

1 Estimation of absolute stress in the hypocentral
2 region of the 2019 Ridgecrest, California, earthquakes

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3 **Abstract.** Strength of the upper brittle part of the Earth’s lithosphere
4 controls deformation styles in tectonically active regions, surface topogra-
5 phy, seismicity, and the occurrence of plate tectonics, yet it remains one of
6 the most debated quantities in geophysics. Direct measurements of stresses
7 acting at seismogenic depths are largely lacking. Seismic data (in particu-
8 lar, earthquake focal mechanisms) have been used to infer orientation of the
9 principal stress axes. I show that the focal mechanism data can be combined
10 with information from precise earthquake locations to place constraints not
11 only on the orientation, but also on the magnitude of absolute stress at depth.
12 The proposed method uses relative attitudes of conjugate faults to evaluate
13 the amplitude and spatial heterogeneity of the deviatoric stress and frictional
14 strength in the seismogenic zone. Relative fault orientations (dihedral an-
15 gles) and sense of slip are determined using quasi-planar clusters of seismic-
16 ity and their composite focal mechanisms. The observed distribution of di-
17 hedral angles between active conjugate faults in the area of Ridgecrest (Cal-
18 ifornia, USA) that hosted a recent sequence of strong earthquakes suggests
19 in situ coefficient of friction of 0.4-0.6, and depth-averaged shear stress on
20 the order of 25-40 MPa, intermediate between predictions of the “strong”
21 and “weak” fault theories.

1. Introduction

22 There is a long-standing debate regarding the level of average shear stress in the Earth's
23 crust [Rice, 1992; Hardebeck and Hauksson, 2001; Scholz, 2000]. Estimates of earthquake
24 stress drops place a lower bound on shear stress resolved on seismogenic faults on the
25 order of 1 - 10 MPa [Choy and Boatwright, 1995; Allmann and Shearer, 2009]. Laboratory
26 measurements of quasi-static rock friction [Byerlee, 1978; Dieterich, 1981; Marone, 1998;
27 Mitchell *et al.*, 2013, 2015], orientation of young faults with respect to the inferred principal
28 stress axes [Walsh and Watterson, 1988; Collettini and Sibson, 2001], and measurements
29 in deep boreholes in stable intraplate interiors [Zoback *et al.*, 1993; Townend and Zoback,
30 2000] suggest that the brittle upper crust should be able to support much higher deviatoric
31 stresses on the order of the lithostatic pressure (> 100 MPa for ~ 15 km thick seismogenic
32 zone), provided that the pore fluid pressure is approximately hydrostatic. Extrapolation of
33 laboratory measurements of quasi-static friction to in situ rock failure, and the assumption
34 of hydrostatic pore pressure constitute the so-called “strong fault” theory [Byerlee, 1978;
35 Scholz, 2000].

36 In contrast, unfavorable orientation of some mature faults with respect to the principal
37 stress axes [Mount and Suppe, 1987; Wernicke, 1995; Wang and Fialko, 2018], the “heat
38 flow paradox” of the San Andreas Fault [Lachenbruch and Sass, 1980], high degree of slip
39 localization on exhumed faults [Chester *et al.*, 2005; Fialko, 2015], a possibility of fluid
40 over-pressurization [Sibson, 2004], low frictional strength of some parts of mature faults
41 suggested by scientific drilling experiments [Lockner *et al.*, 2011], and strong dynamic
42 weakening observed in laboratory friction experiments at slip rates in excess of ~ 0.1

43 m/s [*Han et al.*, 2007; *Di Toro et al.*, 2011; *Goldsby and Tullis*, 2011; *Brown and Fialko*,
44 2012] lend support to the “weak fault” theory according to which faults may operate at
45 background deviatoric stresses well below the failure envelope predicted by the Byerlee’s
46 law [e.g., *Sibson*, 1990; *Noda et al.*, 2009; *Thomas et al.*, 2014]. Low effective friction
47 on major plate boundary faults is also warranted by geodynamic models of large-scale
48 tectonic phenomena such as subduction and orogeny [e.g., *Toth and Gurnis*, 1998; *Sobolev*
49 *and Babeyko*, 2005; *Stern and Gerya*, 2018].

