

Improved Neutral Density Predictions through Machine Learning Enabled Exospheric Temperature Model

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Key Points:

- We develop a nonlinear global model for exospheric temperature prediction called EXEMPLAR-ML.
- We leverage Principal Component Analysis to improve our understanding of the EXEMPLAR-ML temperature formulation.
- EXEMPLAR-ML shows increased accuracy relative to satellite observations during strong geomagnetic storms.

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Abstract

The community has leveraged satellite accelerometer datasets in previous years to estimate neutral mass density and subsequently exospheric temperatures. We utilize derived temperature data and optimize a nonlinear machine-learned (ML) regression model to improve upon the performance of the linear EXEMPLAR (EXospheric TEMPeratures on a PoLyherdrAl gRid) model. The newly developed EXEMPLAR-ML model allows for exospheric temperature predictions at any location with a single model and provides performance improvements over its predecessor. We achieve a 4.2 K reduction in mean absolute error and a 3.42 K reduction in the standard deviation of the error. Like EXEMPLAR, our model's outputs can be utilized by the Naval Research Laboratory Mass Spectrometer and Incoherent Scatter radar Extended (NRLMSISE-00) model to more closely match satellite accelerometer-derived densities. We conducted two case studies where we compare the CHALLENGING Minisatellite Payload (CHAMP) and Gravity Recovery and Climate Experiment (GRACE) accelerometer-derived temperature and density estimates to NRLMSISE-00, EXEMPLAR, and EXEMPLAR-ML during two major storm periods. The storm-time temperature comparison showed error reductions of 7-10% and 2-5% relative to NRLMSISE-00 and EXEMPLAR, respectively, and the density comparison showed error reductions of 20-55% and 8-12%. We use Principal Component Analysis to identify the dominant modes of variability in the model over one solar cycle. This shows the model is dominantly driven by solar activity, and there is a strong latitudinal variation related to the Summer and Winter hemispheres.

Plain Language Summary

Density in the upper atmosphere is highly variable and difficult to model. Empirical density models often rely on temperature profile predictions to determine species and mass densities. One of three key parameters in determining the temperature profiles is the asymptotic value at the top of the thermosphere, called the exospheric temperature. By using temperatures derived from satellite acceleration measurements, we develop a machine-learned global temperature model called EXospheric TEMPeratures on a PoLyherdrAl gRid Machine Learned (EXEMPLAR-ML). We achieve a 4.2 K reduction in mean absolute error and a 3.42 K reduction in the standard deviation of the error relative to the model's predecessor. We also look at temperatures and densities along satellite orbits during two major geomagnetic storms from the 21st century. In this study, we see major improvements over a significant empirical model called NRLMSISE-00 and the linear predecessor to EXEMPLAR-ML. We also use a mathematical decomposition tool on the model outputs to assess its internal formulation. This shows that EXEMPLAR-ML is most heavily driven by solar activity and the seasons.

1 Introduction

Thermospheric mass density modeling is vital to satellite tracking and orbit prediction, yet it remains a formidable task for researchers and operators. The thermosphere is highly driven by external forcings, such as space weather events, and complex internal dynamics. The primary external driver to the thermosphere is solar irradiance (*Qian and Solomon 2011*). A majority of the solar irradiance energy input to the thermosphere can be captured with various solar indices and proxies (*Bowman and Tobiska 2006*). Although, these model drivers become less effective during solar minimum where other processes (e.g. composition changes) become increasingly relevant (*Bowman et al. 2008, Mehta et al. 2019*). Other space weather events, such as coronal mass ejections and solar flares, can send mass and energy towards Earth. This interacts with the magnetosphere resulting in Joule heating and particle precipitation which can cause large, sudden changes in density (*Fedrizzi et al. 2012, Deng et al. 2013*).

Nitric oxide (NO) is a cooling mechanism responsible for long-term cooling trends present during solar minimum (*Kockarts 1980*), and short-term temperature decreases following large geomagnetic storms (*Mlynczak et al. 2003, Knipp et al. 2017*). *Lei et al (2012a)* found that for the 2003 Halloween storm, temperature and density post-storm were appreciably lower than pre-storm levels. Many empirical models do not model this phenomena well and predict higher density in the recovery phase of major storms relative to observations (*Oliveira and Zesta 2019, Licata et al. 2021b*)

The Naval Research Laboratory Mass Spectrometer and Incoherent Scatter radar Extended (NRLMSISE-00 but referred to in this paper as MSIS) is a commonly used empirical thermospheric density model (*Picone et al. 2002*). As with many models (e.g. DTM (*Bruinsma 2015*) and JB2008 (*Bowman et al. 2008*)), MSIS heavily relies on temperature profiles to determine species densities and therefore mass density throughout the thermosphere. A key parameter in predicting the temperature profile is the exospheric temperature (T_{∞}) which is the asymptotic value that the temperature profile approaches at the top of the thermosphere, or thermopause (*Bates 1959, Jacchia 1965*). MSIS uses the Bates-Walker temperature profile (*Walker 1965*).

