets but that these correlations change over time.

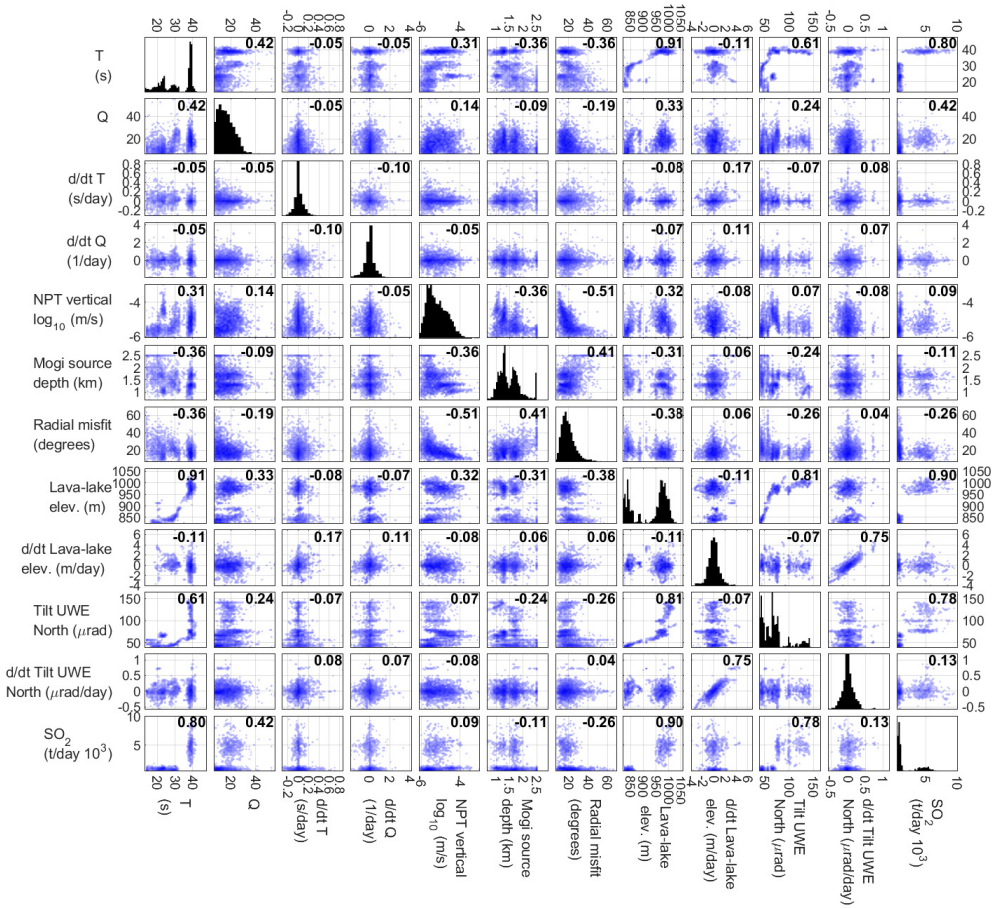

Figure 14. Conduit-reservoir oscillation correlation matrices from 2008-2018 (see Fig. S25 for just the 2012-2018 timespan). Off-diagonal plots are shaded by the logarithm of the number of points in each parameter bin, and histograms on diagonal plots show the distribution of each parameter. Numbers are Pearson's correlation coefficients, only shown for correlations with P-values less than 0.05. All time derivatives, indicated by 'd/dt', were calculated with a 7-day cutoff-period differentiator filter.

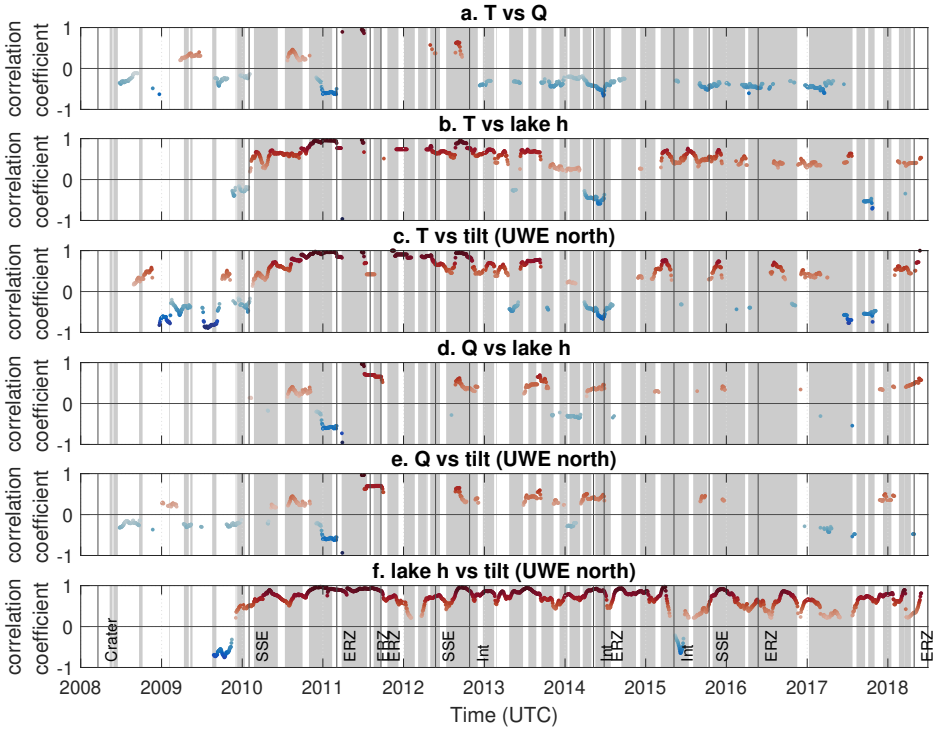

Figure 15. Conduit-reservoir oscillation Pearson's correlation coefficients calculated over moving 90-day windows. Windows with p-values greater than 0.05 were excluded. Red and blue highlight positive and negative correlations, respectively. 'SSE' indicates slow slip events, 'Int' indicates documented summit intrusions, and 'ERZ' indicates eruptions along the East Rift Zone. Grey bars in the all plots indicate times of long-term ground inflation (section 2.8).

3.2.1 Ground deformation and lava-lake elevation correlation

Ground surface deformation data from near field tilt-meters and GPS stations indicates the rate of ground inflation/deflation of the Kīlauea summit region. This primarily reflects pressure in the shallow summit reservoir, but may also be influenced by pressure in the proposed deeper south caldera reservoir or motion of the south flank (e.g., Owen et al., 2000; Baker & Amelung, 2012; Anderson et al., 2015). Lava-lake elevation has previously been shown to be correlated with ground inflation on timescales of hours or more, including during so-called deflation-inflation events, though not during some shorter-duration fluctuations in lava-lake elevation related to gas-pistoning (e.g., Patrick et al., 2015; Anderson et al., 2015; Patrick, Orr, Swanson, & Lev, 2016; Patrick, Swanson, & Orr, 2019). This correlation is present over most of the 2008-2018 timespan, with a 0.8 overall correlation coefficient (Fig. 14, 15, S25). The correlation implies that lava-lake elevation is analogous to a Pitot tube for the summit magma reservoir and responds proportionally to changes in reservoir pressure.