50 One possible explanation reconciling disparate views on the magnitude of deviatoric
51 stresses in the lithosphere is that the effective fault strength may depend on the fault
52 “age”, or total offset: young developing faults may be relatively strong while mature well-
53 slipped faults may be weak, possibly because of activation of various weakening mech-
54 anisms with an increasing cumulative slip [*Fialko and Khazan*, 2005; *Rice*, 2006; *Noda*
55 *et al.*, 2009; *Thomas et al.*, 2014; *Fialko*, 2015]. However, conditions that govern such a
56 transition, and the evolution of fault strength as a function of a cumulative offset are still
57 poorly known.

58 Our understanding of the fault strength problem is severely limited by the lack of mea-
59 surements of deviatoric stress at seismogenic depths. Apart from a scarce set of point
60 measurements in deep boreholes [*Plumb and Hickman*, 1985; *Zoback et al.*, 1993; *Lockner*
61 *et al.*, 2011], most of the available information is derived from analyses of seismic data.
62 The most commonly used method of “stress inversion” relies on earthquake focal mecha-
63 nisms to solve for the orientations of principal stress axes that are most consistent with
64 all of the focal mechanisms in a specified volume [*Gephart and Forsyth*, 1984; *Michael*,

65 1987; *Hardebeck and Hauksson*, 2001]. This method however is unable to determine the
66 magnitude of deviatoric stress.

67 In this paper I show that under certain conditions the magnitude of deviatoric stress
68 can be estimated using a distribution of fault orientations with respect to one of the
69 principle stress axes, or between sets of conjugate faults activated by a given ambient
70 stress. One location where the respective conditions appear to be met is a Ridgecrest
71 area in the northern part of the Eastern California Shear Zone that hosted a sequence of
72 strong earthquakes in 2019 [*Ross et al.*, 2019; *Hauksson and Jones*, 2020; *Jin and Fialko*,
73 2020]. I use microseismicity data to identify active faults in the Ridgecrest area and
74 quantify their orientations, and use the latter to evaluate the magnitude of shear stress
75 acting in the seismogenic zone.

2. Conjugate faults as stress meters

76 Laboratory experiments and geological observations indicate that failure of relatively
77 intact rocks is well described by the Mohr-Coulomb theory [*Lockner et al.*, 1992; *Walsh*
78 *and Watterson*, 1988; *Collettini and Sibson*, 2001; *Scholz*, 2019]. The latter predicts that
79 the failure criterion is independent of the intermediate principal stress (i.e., is intrinsi-
80 cally two-dimensional), and failure can equally likely occur on mutually antithetic sets of
81 planes that are parallel to the intermediate principal stress axis, and make an acute angle
82 with the maximum compressive stress axis. The antithetic failure planes are referred to
83 as conjugate faults [*Anderson*, 1951; *Twiss and Moores*, 1992, p. 173]. A dihedral angle
84 between the newly formed conjugate faults is a measure of internal friction, and can be
85 used to infer the state of stress at the time of failure [*Barton*, 1976; *Angelier*, 1994]. In
86 practice, available data rarely allow one to discriminate between slip on newly formed vs

87 pre-existing faults, and/or faults that experienced a finite rotation since their inception
88 [e.g., *Nur et al.*, 1986; *Fialko and Jin*, 2021]. Seismic focal mechanisms that are widely
89 used to infer orientations of the principal stress axes in the seismogenic zone [*Gephart*
90 *and Forsyth*, 1984; *Michael*, 1987; *Hardebeck and Hauksson*, 2001] are not suitable for
91 studying the relationships between active conjugate faults because because of two fun-
92 damental limitations. First, uncertainties in the fault plane solutions are typically too
93 large, especially for small to intermediate-size events [*Hardebeck and Shearer*, 2002; *Yang*
94 *et al.*, 2012; *Duputel et al.*, 2012], to be useful for evaluation of dihedral angles. Second,
95 an intrinsic ambiguity between the two nodal planes in a focal mechanism does not allow
96 one to isolate sets of synthetic vs antithetic faults, required to define a dihedral angle
97 between the respective fault planes.