The availability of accelerometer-derived density estimates, from satellite such as CHALLENGING Minisatellite Payload (CHAMP) and Gravity Recovery and Climate Experiment (GRACE), has been advantageous for model development and assessment (*Luhr et al. 2002, Bettadpur 2012*). Over the lifetime of satellites with onboard accelerometers, we accumulate measurements over an abundance of locations and space weather conditions. Researchers have used these measurements to derive density estimates by removing accelerations from other sources (*Sutton 2008, Doornbos 2012, Calabia and Jin 2016, Mehta et al. 2017*). *Weimer et al. (2016)* used the density estimates from *Mehta et al. (2017)* to approximate exospheric temperatures by varying the parameter in MSIS using the bisection method until the model density closely matched that of the satellite. *Weng et al. (2017)* followed this methodology and used *Sutton's* CHAMP density estimates to create an exospheric temperature model.

Weimer et al. (2020) had used the derived exospheric temperatures to fit 1,620 linear models to make predictions on a polyhedral grid as a function of different space weather conditions over time. The model is called EXEMPLAR (EXospheric TEMPeratures on a PoLyherdrAl gRid). In this work, we develop an improved exospheric temperature model by using a single nonlinear artificial neural network (ANN) to make predictions at any location. This global model is called EXEMPLAR Machine Learned (EXEMPLAR-ML).

Principal Component Analysis (PCA), also referred to as Empirical Orthogonal Function (EOF) analysis or Proper Orthogonal Decomposition (POD), is used in this work to investigate the most dominant modes of variability in EXEMPLAR-ML. PCA has been used to analyze thermospheric density datasets previously and is often used in the development of reduced-order models (*Mehta and Linares 2017, Mehta et al. 2018, Gondelach and Linares 2020*). PCA has also been used to study satellite accelerometer datasets (*Matsuo and Forbes 2010, Lei et al. 2012b, Calabia and Jin 2016*). *Sutton et al. (2012)* used PCA to produce basis functions that represented the variability of temperature parameters used in an empirical *Jacchia* family model to improve its nominal density formulation (*Jacchia 1970*). *Ruan et al. (2018)* used CHAMP density estimates and a physics-based density model to develop an exospheric temperature model based in PCA. ML models tend to be ambiguous in nature, so we utilize PCA only to improve our understanding of the physical processes that drive EXEMPLAR-ML, not for model development.

The paper is organized as follows, we start by detailing the model development. Then, we discuss the methodology for temperature and density prediction using the model. After, we look at a baseline global temperature map to compare to the preceding model. We then investigate the dominant modes and PCA coefficients across one solar cycle. As a case

study, we compare the temperature and density predictions of MSIS, EXTEMLAR and EXTEMLAR-ML to CHAMP and GRACE-A during two major geomagnetic storms.

2 Methodology

2.1 Model Development

We had access to over 81 million exospheric temperature estimates from Weimer et al. (2020), the associated polyhedral grid locations, and different space weather indices/proxies as potential drivers. The best linear model from previous work used S_{10} , $\sqrt{M_{10}}$, Poynting flux totals (S_N and S_S), a temperature perturbation term (ΔT), day of year (doy), and universal time (UT). The cooling effect of Nitric Oxide emissions was simulated in the calculation of ΔT . We set out to use only operational indices for EXTEMLAR-ML so that it could be used in real time. Therefore, we use S_{10} , M_{10} , S_N , S_S , local solar time (LST), geodetic latitude, doy, and UT. The S_{10} and M_{10} indices are representative of solar activity and are part of Space Environment Technologies' (SET) *SOLAR2000* algorithm (Tobiska et al. 2000) which has been recently benchmarked by Licata et al. (2020b). Descriptions of these indices are thoroughly explained by Tobiska et al. (2008). The Poynting flux values are calculated using an electrodynamics model (referred to as the W05 model) described by Weimer (2005a, 2005b). For doy and UT, the model uses sine and cosine functions of the fractional doy and UT, generating four temporal inputs (t_1 - t_4), see Equation 1.

$$t_1 = \sin\left(\frac{2\pi \text{doy}}{365.25}\right) \quad t_2 = \cos\left(\frac{2\pi \text{doy}}{365.25}\right) \quad t_3 = \sin\left(\frac{2\pi UT}{24}\right) \quad t_4 = \cos\left(\frac{2\pi UT}{24}\right) \quad (1)$$

Upon having set up the data into inputs (described above) and labels (associated $\log_{10} T_{\infty}$), we leverage a tool called Keras Tuner (O'Malley et al. 2019). This allows us to provide a range of hyperparameters upon which the tuner searches to find the best architecture/model through a Bayesian optimization scheme. The tuner settings are shown in Table 1. The tuner is provided 1 million random training samples and 200,000 validation samples.

Table 1. Hyperparameter search space for EXTEMLAR-ML tuner.

Parameter	Choices
<i>Number of Hidden Layers</i>	1 – 10
<i>Neurons</i>	min = 64, max = 1024, step = 4
<i>Activations</i>	relu, softplus, tanh, sigmoid, softsign, selu, elu, linear
<i>Dropout</i>	min = 0.01, max = 0.50, step = 0.01
<i>Optimizer</i>	RMSprop, Adam, Adadelata, Nadam

Once complete, the tuner returns the ten best models, which we evaluate on independent data to confirm model performance. The best architecture to come out of the tuner is displayed in Table 2. This model was trained further using 60 million random samples, with the remaining 21 million used as validation/test data. Once the final model is developed, we test its validity by first comparing its global temperature maps to that of its predecessor. This is to check for anomalies in the temperature distributions for a given condition. While EXTEMLAR-ML is not restricted to prediction at the polyhedral grid locations, it still contains the name EXTEMLAR, because it is trained on temperatures that are binned to those locations.