However, this relation is not constant as evidenced by both the non-linear relationship between lava-lake elevation and tilt (Fig. 14) and the variation in local correlation coefficients from almost 1 to negative values (Fig. 15). This indicates that the Pitot tube relation between ground inflation and lava-lake elevation changes over time. We believe that these deviations reflect superposition of processes on different characteristic timescales. For example, in early 2017 ground inflation and lava-lake elevation are positively correlated on day-month long timescales, but there is a long-term ground inflation trend

despite average lava-lake elevation remaining constant (Fig. 11). There are also abrupt events that change the relation between ground inflation and lava-lake elevation, such as the May 2015 intrusion (Fig. 11).

3.2.2 Conduit-reservoir resonance correlations

During most of the timespan conduit-reservoir oscillation T and Q exhibit a weak negative correlation, with an overall correlation coefficient of -0.06 but local correlation coefficients often around -0.7 (Fig. 14, 15, S25). There are isolated times where T and Q are positively correlated, such as in mid-2010 (correlation coefficient near 1) and mid-2012 (correlation coefficient around 0.7) (Fig. 10, 11, 15).

Conduit-reservoir oscillation T is positively correlated with lava-lake elevation during most of the timespan, with correlation coefficients mostly between 0.3 and 1 (Fig. 15), and a weak overall correlation coefficient of 0.11 (Fig. 14, S25). However, there are times with negative local correlations, such as around the 2014 Pu‘u ‘Ō‘ō eruption (correlation coefficient around -0.6), and in late 2017 (correlation coefficient around -0.7). The correlation between T and ground inflation (i.e., tilt) exhibits a similar trend to the correlation between T and lava-lake elevation after the arrival of a persistent lava-lake in late 2009, and exhibits a variable but mostly negative trend prior to this (Fig. 14, 15, S25). Conduit-reservoir T is positively correlated with event amplitude, even when considering only vertical velocity (which should not be sensitive to instrument tilt) (Fig. 14, S25).

Conduit-reservoir oscillation Q exhibits much less consistent correlations with ground inflation and/or lava-lake elevation than T does (Fig. 14, 15, S25). Throughout much of the studied timeline there is no significant correlation between Q and either dataset. There are several isolated time-segments such as June-September 2011 where Q is positively correlated with ground inflation and lava-lake elevation, and one time-segment from December 2010 to March 2011 with a significant negative correlation (Fig. 15).

We find increases in both conduit-reservoir event density and T around the inferred October 2012 and May 2015 intrusions. There is no obvious change in Q corresponding to either intrusion, though the correlation between T and Q does change from positive to negative at the October 2012 intrusion (Fig. 9, 15). Perhaps surprisingly, neither intrusion appears to correspond to changes in ground motion patterns (Fig. 16).

ERZ eruptions for which we detect conduit-reservoir oscillations both before and after the events (i.e., the June 2014 and May 2016 Pu‘u ‘Ō‘ō eruptions) do not obviously relate to changes in conduit-reservoir oscillation T or Q. However, sharp changes in the correlations between T and Q, T and lava-lake elevation/tilt, and Q and lava-lake elevation/tilt occur alongside the June 2014 eruption, and more subtle changes in these correlations may also be present alongside the May 2016 eruption (Fig. 9, 15). Interestingly, there are changes in ground motion patterns following both eruptions that are readily apparent in the time-series of Mogi source inversions and vertical/horizontal velocity ratios (Fig. 16).

3.2.3 Lava-lake sloshing correlations

Due to the sparsity of well-characterized lava-lake sloshing events it is difficult to robustly examine correlations with other other datasets on timescales of months or less. Long-term average lava-lake sloshing T increased over most of the timespan, except for during 2012 (when lava-lake sloshing events were sparse and exhibited large scatter in T) and a clear decrease during late 2015. The long-term increase in T roughly corresponds to an observed long-term increase in lava-lake surface area, and the decrease in lake 2015 roughly corresponds to a several month long decrease in average lava-lake elevation. Lava-lake sloshing Q exhibits large scatter over most of the timespan, with the exception of

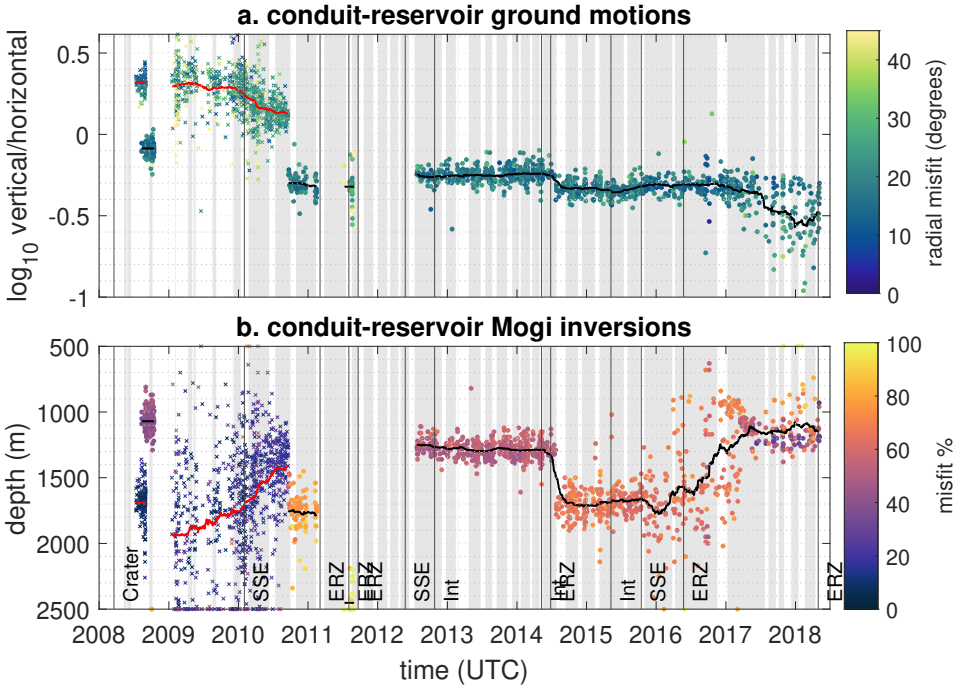

Figure 16. Ground motion patterns and Mogi spherical reservoir source inversions for conduit-reservoir oscillations. Dots and black lines indicate events and 120-day moving averages for times with more than 6 stations available. Crosses and red lines indicate events and 120-day moving averages for times with only one station available, so ground motion patterns are poorly constrained and should not be directly compared to events with more stations. Depths are relative to the caldera floor. 'Crater' indicates where the Halema'uma'u crater first formed, 'SSE' indicates slow slip events, 'Int' indicates documented summit intrusions, and 'ERZ' indicates eruptions along the East Rift Zone. Grey bars in all plots indicate times of long-term ground inflation (section 2.8).

during 2012 when Q was generally less than 20, and during 2015 when Q was generally between 10 and 30. There is a roughly linear relation between conduit-reservoir oscillation amplitude and lava-lake sloshing amplitude, though with an appreciable amount of scatter (Fig. 13). Lava-lake sloshing Q does not appear to be correlated with conduit-reservoir oscillation Q (Fig. 13), which could indicate that some properties that govern damping of the two resonant modes vary independently.