98 These limitations can be mitigated by combining information provided by focal mecha-
99 nisms with geometric constraints from the well-determined earthquake hypocenters. Pre-
100 cisely relocated seismicity catalogs reveal ubiquitous lineated clusters of earthquakes that
101 illuminate faults or fault segments of various sizes and strikes (e.g., see Figure S1 in Sup-
102 plementary Materials). Such clusters of earthquakes can be used to map the distribution
103 and attitude of active faults throughout the seismogenic layer. Fault strikes can be deter-
104 mined with accuracy up to several degrees, an order of magnitude improvement over the
105 individual focal mechanism solutions. Also, fault orientations (well defined by seismicity
106 lineations) along with the polarity of focal mechanisms uniquely constrain the sense of
107 fault slip. I illustrate the method using data from the Ridgecrest area in Eastern California
108 Shear Zone (ECSZ) that hosted a sequence of strong earthquakes in 2019 (Figure 1).

3. Data and methods

109 The ECSZ is an emergent plate boundary that accommodates an increasing fraction of
110 the relative motion between the Pacific and North American plates since its inception 6-10
111 Ma [*Dokka and Travis, 1990; Nur et al., 1993; McClusky et al., 2001; Tymofyeyeva and*
112 *Fialko, 2015; Floyd et al., 2020*]. As such, the ECSZ is a natural laboratory for studying the
113 development and evolution of new as well as re-activation of old fault systems. The ECSZ
114 is currently the most seismically active region in California, with 3 major earthquakes
115 occurring over the last 30 years [*Sieh et al., 1993; Hauksson et al., 2002; DuRoss et al.,*
116 *2020*]. The most recent major event with magnitude 7.1 occurred in July 2019 near the
117 town of Ridgecrest in the northern part of the ECSZ (Figure 1), and involved rupture of
118 a system of right and left-lateral strike-slip faults [*Ross et al., 2019; Hauksson and Jones,*
119 *2020; Jin and Fialko, 2020*].

120 The nearly perpendicular orientation of conjugate faults ruptured by the Ridgecrest
121 earthquakes (Figure 1b) is distinctly different from optimal orientations predicted by the
122 strong fault theory (dihedral angles of 50-60 degrees for the coefficient of friction of 0.6-0.8)
123 [*Sibson, 1990; Scholz, 2019*]. This prompted suggestions that in situ coefficient of friction
124 is close to zero [*Ross et al., 2019*]. Alternatively, high-angle conjugate faults could result
125 from rotation away from the optimal orientation since the initiation of the ECSZ [*Fialko*
126 *and Jin, 2021*]. As noted by *Fialko and Jin [2021]*, a pattern of high-angle faulting similar
127 to that involved in the 2019 earthquake sequence is prevalent in a broader region around
128 the 2019 ruptures (Figure 1a). I start by quantifying the distribution of fault strikes and
129 relative orientations between conjugate faults expressed in microseismicity (Figure 1a).

3.1. Analysis of fault orientations

130 To identify a population of active faults in the Ridgecrest area, I use a refined catalog
131 of earthquake focal mechanisms for southern California with earthquake locations derived
132 from waveform cross-correlation [Yang *et al.*, 2012], updated to include data up to year
133 2020 (see Section “Data availability” in Supplementary Materials). The catalog data
134 for the area of interest include around 3.2×10^4 focal mechanisms for earthquakes that
135 occurred between January 1981 and July 2019 (Figure 1a). The orientation of seismically
136 active faults is evaluated using the following procedure. Seismicity on sub-vertical strike-
137 slip faults is manifested by lineated clusters of epicenters in the map view (Figure 1). I use
138 an unsupervised learning algorithm OPTICS (Ordering Points To Identify the Clustering
139 Structure) to select clusters of events that satisfy prescribed criteria of proximity and
140 density [Ankerst *et al.*, 1999]. An event epicenter is selected as a core point of a cluster if
141 it has a number of geometrically defined neighbors equal to or greater than 10. The search
142 algorithm is executed iteratively, with an increasing distance that defines neighbors within
143 a cluster, from 0.5 to 1.5 km. At the end of each iteration selected clusters are removed
144 from the catalog and the search continues. Clusters chosen by the OPTICS algorithm
145 can have diverse geometries that are not necessarily linear. To select clusters that have
146 a quasi-linear shape, and estimate the best-fit linear trends, I use RANSAC (Random
147 Sample Consensus) [Schnabel *et al.*, 2007] and robust linear regression algorithms. This
148 method is similar to that used by Skoumal *et al.* [2019] to analyze induced seismicity
149 in central Oklahoma, although the two approaches were developed independently. One
150 advantage of the clustering algorithm used in this study is that it allows for identification
151 of relatively small faults in the neighborhood of large clusters of earthquakes. In addition,