Table 2. Model architecture for the best model from the EXEMPLAR-ML tuner. There are 10 inputs for Layer 1.

	Neurons	Activation	Dropout Rate
Layer 1	780	elu	0.23
Layer 2	584	tanh	0.13
Layer 3	336	softplus	0.13
Output	1	linear	0.00

2.2 Principal Component Analysis

Principal Component Analysis is an eigendecomposition technique that determines uncorrelated linear combinations of the data that maximize variance (F.R.S. 1901, *Hotelling* 1933). As mentioned in the Introduction, PCA is widely used in thermospheric density and exospheric temperature studies as both a modeling and analytical tool. We use PCA to get insight into EXEMPLAR-ML, which requires predictions covering a vast array of conditions. To accomplish this, we evaluated the model at all 1,620 EXEMPLAR grid locations between the solar maximums of solar cycle 23 and 24 (~2002-2014) at a three hour cadence. These predictions provide the global evolution of exospheric temperatures spanning a solar cycle. We perform PCA on the spatiotemporal temperature maps to obtain the U , Σ , and V matrices. PCA decomposes the data and separates spatial and temporal variations such that:

$$\mathbf{x}(\mathbf{s}, t) = \sum_{i=1}^r \alpha_i(t) U_i(\mathbf{s}) \quad (2)$$

where $\mathbf{x} \in \mathbb{R}^n$ is the model output state (full 2D temperature maps), r is the choice of order truncation, α_i are temporal coefficients, and U_i are orthogonal modes or basis functions. The modes are the first r columns of the left singular vector derived by performing PCA on an ensemble of model output solutions such that:

$$\mathbf{X} = \begin{bmatrix} | & | & | & \dots & | \\ \mathbf{x}_1 & \mathbf{x}_2 & \mathbf{x}_3 & \dots & \mathbf{x}_m \\ | & | & | & \dots & | \end{bmatrix} \quad \text{and} \quad \mathbf{X} = U\Sigma V^T \quad (3)$$

In Equation 3, m represents the ensemble size (one solar cycle). The temperature data is denoted by \mathbf{X} . U is the left unitary matrix, and it is made of orthogonal vectors that represent the modes of variation. Σ is a diagonal matrix consisting of the squares of the eigenvalues that correspond to the vectors in U . We can extract temporal coefficients by performing matrix multiplication between Σ and V^T . Therefore, the signs of the modes and coefficients are important in the analysis phase.

2.3 Geomagnetic Storm Case Study

We look at a 48 hour period between 12:00 UT on July 26, 2004 to 12:00 UT on July 28, 2004. This encompasses a day-long geomagnetic storm with a_p peaking at 300 $2nT$. We predict exospheric temperatures along the orbits of CHAMP and GRACE-A and compare it to the satellite-derived temperatures, MSIS, and the best linear EXEMPLAR model. We perform a similar comparison across the three-day period of October 29-31, 2003. This was one of the most significant geomagnetic storms of the 21st century, with a_p reaching 400 $2nT$ on two separate occasions. We then look at the CHAMP and GRACE-A densities plotted against MSIS, MSIS + EXEMPLAR, and MSIS + EXEMPLAR-ML for the same two periods. The density values for EXEMPLAR and EXEMPLAR-ML are obtained from MSIS while bypassing the normal T_∞ calculation within MSIS, using the models' temperature outputs instead, as described by Weimer et al. (2020).

3 Results

Once we obtained the model described in Section 2.1, we evaluated it on all training and validation data. This is shown in Figure 1. The top panel shows the original and predicted T_{∞} values in a scatter plot with a background contour showing the absolute error. The bottom panel shows the error distributions for training and validation samples.