4 Discussion

Our new catalog of VLP seismic events provides an outstanding tool both to document the progression of a long-lived (10 year) open vent eruptive episode at Kīlauea Volcano and probe shallow magma plumbing system geometry and magma properties through time. In the following discussion we highlight how simple physical models for the resonant oscillations identified in Kīlauea seismic data may be used to understand some of the trends observed in the 2008-2018 eruptive sequence. We also identify observations that are not well explained by current models and that point to next steps for

understanding VLP seismicity at Kīlauea. Lastly, we interpret the 2008-2018 timeline of VLP seismicity with insights from the resonance models and other datasets and observations.

4.1 Interpreting changes in conduit-reservoir resonance

The conduit-reservoir oscillator model of Liang, Karlstrom, and Dunham (2020), which extends earlier work by (Chouet & Dawson, 2013), provides estimates of T and Q assuming a cylindrical conduit and isothermal conditions, and neglecting inertia and viscous drag in the overlying lava-lake and compressibility of magma in the conduit. The inviscid conduit-reservoir resonance period is:

$$T_0 = 2\pi\sqrt{\frac{L_c\bar{\rho}_c}{\Delta\rho_c g\sin\alpha + A_c C_t^{-1}}}. \tag{9}$$

where L_c is conduit length, $\bar{\rho}_c$ is average magma density in the conduit, $\Delta\rho_c$ is density difference between the bottom and top of the conduit, α is conduit dip angle, A_c is conduit cross-sectional area, and C_t is total reservoir storativity (from both magma compressibility and elastic reservoir stiffness). With viscous damping included, T and Q depend upon T_0 as well as a momentum diffusion timescale:

$$\tau_{visc} = \frac{R_c^2\bar{\rho}_c}{\mu_c}, \tag{10}$$

where R_c is conduit radius and μ_c is average magma viscosity. Liang, Karlstrom, and Dunham (2020) detail the full governing equations and numerical methods used to solve for T and Q.

This model involves a number of simplifications that limit its applicability for a detailed analysis of Kīlauea VLP seismicity and its observed relations to other datasets over time. Lava-lake elevation, which is strongly correlated with T at many times (Fig. 15), is not considered in this model. Inertia and viscous drag in the lava-lake might affect resonance, as could non-cylindrical conduit/lava-lake geometries, non-Newtonian magma rheology, and bubble growth and resorption (e.g., Karlstrom & Dunham, 2016) in the magma reservoir. Lastly, incorporating a background state model for density/viscosity profiles of the multiphase magma contained within the conduit-reservoir system based on known magma physics, chemistry, and outgassing dynamics would greatly enhance the applicability of the model. This could range from simple magmastatic cases (e.g., Karlstrom & Dunham, 2016) to considering exchange flow (e.g., Fowler & Robinson, 2018). This would allow changes in T and Q to be related to volcanologically important processes such as inputs of new melt/volatiles and changes in magma convection regimes. This would also allow comparison with summit gas datasets and inform how the magma density profile in the conduit shifts with lava-lake elevation and/or reservoir pressure, which likely plays a role in the observed correlations with these datasets. Implementing a model with these improvements is beyond the scope of this project, but the model of Liang, Karlstrom, and Dunham (2020) can still help interpret some of the observations from this VLP seismicity catalog.

Liang, Crozier, et al. (2020) conducted stochastic inversions for 4 events from 2008-2013, and favor a geometry consisting of a spherical reservoir with a centroid ∼1.4 km beneath the vent and a radius of ∼1 km, resulting in a conduit length of a few hundred meters. In this regime T and Q are controlled by conduit geometry and magma properties in the conduit, and have minimal sensitivity to reservoir compressibility (Fig. 17). However, the inversions show that there are many trade-offs that make uniquely constraining model parameters for a given event difficult without additional constraints. Fig. 17 illustrates this problem: T and Q vary with multiple unknown parameters that likely covary in different ways and on differing timescales. The inversions do show probable differences in both magma properties (density, density contrast, and viscosity) and in magma

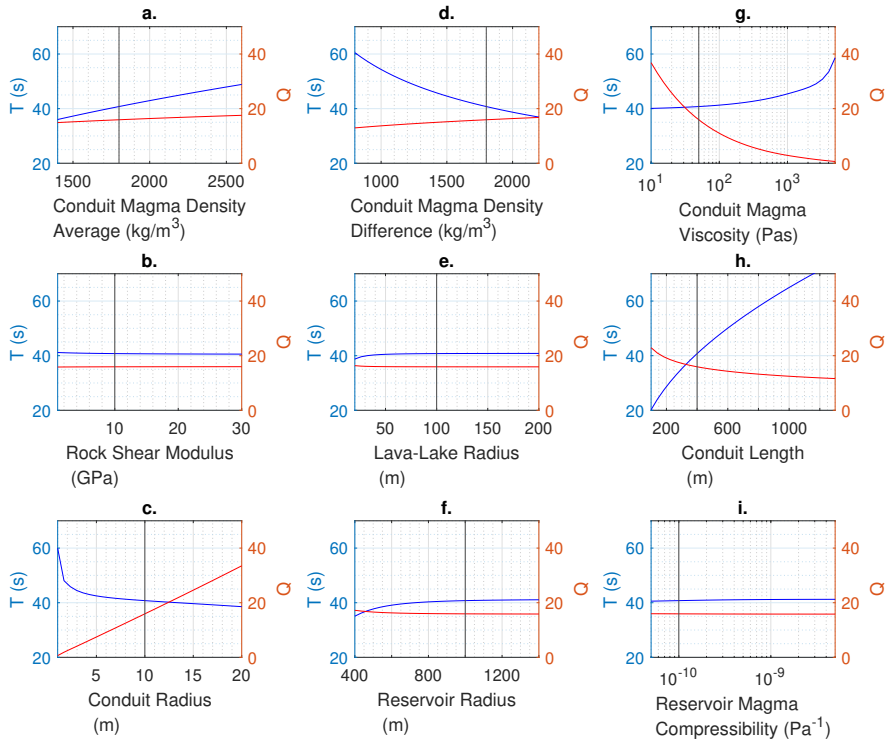

Figure 17. (a-i) Predicted variation in T and Q due to varying each model parameter in isolation in the conduit-reservoir resonance model of Liang, Karlstrom, and Dunham (2020) (Eq. 9-10), assuming a spherical reservoir geometry. Black lines indicate the default value used for each parameter.

system geometry (conduit length and radius) between the four events selected, though there is significant overlap of the probability density functions for these parameters.

Even robustly constraining the Kīlauea shallow magma reservoir geometry at a given time is difficult, as indicated by the scatter in even the simple metrics shown in Fig. 16 and by the uncertainty and/or differing results obtained in previous seismic and geodetic inversions. Some previous seismic studies have inferred a source consisting of intersecting dikes (Chouet & Dawson, 2011, 2013), and multiple previous seismic and geodetic studies have supported a spherical or ellipsoidal reservoir geometry (Baker & Amelung, 2012; Anderson et al., 2015; Anderson & Poland, 2016; Liang, Crozier, et al., 2020; Anderson et al., 2019). We have not shown source models such as dikes or ellipsoids since inversions with these more complex source models for single frequency components of these VLP events are often not well constrained (Crozier et al., 2018).

4.1.1 Short timescales

One way to reduce the number of free parameters is to focus on short timescales (hours-months), where it is probably reasonable to assume that the geometry of the system remains relatively constant except possibly at the few isolated times where abrupt changes in ground motion patterns occur (Fig. 16). Variation in T and Q on these short timescales is thus most likely related to changes in magma properties. Figure 17 shows

that of these magma properties, T is most sensitive to average magma density and magma density difference. Assuming reasonable values for other model parameters based off the inversions of Liang, Crozier, et al. (2020), variation in either density parameter of ∼500 kg/m^3 would be required to explain the observed month-scale variability in T of up to ∼6 s (e.g., July-September 2013, Fig. 11). Similarly, the day-scale variability in T of up to ∼3 s would require changes in either density parameter of ∼250 kg/m^3. Q is most sensitive to magma viscosity (Fig. 17). Variation in magma viscosity of up to an order of magnitude would be required to explain the observed day-month timescale variability in Q of up to a factor of four (e.g., Feb-April 2014, Fig. 11).

At many times there is a negative correlation between T and Q (Fig. 15). This could be produced by either isolated changes in magma density difference, magma viscosity, conduit radius, or conduit length, or by changes in various combinations of parameters (Fig. 17). There are also times where T and Q are positively correlated (Fig. 15). Conduit average magma density is the only parameter that could produce this in isolation, though since the effect of average magma density on Q is very minor the positive correlations more likely indicate changes in some parameter combinations. For example, increasing average magma density or decreasing magma density difference while decreasing magma viscosity would result in a net increase in both T and Q.

4.1.2 Magma properties

Variation in magma density in the Kīlauea shallow magma system primarily reflects changes in porosity, which is controlled by volatile contents, pressure, and temperature. In general, producing high porosities deeper in the conduit will require large amounts of volatiles since both volatile solubility and gas density increase with increasing pressure (e.g., Gonnermann & Manga, 2007; Iacono-Marziano et al., 2012). We show magma density as a function of volatile contents and pressure in Fig. 18 plot j. These densities are calculated using the average Kīlauea glass composition from Edmonds et al. (2013) and the H_2O-CO_2 solubility model of Iacono-Marziano et al. (2012). At 1 MPa (∼50-100 m deep) the required 500 kg/m^3 change in density could arise from a two-fold increase in H_2O or CO_2, while at 10 MPa (∼500-1000 m deep) this change would require a four-fold or more increase in H_2O or CO_2. Estimates of primitive (or 'parent') magma volatile contents are variable from 0.5-1 wt% CO_2, 0.4-0.7 wt% H_2O, and up to 0.18 wt% sulfur (Edmonds et al., 2015). However, different amounts of volatiles may be present at a given depth due to disequilibrium degassing (e.g., volatile accumulation or depletion due to gas fluxing and/or magma convection) since CO_2 begins exsolving well beneath the shallow reservoir and H_2O and sulfur will generally begin exsolving around the shallow reservoir or conduit (e.g., Iacono-Marziano et al., 2012; Edmonds et al., 2015).

Variation in apparent magma viscosity (melt + bubbles) could be due to changing porosity (the effects of which depend upon flow regime), dissolved H_2O concentration, melt temperature, and crystal contents (e.g., Llewellin & Manga, 2005; Giordano et al., 2008; Mader et al., 2013). We show how apparent magma viscosity μ might vary in response to temperatures and porosity in Fig. 18 plot k. We calculate melt viscosity μ_l from the model of Giordano et al. (2008) using the average Kīlauea glass composition from Edmonds et al. (2013), then apply the low capillary-number model from Llewellin and Manga (2005) to account for porosity ϕ:

$$\mu = (1 - \phi)^{-1} \mu_l \tag{11}$$

Porosity alone will generally only change viscosity by up to a factor of three, so the required order of magnitude changes likely also involve changes in temperature on the order of 100 C or significant changes in crystal contents (e.g., Mader et al., 2013).

Changes in convective regimes could cause changes in volatile contents, crystal contents, and melt temperature (e.g., Witham & Llewellin, 2006; Harris, 2008; Fowler & Robinson, 2018). For example, a single convective cell extending from the lava-lake surface though

the conduit might result in lower average magma temperatures in the conduit than separate convective cells in the lava-lake and conduit (Patrick, Orr, Swanson, & Lev, 2016). Injections of new volatiles and/or melt from depth, or changes in the background volatile/melt supply rate, could impact both temperature and volatile contents on various timescales. Stokes rise velocity of bubbles with radii of 1-100 mm are 0.01 mm/s-1 m/s, and simulations of bubble slugs show ascent velocities on the order of 1 m/s (Chouet et al., 2010). Based on inferred magma upwelling rates in the lava-lake of 0.15-0.3 m/s, circulation timescales in the lava-lake would be on the order of hours (Patrick, Orr, Swanson, & Lev, 2016). So volatile rise timescales through the conduit/lava-lake for large bubbles could be on the order of minutes, whereas smaller bubbles will mostly move by convecting with the surrounding melt. Shallowly-driven processes such as gas pistoning or foam buildup likely also contribute to changes in volatile contents on timescales of minutes-days (e.g., Nadeau et al., 2014; Patrick, Orr, Sutton, et al., 2016; Patrick, Swanson, & Orr, 2019).

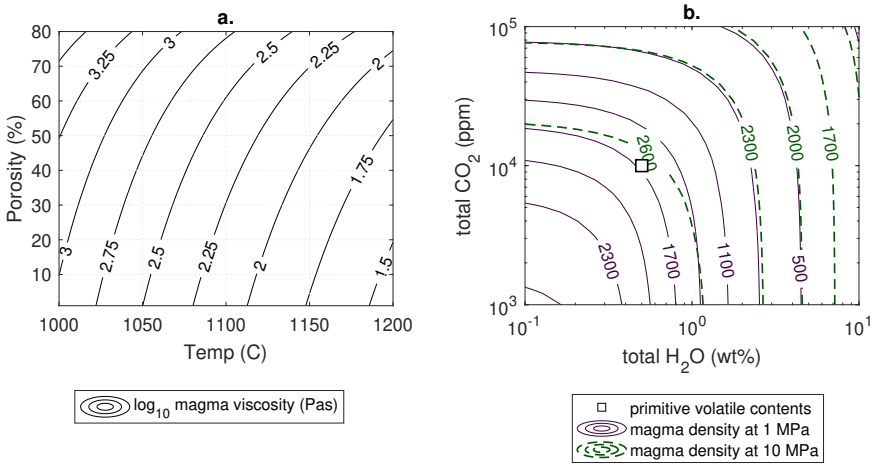

Figure 18. (a) Apparent magma viscosity as a function of temperature and porosity (section 4.1). (b) Magma density as a function of H_2O and CO_2 contents at two pressures (1 and 10 MPa correspond to magmastatic depths of 40-100 m and 0.4-1 km respectively) and an assumed temperature of 1100 C (section 4.1). The density of pure melt is ∼2650 kg/m^3. Estimates of primitive (or 'parent') magma volatile contents are from Edmonds et al. (2015).