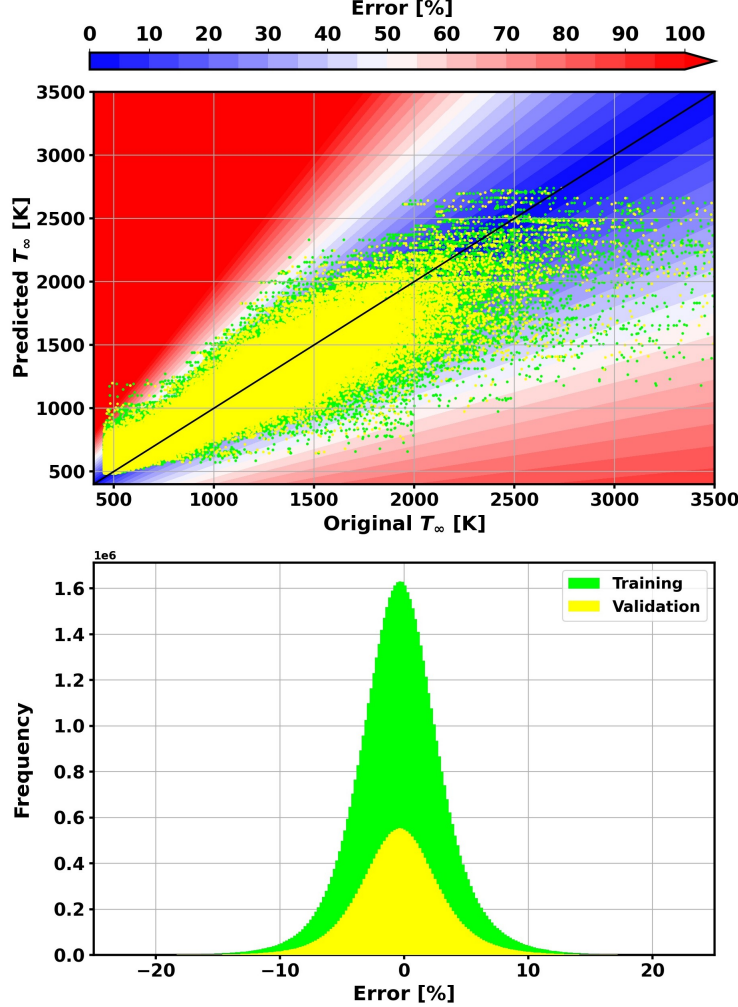


Figure 1. Comparison of observed and predicted T_{∞} for training (green) and validation (yellow) sets. The background contour shows mean absolute percent error for that temperature combination. The bottom panel shows histograms of error for both sets.

The T_{∞} scatter plot is fairly centered on the 1:1 line, which indicates a zero-error prediction. There is a skew towards underprediction at very high temperatures. However, some of these exospheric temperatures are not physical, due to some instances where an abnormally high temperature needs to be input to MSIS to obtain a match with the measured density. A distinguishing feature in the top panel is the similarity between training and validation performance. This indicates that the model is well-generalized and performs well on independent/new data. The bottom panel of Figure 1 shows that the error distributions have close to zero-mean, and over 98% of training and validation samples have less than 10% error. The mean absolute error for training and validation are both 2.81%, confirming the

generalized behavior of the model. Table 3 shows the mean absolute error and standard deviation of the error for EXTEMLAR-ML and the best linear EXTEMLAR model from Weimer et al. (2020), in Kelvin.

Table 3. Model statistics for linear EXTEMLAR (version 6) and EXTEMLAR-ML.

Model	Mean Absolute Error	Standard Deviation
EXTEMLAR v6	27.92 K	37.53 K
EXTEMLAR-ML	23.72 K	34.12 K

EXTEMLAR-ML achieves an absolute error reduction of over 4 K, and a reduction in the error standard deviation of over 3 K. As previously mentioned, the EXTEMLAR-ML drivers are only a subset of the EXTEMLAR version 6 (v6) drivers, in an effort to make the model operation-capable, which makes the performance improvement significant. Next, we evaluate EXTEMLAR-ML for a global grid to compare Figure 2 (below) with Figure 4 from Weimer et al. (2020).

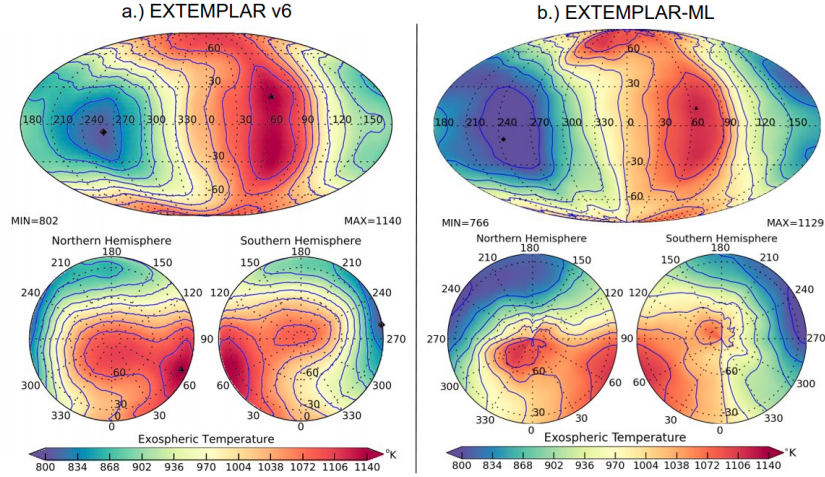


Figure 2. Global T_{∞} map with following inputs: $S_{10}=M_{10}=120$ sfu, $S_N=S_S=50$ GW, doy = 80, and UT = 15 hours for EXTEMLAR v6 (left) and EXTEMLAR-ML (right). The black triangle and square refer to the maximum and minimum temperature locations, respectively.

The global map has no clear defects and shows strong similarities to the EXTEMLAR v6 map for the same conditions. The locations of maximum and minimum temperatures are also similar to the previous model. The main difference is in the low temperature region in the western hemisphere, where there is a larger region of < 834 K for EXTEMLAR-ML. As there are only point estimates along orbits, there is no way to validate the global temperature maps, so we cannot confidently say which map is more accurate. However, we attribute this difference to the nonlinear temperature formulation by EXTEMLAR-ML.

3.1 Principal Component Analysis

With the extensive EXTEMLAR-ML prediction set described in Section 2.2, we can investigate the most dominant modes of variability and their associated PCA coefficients.

This is shown in Figure 3. It is important to note that the data was not centered prior to performing PCA, so the first mode is representative of the mean temperature distribution over this period. The longitudinal coordinates are local solar time scaled to longitude values with local noon being at 0° .