4.2 Interpreting changes in lava-lake sloshing

The lava-lake sloshing events at Halemaʻumaʻu have previously been interpreted from models for surface gravity wave resonance of inviscid and incompressible fluid in a cylindrical or wedge-shaped tank (Dawson & Chouet, 2014; Liang & Dunham, 2020). The Halemaʻumaʻu crater geometry has changed over time but remained roughly cylindrical (Patrick, Swanson, & Orr, 2019), though with semi-diameters that are different enough to produce two concurrent sloshing signals with slightly different periods (Dawson & Chouet, 2014; Liang & Dunham, 2020). The crater walls are also slightly inward dipping, but the analysis of Liang and Dunham (2020) indicates that this dip will not produce appreciably different inviscid sloshing periods than vertical walls.

Studies of viscous incompressible fluid sloshing indicate that T and Q depend on fluid density, fluid viscosity, and tank geometry (e.g., Bauer, 1981; Ibrahim, 2005). Due to the presence of bubbles, a solidified surface crust, and possible foam layers under the crust, magma in the Halemaʻumaʻu lava-lake will generally be both compressible and strat-

775 ified (e.g., Carbone et al., 2013; Patrick, Orr, Sutton, et al., 2016; Poland & Carbone,
776 2016). The surface crust will not always act as a fully rigid or elastic cap since videos
777 of rockfall-triggered lava-lake sloshing show that the crust sometimes disintegrates/overturns
778 following event onsets (Orr et al., 2013; USGS, 2020), but it may still impact sloshing
779 dynamics for some events. An isotropic component of deformation found in previous in-
780 versions by Liang and Dunham (2020) suggests that the lava-lake sloshing drives magma
781 in and out of the underlying conduit/reservoir, so viscous dissipation from the conduit
782 may also be important. The degree of coupling between lateral fluid motions in the lava-
783 lake and vertical fluid motions in the conduit will depend on the offset of the top of the
784 conduit along the lava-lake sloshing axis, and thus on the direction of lava-lake sloshing.
785 Detailed analysis and inversions for T and Q for lava-lake sloshing events would require
786 modeling that can account for all these factors and is self-consistently coupled to the conduit-
787 reservoir resonance. However, we can still gain some new insights from our timeline of
788 lava-lake sloshing events using existing models for viscous sloshing in an isolated tank.

789 We assume a cylindrical crater geometry, for which analytical solutions for viscous
790 sloshing of an incompressible fluid are available. The period for the fundamental slosh-
791 ing eigenmode is given by (Case & Parkinson, 1957; Ibrahim, 2005):

$$T = 2\pi \left(\frac{jg}{R_L} \tanh\left(\frac{jh_L}{R_L} \right) \right)^{-1/2} \tag{12}$$

792 where R_L is lava-lake radius, h_L is lava-lake depth, ρ_L is magma density in the lava-lake,
793 and j is the Bessel root that satisfies $\partial J_1(jr)/\partial r|_{r=R_L} = 0$. Except when the lava-lake
794 is very shallow Q is controlled by viscous damping from the lava-lake sidewalls:

$$Q = 2\pi R_L \sqrt{\frac{2\rho_L}{\omega_L \mu_L}} \left(\frac{1 + (jR_L)^{-2}}{1 - (jR_L)^{-2}} - \frac{2jH_L}{\sinh(2jH_L)} \right)^{-1} \tag{13}$$

795 where μ_L is magma viscosity in the lava-lake; the additional terms for viscous damping
796 from the tank bottom and the fluid free surface are shown in Case and Parkinson (1957).
797 Figure 19 shows the effect of the model parameters on T and Q.

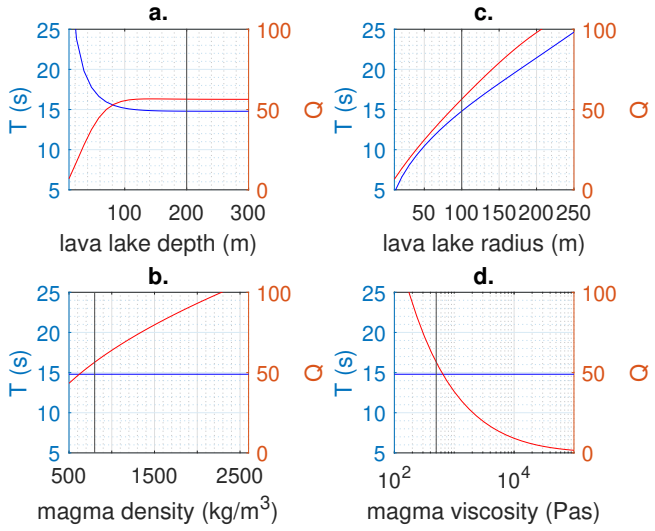

Figure 19. (a-d) Predicted variation in T and Q due to varying each model parameter in isolation in the viscous cylindrical tank model of (Case & Parkinson, 1957) (Eq. 12-13). Black lines indicate the default value used for each parameter.

The long-term increase in T is roughly consistent with the observed increases in lava-lake diameter according to Eq. 12 (Fig. 11, 19). On shorter timescales (months or less), the crater geometry should be relatively constant, though the effective lava-lake surface diameter could change slightly with changing lava-lake height due to the irregular crater shape (Patrick, Swanson, & Orr, 2019), which might explain the decrease in T in late 2015. Lava-lake sloshing T does exhibit variability of up to ∼3 s on timescales of months or less (Fig. 11), though part of this is from sloshing along different axes of the lava-lake which detailed seismic inversions and/or video of the lava-lake could help resolve (Liang & Dunham, 2020).

Lava-lake sloshing exhibits variation in average Q by up to a factor of four on timescales of years (Fig. 11), and similar variability on timescales of days-weeks. Changes in lava-lake depth should have a relatively minimal effect on Q except when the lava-lake is very shallow. Additionally, since many events with similar lava-lake elevation have very different Q (Fig. 11), we expect other factors are primary drivers of much of the variation in Q. For a density of 1000 kg/m^3, depth of 200 m, and radius of 100 m, producing the observed values of Q requires viscosities ranging from ∼400-8000 Pas (Fig. 19). The higher end of this viscosity range could likely only be produced by magma cooler than ∼1000 C (Fig. 18), which is appreciably less than geochemically inferred temperatures of 1160-1300 C (Edmonds et al., 2013). Low magma temperatures are expected near the lava-lake surface, where the solid crust temperatures are often ∼300 C, but temperatures should increase with depth in a manner dependent upon the convective regime (Patrick, Orr, Swanson, & Lev, 2016). The model used here has no vertical stratification, so does not indicate the sensitivity of Q to viscosity as a function of depth. However, it is likely that variation in magma properties with depth in the lava-lake is required to explain the observed variation in Q.

For the same forcing mechanism (e.g., rockfall) and forcing location, if everything else is constant we would expect a linear relationship between lava-lake sloshing amplitude and conduit-reservoir oscillation amplitude for small amplitude perturbations. The observed scatter could be caused by variable forcing location or mechanism, changes in the shallow magma system geometry, or changes in magma properties in the lava-lake or in the conduit-reservoir system. The lack of observed correlation between Q of conduit-reservoir oscillations and Q of lava-lake sloshing (Fig. 13), which is also apparent at short (months or less) timescales (Fig. 11), suggests that magma properties in the lava-lake and conduit may be largely decoupled. Changes in porosity alone will generally not cause order of magnitude changes in magma viscosity (Fig. 18), so appreciably different magma temperatures in the conduit and lava-lake at various times may be required to explain the large scatter in Q between the two oscillations, which could suggest separate convective cells in the lava-lake and conduit (Patrick, Orr, Swanson, & Lev, 2016).

4.3 Timeline of Kīlauea VLP Seismicity

Here we present a brief chronological overview of Kīlauea activity and summit VLP seismicity from 2008-2018, with particular focus on new observations not discussed in previous summaries of Kīlauea activity (Dawson & Chouet, 2014; Anderson et al., 2015; Poland & Carbone, 2016; Patrick, Swanson, & Orr, 2019). We break the timeline into one or two year long time-segments based on notable changes in VLP seismicity or eruptive activity.

4.3.1 January 2008-January 2010: Overlook Crater formation and intermittent lava-lake

The Overlook Crater first began forming inside the Halemaʻumaʻu summit crater in March 2008, following months of elevated SO_2 emissions and seismicity (e.g., Patrick et al., 2011; Dawson & Chouet, 2014; Patrick, Swanson, & Orr, 2019). Two years of el-

evated seismicity, long-term ground deflation, and occasional explosive events led to the establishment of a persistent lava-lake in early 2010 (Fig. 10). Much of the VLP seismicity during this time was periodic tremor (Fig. S18, S20), though there were times where discrete events were apparent (Fig. S17, S19) (Dawson & Chouet, 2014). Average T increased and decreased significantly multiple times during this interval, from a maximum of around 25 s in July 2008 to minima of around 13 s in February and August of 2009. While measurements of lava-lake level are limited during this time, the local minima in 2009 correspond with low reported lava-lake levels and the local maxima around July 2008 corresponds with higher reported lava-lake levels (Patrick, Swanson, & Orr, 2019). Q was highly variable but mostly less than 25. The high variability in T and Q over timescales from hours to months during this timespan likely reflects changes in both magma system geometry and magma properties, indicating a highly dynamic shallow magma system.

4.3.2 January 2010-March 2011 Kamoamoa fissure eruption: inflation and lava-lake filling

In early 2010 the lava-lake became persistent and filled from an elevation of 820 m to 950 m by early 2011, accompanied by corresponding long-term ground inflation (Fig. 10). Normal conduit-reservoir events with clear impulsive onsets and decays began occurring during this time, though VLP periodic tremor was also still present (Fig. 12) (Dawson & Chouet, 2014). A more continuous band of conduit-reservoir VLP events began in November 2009 and continued until the March 2011 Kamoamoa fissure eruption. Lava-lake sloshing events with T around 11 s began to appear alongside some of the Normal conduit-reservoir oscillations (Fig. 10).

The long-term increase in conduit-reservoir T from $\sim$20 s in early 2010 to $\sim$35 s by early 2011 is the largest such change observed during the 2008-2018 eruption. Unfeasibly large changes in average magma density and/or density contrast would be required to produce this increase in T if the shallow magma system geometry were constant, so it is likely that some evolution in geometry occurred over this time. Analysis of ground motion patterns during this time is hindered by limited station availability (Fig. 2). There was a continuous decrease in vertical/horizontal velocity ratios and Mogi source depths from early-mid 2010 (Fig. 16), though these may be partially due to the increasing contribution of tilt with increasing T (e.g., Maeda et al., 2011). Increases in conduit length of several hundred meters or decreases in conduit radius by around a factor of five could produce the changes T over this time-segment (Fig. 17). An increase in conduit length by several hundred meters over a 1-yr timescale due to solidification of melt at the roof of an ellipsoidal reservoir is unfeasible (e.g. Karlstrom & Richards, 2011), but could be caused by a migration of the intersection between the conduit and reservoir (e.g., if the conduit connects further down along the sidewalls of an ellipsoidal reservoir or dipping dike). Changes in lava-lake geometry and elevation during this time-segment likely also contribute, but are not considered in detail in existing models (section 4.1).

Our VLP catalog resolves two pronounced T local maxima in March and June 2010 more clearly than the catalog of Dawson and Chouet (2014); both are about 2 s above the background trend in T and about a month long. The June maximum corresponded to a pronounced local maximum in ground inflation and lava-lake elevation, but the March maximum is less clearly correlated with ground inflation or lava-lake elevation. For the remainder of this time-segment, conduit-reservoir oscillation T was well correlated with both ground inflation and lava-lake elevation. There was a gradual increase in Q starting around August 2010, followed by a rapid drop around February 2011. Q was correlated with T, ground inflation, and lava-lake elevation in mid-2010 then became anti-correlated with all three datasets by late 2010. These changes in correlations in early and late 2010 indicate additional changes in the shallow magma system superimposed upon the long-term increase in T over this time-segment.

4.3.3 March 2011 Kamoamoa fissure eruption-September 2011 Pu‘u ‘Ō‘ō eruption: multiple East Rift Zone eruption and lava-lake draining events

After the March 2011 Kamoamoa fissure eruption, there was a gradual increase in lava-lake elevation and ground inflation leading up to the August 2011 Pu‘u ‘Ō‘ō eruption, followed by another short stretch of ground inflation and lava-lake refilling before the September 2011 Pu‘u ‘Ō‘ō eruption (Fig. 10). Similar to Dawson and Chouet (2014), we do not detect very many VLP events between the March 2011 Kamoamoa and August 2011 Pu‘u ‘Ō‘ō eruptions, though there were some that exhibited strong glides in period. Between the August and September 2011 Pu‘u ‘Ō‘ō eruptions there was a cluster of low Q VLP activity with T around 20 s, and some events that exhibited strong glides in period (Fig. S23).

It is interesting that there were very few VLP events during most of this time-segment even at times when the lava-lake elevation was relatively high, especially since the strongly fluctuating lava-lake elevation might be expected to induce abundant rockfalls from the crater walls to trigger resonance. The changing lava-lake elevation and good correlation between lava-lake elevation and ground inflation during this time indicates that there was still an open hydraulic connection between the lava-lake and shallow magma reservoir. However, it is possible that the geometry of the conduit during this time changed in a manner that inhibited magma flow on timescales of the conduit-reservoir oscillation (e.g., became more constricted or sinuous).