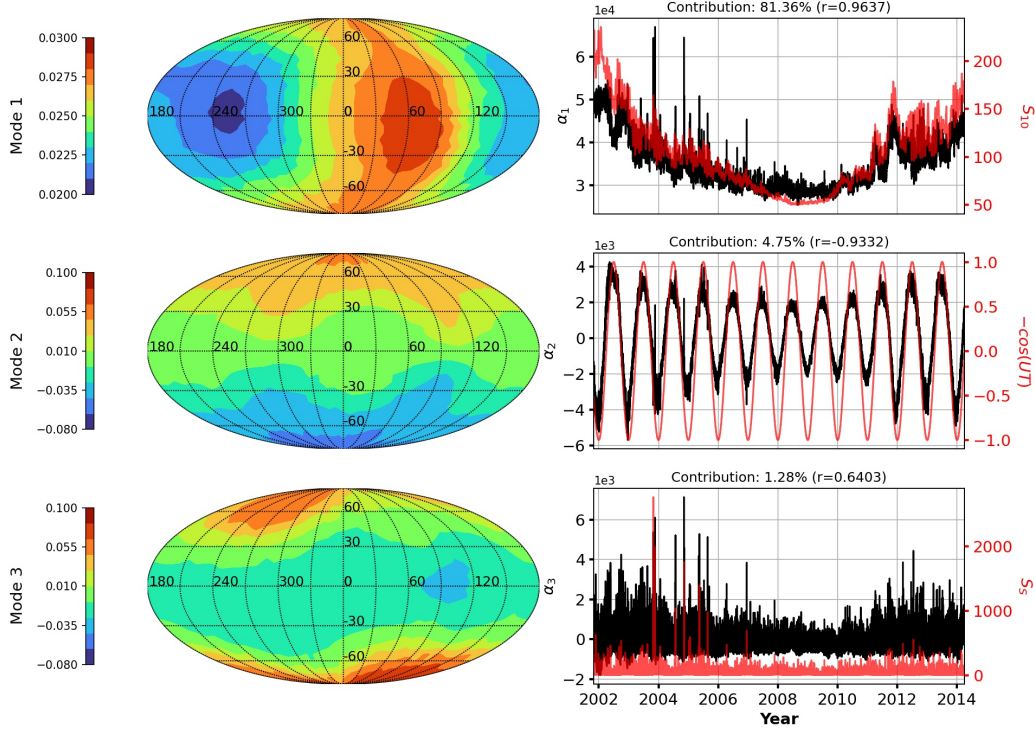


Figure 3. First three modes (left) and corresponding PCA coefficients (right) for the exospheric temperatures between November 1, 2001 and April 1, 2014. The most highly correlated drivers are plotted against the coefficients for comparison with the Pearson correlation coefficient shown in the title (*Schober et al.* 2018).

The first mode is representative of solar EUV heating denoted by the diurnal temperature map and strong correlation with S_{10} . This mode accounts for over 80% of the system's variance. Mode 2 represents a latitudinal Summer-Winter variation. There is a linear progression of the mode with latitude and α_2 oscillated about zero with a period of 365 days. It has an inverse relationship to t_2 , described in Equation 1, and its amplitude is a function of the solar activity. Mode 3 resembles a map of the magnetic field with the low latitude band following the magnetic equator. There are also peaks in the poles, and α_3 most strongly correlates with the Poynting flux totals (~ 0.64 with S_N and S_S). We suspect this mode corresponds to the effects of high latitude heating from either Joule heating or electron precipitation.

3.2 Modeled vs Observed Temperature Along Orbits

In an effort to compare model performance between other temperature models and the observations, we evaluate the MSIS (unmodified), EXEMPLAR v6, and EXEMPLAR-ML exospheric temperature values along CHAMP and GRACE-A orbits for two storm periods. The first is the 48 hour period between 12:00 UT on July 26, 2004 to 12:00 UT on July 28, 2004. The results are shown in Figure 4.

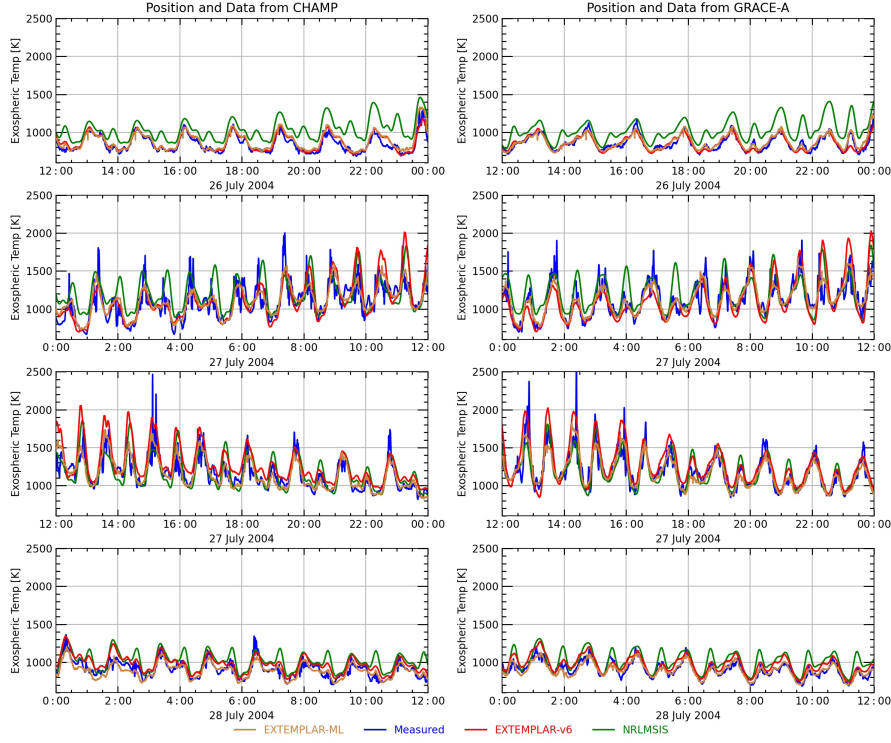


Figure 4. T_{∞} for MSIS, EXEMPLAR v6, EXEMPLAR-ML plotted alongside CHAMP (left) and GRACE-A (right) for a July 2004 geomagnetic storm.

In the pre-storm period (top panel), both EXEMPLAR models adequately track the satellites while MSIS overpredicts. During the early phase of the storm, both EXEMPLAR models still track the observations well, but the linear model becomes more sporadic around 10:00 UT on July 27th. Both models far outperform MSIS in the second panel. The third panel shows the storm recovery where EXEMPLAR-ML tracks the observations most closely, and EXEMPLAR v6 overpredicts. In the last twelve hours, both EXEMPLAR models do well, and MSIS overpredicts. The mean absolute error for EXEMPLAR-ML is 5.84% and 4.85% with respect to CHAMP and GRACE-A. For EXEMPLAR v6, the mean absolute error is 8.55% and 7.46% with respect to CHAMP and GRACE-A. MSIS has the highest errors with 15.05% and 12.86% with respect to CHAMP and GRACE-A. Figure 5 shows a similar comparison for a 72-hour period encompassing the 2003 Halloween storm.

EXEMPLAR-ML tracks the trends in both satellites for all 12-hour windows. Like the other two models, it has a more general response and does not track the abrupt peaks that are likely a result of imperfections in data processing. EXEMPLAR struggles for brief periods and MSIS has a mixed response with respect to accuracy. The mean absolute error for EXEMPLAR-ML is 6.26% and 5.64% with respect to CHAMP and GRACE-A. For EXEMPLAR v6, the mean absolute error is 10.89% and 9.98% with respect to CHAMP and GRACE-A. MSIS has the highest errors with 15.91% and 13.03% with respect to CHAMP and GRACE-A.

3.3 Modeled vs Observed Density Along Orbits

We input the exospheric temperatures from Figures 4 and 5 into MSIS in order to obtain the associated mass density values along the CHAMP and GRACE-A orbits. Figure 6

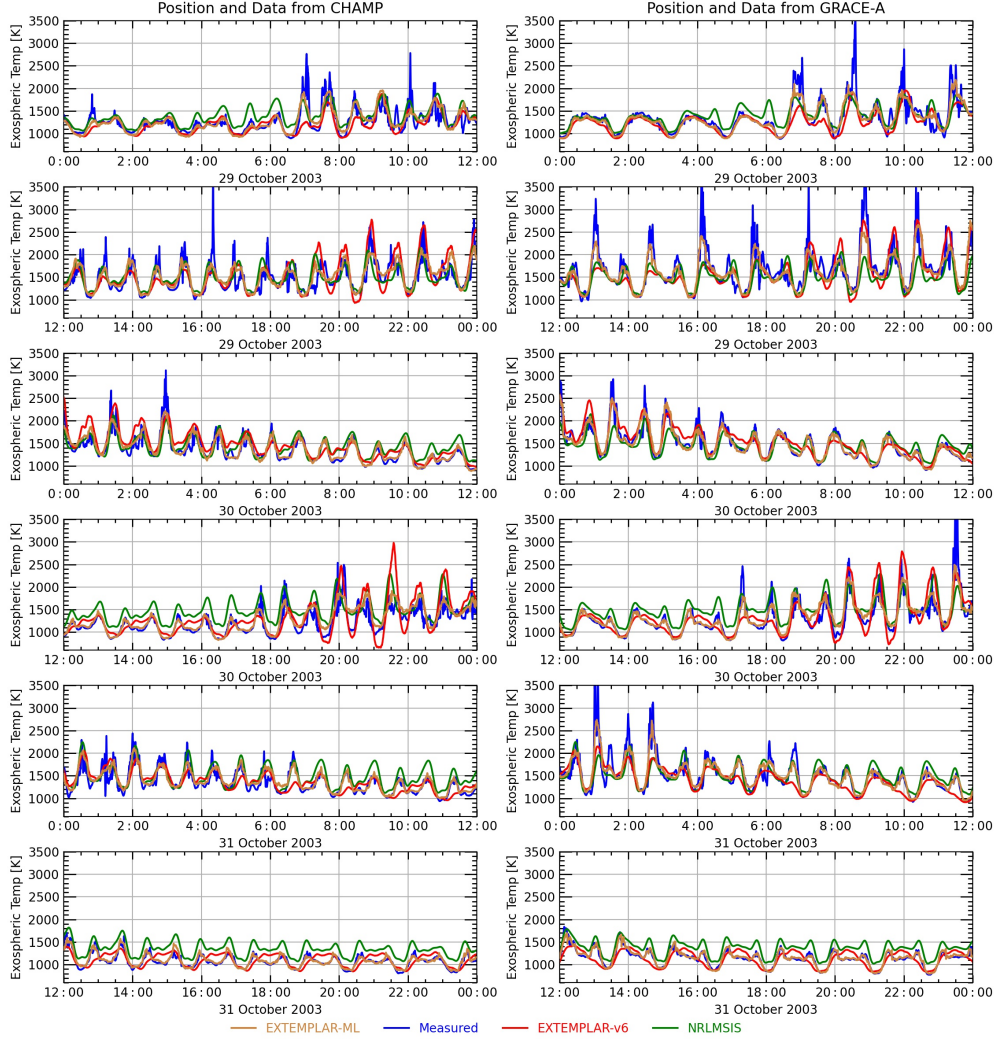


Figure 5. T_{∞} for MSIS, EXEMPLAR v6, EXEMPLAR-ML plotted alongside CHAMP (left) and GRACE-A (right) for the 2003 Halloween Storm.

shows the modeled densities, including the unmodified MSIS values, along with the satellite density estimates for the July 2004 storm.