4.3.4 September 2011 Pu‘u ‘Ō‘ō eruption-October 2012 intrusion: lava-lake filling and reappearance of conduit-reservoir resonance

Between the September 2011 Pu‘u ‘Ō‘ō eruption and May 2012 SSE average lava-lake level increased from ∼930 m to ∼960 m, although there was only a very slight corresponding ground inflation (Fig. 11). After the May 2012 SSE, which corresponded to a temporary 10-day drop in lava-lake elevation, lava-lake elevation and ground inflation both decreased until around August, then continually increased until the October 2012 intrusion. VLP seismicity during this time-segment consisted of Normal and Reverse events, VLP periodic tremor, sparse lava-lake sloshing, and gliding-frequency events (Fig. 12, S21, S24). Until around the time of the May 2012 SSE conduit reservoir oscillations had very low Q, sometimes below our threshold for robust detections (section 2.3) which contributes to the apparent sparsity of events (Fig. 11). After the May 2012 SSE average conduit-reservoir oscillation Q continually increased until the October 2012 intrusion. Average conduit-reservoir oscillation T decreased until around August then continually increased until the October 2012 intrusion and was well correlated with lava-lake elevation (Fig. 15). T and Q were positively correlated in late 2012 for the last time in the 2008-2018 timespan.

A steadily widening conduit, perhaps due to thermal erosion and/or increasing magmastatic pressure on the conduit walls, could explain the increase in conduit-reservoir Q over 2012. A very narrow conduit at the start of this time-segment would also be consistent with the reduced conduit-reservoir VLP seismicity during the previous time-segment. Alternately, the increase in Q could be caused by a decrease in magma viscosity. This would likely not be from a decrease in porosity, since if everything else were constant the very gradual ground inflation rate that occurs over this time-segment relative to the lava-lake filling rate would imply an increase in magma porosity. Viscosity decreases might instead reflect increases in magma temperature, perhaps indicating an influx of hotter magma from depth that may have been initiated by the 2012 SSE.

4.3.5 October 2012 intrusion-June 2014 Pu‘u ‘Ō‘ō eruption: stable lava-lake

Between the October 2012 intrusion and the June 2014 Pu‘u ‘Ō‘ō eruption there was a long-term ground inflation trend while average lava-lake level remained constant (Fig. 11), though on shorter timescales lava-lake elevation and ground inflation were well correlated (Fig. 15). VLP seismicity during this time included both Normal and Reverse events, periodic tremor, and lava-lake sloshing (Fig. 12, 13, S22). Until around late 2013 average conduit-reservoir T varied from 38-41 s over timescales of months and was generally well correlated with lava-lake elevation. After this T remained relatively constant despite continuing fluctuations in lava-lake elevation, and became anti-correlated with lava-lake height by April 2014. Average conduit-reservoir Q decreases from ∼20 to ∼11 by May 2013, followed by a non-monotonic increase to ∼25 by the June 2014 Pu‘u ‘Ō‘ō eruption. Conduit-reservoir Q was negatively correlated with T over most of the time-segment but exhibited variable correlation with lava-lake elevation and ground inflation. Local maxima in conduit-reservoir event density occurred during times of inflation in May 2013, August 2013, February 2014, and around the May 2014 intrusion (Fig. 13). Conduit-reservoir ground motions were constant over this time-segment, indicating a stable reservoir geometry (Fig. 16). Average lava-lake sloshing Q was highly variable between 6-50 but increased on average over this time-segment (Fig. 11).

The lack of changes in conduit-reservoir ground motions patterns around either the October 2012 or May 2014 intrusions likely indicates that these intrusions did not have direct enough hydraulic connections to the main shallow reservoir to be involved in the oscillations. However, the changes in correlations between T, Q, and lava-lake elevation around both intrusions does indicate some change in the shallow magma system. This could be related a change in magma properties if some of the shallow magma and/or the supply of new melt/volatiles from depth was routed into the intrusions. It is also interesting that the highest post-2011 VLP event density occurs around the May 2014 intrusion, despite this intrusion having a relatively minor signature in the other datasets.

4.3.6 June 2014 Pu‘u ‘Ō‘ō eruption-May 2016 Pu‘u ‘Ō‘ō eruption: variation in conduit-reservoir ground motion patterns

There was steady long-term ground inflation during most of this time-segment, with more rapid inflation in the months around the May 2015 intrusion (Fig. 11). Lava-lake elevation varied between 950-1000 m, except for the months leading up to the May 2015 intrusion when it increased sharply to 130 m and overflowed out of the overlook crater, then sharply dropped following the intrusion. The months after the May 2015 intrusion exhibit the only anti-correlation between lava-lake elevation and tilt after 2010 (Fig. 15). VLP seismicity during this time-segment included both Normal and Reverse conduit-reservoir events, periodic tremor, and lava-lake sloshing (Fig. 13). Local maxima in conduit-reservoir event density occurred during the May 2015 intrusion, May 2016 Pu‘u ‘Ō‘ō eruption, and generally near the onset of long-term inflation periods (for example October 2014, December 2014, and March 2015). After the June 2014 Pu‘u ‘Ō‘ō eruption there was an abrupt change in conduit-reservoir oscillation ground motions apparent as a decrease in vertical/horizontal ratios and in Mogi depths (Fig. 16). Ground motions then remained stable until around the October 2015 SSE when they became more variable. Conduit-reservoir T was relatively constant around 39 s except for increasing to 41 s in the months leading up to the May 2015 intrusion. Interestingly, the subsequent decrease in T occurred over months despite the rapid drop in lava-lake elevation; T remained correlated with lava-lake elevation during this time but not with tilt (Fig. 15). There was a month-long ∼1 s local minima in T corresponding to the October 2015 SSE. Conduit-reservoir Q averaged around 25 until a few months before the May 2015 intrusion, when it dropped to around 18 and remained stable for the remainder of the time-segment. Q

was either anti-correlated or not correlated with T during this time-segment and was not strongly correlated with lava-lake elevation or ground inflation.

The change in conduit-reservoir event displacement patterns after the June 2014 Pu‘u ‘Ō‘ō eruption likely reflects a change in reservoir geometry, and the lack of any corresponding changes in T or Q indicates that the conduit geometry probably remained constant. Since this change is very abrupt it might reflect the opening/closing of a dike or sill, perhaps peripheral structures extending from the main reservoir region. However, it is not clear why this would have been related to the ERZ eruption since there were apparently no strong changes in summit reservoir pressure. Conduit-reservoir ground motions were highly variable around the May 2016 Pu‘u ‘Ō‘ō eruption, so it is difficult to conclude whether this eruption directly corresponded to a change in reservoir geometry as the 2014 one did. While there were minimal changes in conduit-reservoir T and Q, lava-lake elevation, and ground inflation around the May 2016 Pu‘u ‘Ō‘ō eruption, an abrupt change in SO_2 emissions indicates that this event did perturb the summit magma system.

The anti-correlation between tilt and lava-lake elevation around the May 2015 intrusion is likely because the intruded magma contributed to ground inflation even while pressure dropped in the main shallow reservoir. As with the October 2012 and May 2014 intrusions, the lack of changes in conduit-reservoir ground motion patterns following this intrusion indicates that it did not have a direct enough hydraulic connection to the main shallow reservoir to be involved in the oscillations. Unlike those earlier intrusions the May 2015 intrusion does not correspond to clear changes in correlations between T, Q, and lava-lake elevation.