The overprediction of exospheric temperature by MSIS in the first 12 hours, seen in Figure 4, causes its modeled density to be notably higher than the observed values. Both EXEMPLAR models provide similar accuracy pre-storm, but EXEMPLAR-ML more closely matches the CHAMP and GRACE-A estimates during the storm. In the recovery phase, EXEMPLAR-ML densities are more similar to GRACE-A than to CHAMP. The mean absolute error for EXEMPLAR-ML is 19.13% and 20.81% with respect to CHAMP and GRACE-A. For EXEMPLAR v6, the mean absolute error is 27.78% and 32.33% with respect to CHAMP and GRACE-A. MSIS has the highest errors with 62.32% and 75.38% with respect to CHAMP and GRACE-A. Figure 7 shows the density variations resulting from the temperatures in Figure 5.

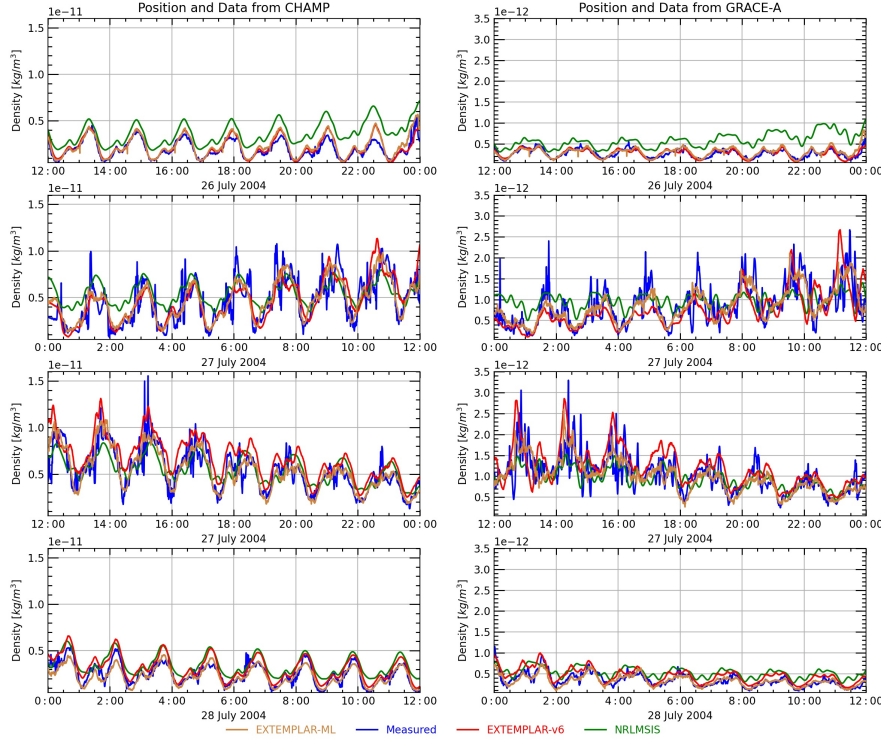


Figure 6. Density for MSIS, EXTEMLAR v6, EXTEMLAR-ML plotted alongside CHAMP (left) and GRACE-A (right) for a July 2004 geomagnetic storm.

EXTEMLAR-ML tracks the satellite densities well for the entire three-day period. The performance enhancement is most notable in the recovery phase (bottom panel) where the other two models tend to overpredict. The ability to capture the anomalously low temperature and density from enhanced NO production following a shock-led geomagnetic storm is highly desired as this prolonged period of lower than expected density can result in substantially different satellite positions in the context of conjunction analyses (*Oliveira and Zesta 2019*). The mean absolute error for EXTEMLAR-ML is 14.43% and 15.94% with respect to CHAMP and GRACE-A. For EXTEMLAR v6, the mean absolute error is 24.62% and 25.34% with respect to CHAMP and GRACE-A. MSIS has the highest errors with 35.39% and 35.97% with respect to CHAMP and GRACE-A.

4 Summary

In this work, we developed and optimized a machine learned nonlinear regression model to predict exospheric temperatures given a set of operational Space Weather and temporal drivers. This model, called EXTEMLAR-ML, has nearly identical training and validation/test performance with 2.81% mean absolute error across 81 million available samples. This is an extension of a linear EXTEMLAR model developed by Weimer et al. (2020). Using fewer drivers, EXTEMLAR-ML outperforms EXTEMLAR with a 4.20 K decrease in absolute error and a 3.41 K decrease in the error standard deviation. An advantage of EXTEMLAR-ML is that the single model can provide temperature predictions at any location, which was a limitation of its predecessor. The use of PCA provided insight to the temperature formulation within the "black-box" ML model. The first mode represented the effects of solar EUV heating and accounted for 81% of the system's variance. Latitudinal variations accounted for the next 4.75% of the variance and were still a function of solar ac-