Conduit-reservoir events after the October 2015 SSE exhibit increased variability in Mogi depths (Fig. 16), but no clear changes in the other metrics for ground displacement patterns. This could reflect a subtle change in the shallow magma system geometry or rock properties that made the Mogi inversions more sensitive to noise. Alternately, it could indicate that the hydraulic connection to some feature of the shallow magma system (e.g., a peripheral dike or sill) is variable over this time. Tectonic stress changes from the October 2015 SSE could have conceivably contributed to either scenario.

4.3.7 May 2016 Pu‘u ‘Ō‘ō eruption-May 2018 caldera collapse onset: variation in conduit-reservoir ground motion patterns and climactic eruption precursors

Long-term averaged lava-lake elevation increased gradually until late 2016 when small overflows occurred (Patrick, Swanson, & Orr, 2019), then decreased gradually until mid-2017. Lava-lake elevation began increasing again more steeply in March 2018 before eventually overflowing on April 26, then began draining rapidly on May 2 (e.g., Neal et al., 2019) (Fig. 11). There was long term ground inflation over most of this time-segment, and lava-lake elevation and ground inflation were mostly correlated on shorter timescales except for a few months in mid-2017 (Fig. 15). VLP seismicity during this time included Normal and Reverse events, periodic tremor, and lava-lake sloshing (Fig. 12, 13, S12, S13, S14). Conduit-reservoir event density was relatively stable over this time-segment, while lava-lake sloshing events were numerous until mid-2017 then much sparser after this. Conduit-reservoir oscillation T was stable around 39 s until October 2017 when it dropped to 37 s; then increased again in the months leading up to the May 2018 collapse eruptions before sharply dropping from 40 s on May 5 to 32 s on May 7 when the last definitive conduit-reservoir event in our catalog occurred (Fig. 11). During this time-segment T was alternately correlated and un-correlated or anti-correlated with lava-lake elevation and ground inflation (Fig. 15). Conduit-reservoir oscillation Q remained stable around 18 and was anti-correlated with T until late 2017, when Q began to vary and show a correlation with lava-lake elevation and became uncorrelated with T. Conduit-

reservoir ground motion patterns remained highly variable over this time-segment, but average Mogi depths decreased until early 2017, after which they remained consistent and with lower misfit (Fig. 16).

That different ground motion metrics show large variability at different times within this time segment indicates that the evolution of reservoir geometry may have been complex, but it does seem that some gradual evolution was likely occurring at least until early 2017. The numerous changes in correlations around mid-2017 also indicate some change in the shallow magma system. The continual increase in T in the months leading up to the 2018 collapse eruption onset seems to be similar to the buildup to the October 2012 and May 2015 intrusions, which in all three cases seems to track increases in lava-lake elevation and ground inflation indicating a buildup of magma/pressure in the shallow summit magma system. The month-timescale fluctuations in average Q starting in late 2017 indicate some variability in magma properties, but that Q remains relatively low (mostly $<$20) could indicate that there was not a significant increase in magma temperature. This would be consistent with the idea that the increase in pressure could be explained primarily by a blockage along the ERZ rather than by an increase in the flux of new hotter magma from depth (Patrick et al., 2020). Detailed modeling of T, Q, and the other datasets available could yield more insight into what changes in the magmatic system were occurring during this time and what they could have indicated about the upcoming eruptions.

5 Conclusions

We have presented a fully automated workflow using wavelet transforms to both detect and categorize VLP seismic signals that arise from magma resonance. These methods can detect multiple distinct spectral peaks and provide robust estimates of quality factors. They do not rely upon any training data and are readily transferable to other volcanoes and to resonant signals in long-period seismic or infrasound data. We expect these methods will be useful for both analyzing historical seismic data and for near-real-time monitoring at various volcanoes.

We then used these methods to generate a catalog of VLP events that occurred between 2008-2018 during a prolonged open vent eruptive episode at Kīlauea Volcano, Hawaii USA. This catalog expands upon earlier VLP catalogs by characterizing more types of signals and providing refined estimates of quality factors, revealing new a rich and structured time series of events. We focus particularly on two common classes of events: the 'conduit-reservoir' oscillation, which is prevalent over most of this timespan and represents the fundamental eigenmode of the shallow magma plumbing system, and a 'lava-lake sloshing' resonance representing surface gravity wave propagation in the summit lava-lake. We document significant changes in period, quality factor, and ground motion patterns over timescales ranging from hours to decades for the conduit-reservoir oscillation, including consistent trends around intrusion and eruption events. We also characterize a trend of lava-lake sloshing between 2010 and 2018 that exhibits a relatively consistent increase in period over time but wide variability in quality factors. Both classes of VLP event exhibit variable correlations with each-other and with auxiliary geophysical data such as tilt, lava-lake elevation, and SO_2 emissions.

The variation in VLP event properties likely indicates changes in magma properties such as density and viscosity in the conduit and lava-lake over timescales ranging from hours to years, as well as both abrupt and gradual changes in magma plumbing system geometry. This places these resonant oscillations amongst a rich suite of existing data available to understand the evolution of the shallow magma system and processes occurring in it over the 2008-2018 eruptive episode. We anticipate that future co-inversions of these VLP oscillations and other geophysical data will lead to new insights into the

physical processes responsible for a dynamic and long-lived eruptive episode at Kīlauea volcano.

Appendix A Synthetic Waveform Tests

We construct synthetic seismograms to test the resonant signal detection and classification methods described in the methods section. Displacements are calculated from an isotropic point source in an elastic half space model (Aki & Richards, 1993), with the source located 1 km beneath the Halemaʻumaʻu vent. The synthetic source-time functions consist of combinations of step displacements and exponentially decaying sinusoids with impulsive onsets. We apply a sinusoidal taper to the signal onsets to prevent sharp discontinuities and create signals with continuous first derivatives (Fig. S26). The sinusoid used as a taper has the same period as the signal, amplitude equal to the initial signal amplitude divided by $\sqrt{2}$, and is joined at the location where the derivative and position of the taper match those of the signal. Where step displacements are also added, we taper the step displacement over the same wavelength used to taper oscillation onsets (Fig. S27). We then add white noise from a standard normal distribution, scaled to various fractions of the signal amplitude as listed in each test figure. We then calculate displacements and tilts at each station location using the point source Green's functions, and convolve these with the instrument responses (Maeda et al., 2011; Liang, Crozier, et al., 2020).

Acknowledgments

Additional figures S1-S27 are included in the supplement. The Kīlauea VLP seismicity catalog is available at *(included as a spreadsheet with this submission, and will also be uploaded to a data repository consistent with the Enabling FAIR data Project guidelines prior to publication).* Codes used to make and analyze the VLP catalog are available at https://bitbucket.org/crozierjosh1/vlp-seismicity-catalog-codes/src/master/, and the authors will provide updated versions and/or assistance upon request.

Seismic data from 2008-2011 was obtained from the USGS, subsequent seismic data is publicly available from IRIS. GPS data is publicly available from UNAVCO. Tilt-meter data is available at Johanson (2020). Lava-lake elevation data was obtained from the USGS, and is published up to 2018 in Patrick, Swanson, and Orr (2019). SO_2 data from 2007-2010 is available at Elias and Sutton (2012). SO_2 emission from 2014-2017 is available at Elias et al. (2018). The VLP seismicity catalog extended from the methods of Dawson and Chouet (2014) was obtained from the USGS.

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