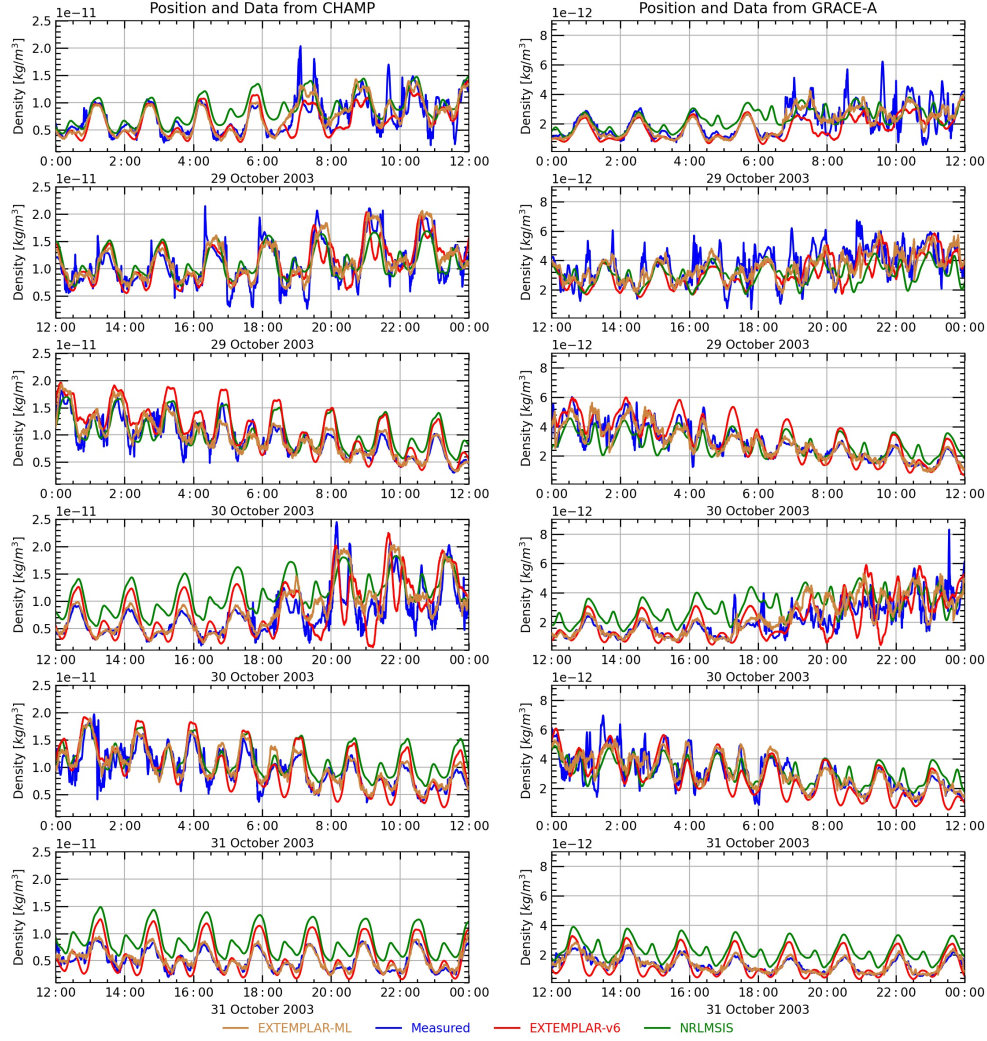


Figure 7. Density for MSIS, EXEMPLAR v6, EXEMPLAR-ML plotted alongside CHAMP (left) and GRACE-A (right) for the 2003 Halloween Storm.

tivity. The last mode we looked at only accounted for 1.28% of the variance but described the effects of high latitude heating caused by geomagnetic storms.

We performed two case studies where EXEMPLAR-ML along with EXEMPLAR v6 and MSIS predicted T_{∞} along CHAMP and GRACE-A orbits during two major geomagnetic storms. In the July 2004 storm, EXEMPLAR-ML achieved error reductions along both CHAMP and GRACE-A's orbits ranging from 2.07-9.35% compared to EXEMPLAR v6 and MSIS. In the 2003 Halloween storm, EXEMPLAR v6 struggled during periods, leading to a higher error reduction of 4.57% and 3.97% with respect to CHAMP and GRACE-A. When these temperatures were used for density prediction, the relative accuracy of EXEMPLAR-ML became more pronounced. The error reduction from EXEMPLAR in terms of the resulting density ranged from 8-11% and 9-12% with respect to CHAMP and GRACE-A, respectively for the two storms. In the future, we plan to incorporate model uncertainty into EXEMPLAR-ML (Licata *et al.* 2020a, Licata and Mehta 2021, Licata *et al.* 2021a). We plan to develop a newer model using temperatures derived with NRLMSIS 2.0

(Emmert *et al.* 2021). With the successive model, we also plan to use the exact observation locations to reduce errors associated with binning measurements to the polyhedral grid.

Data Availability Statement

CHAMP and GRACE density estimates from (Mehta *et al.* 2017) can be found at <http://tinyurl.com/densitysets>. A data archive containing the supplemental graphs of neutral density predictions can be accessed online (at <https://doi.org/10.5281/zenodo.3525166>). Also contained here are the adjustments to the NRLMSISE-00 model supplied by J. Emmert; the total Poynting flux into both Northern and Southern Hemispheres from the Weimer 2005 model, for years 2002–2017; the derived ΔT values; and EXTEM-PLAR model code with the required files.

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