152 I interrogate a three-dimensional (3-D) distribution of earthquake hypocenters to identify
 153 quasi-planar surfaces using a robust statistics algorithm for plane detection in unorganized
 154 point clouds [Araújo and Oliveira, 2020]. To maximize the likelihood of feature detection
 155 in three dimensions, I use the full waveform-relocated catalog [Hauksson et al., 2012] which
 156 has ~ 3 times more events than the focal mechanism catalog [Yang et al., 2012]. Planar
 157 features that were not associated with a sufficient number of clustered hypocenters in
 158 the focal mechanism catalog were excluded from the subsequent analysis. The 3-D plane
 159 detection and the 2-D line clustering methods produced a number of spatially overlapping
 160 features that likely represented the same fault structures. In such cases only one best-
 161 fitting fault segment was retained.

162 Examples of selected event clusters are shown in Figure 2. For each of the linear fits
 163 to the scattered epicenter locations (see red lines and black dots in Figure 2), I estimate
 164 errors in the best-fit strike angle by computing deviation of the least-square linear fits
 165 treating northing and easting coordinates as independent variables [Fialko, 2004]. The
 166 respective errors are shown as red numbers for each cluster (see Figure 2). On average
 167 the estimated uncertainties in fault strikes are on the order of several degrees.

3.2. Analysis of slip direction

168 To determine the sense of slip on the identified fault segments, I use focal mechanisms
 169 of events in the respective clusters. For each event I compute components of the seismic
 170 moment tensor M_{ij} from the magnitude (M_w), strike, dip, and rake angles provided in
 171 the focal mechanism catalog, $M_{ij} = M_0(u_i n_j + u_j n_i)$, where $M_0 = 10^{1.5M_w + 9.1}$ is the
 172 scalar seismic moment in newton meters, n_i is the normal to a slip plane (defined by the
 173 strike and dip angles), and u_i is the unit slip vector (defined by n_i and the rake angle).

174 I then compute a tensorial sum $\Sigma_k M_{ij}$, where k is the number of events in a cluster. To
 175 investigate the effect of diversity of focal mechanisms (e.g., to avoid a possible dominance
 176 of a largest event in a cluster), I also use moment tensors normalized by their scalar
 177 moments, $\bar{M}_{ij} = M_{ij}/\sqrt{M_{mn}M_{mn}/2}$ (repeated indices imply summation). I find that
 178 using original and normalized moment tensors gives rise to essentially the same results.

179 The composite moment tensors may have an appreciable non-double-couple component
 180 if focal mechanisms of events in a cluster are highly diverse. Yet orientations of the P
 181 and T axes (that determine the average sense of slip on a plane defined by a seismicity
 182 lineation) are well resolved. The focal mechanisms shown in Figure 2 represent the best-fit
 183 double couple solutions for composite moment tensors $\Sigma_k \bar{M}_{ij}$. For some event clusters, the
 184 composite focal mechanisms revealed a nearly vertical plunge of the P axis, suggestive of
 185 a predominantly dip-slip motion. The respective clusters were removed from the dataset.
 186 Application of the algorithm described in this Section to the background (prior to July
 187 2019) seismicity data (Figure 1a) resulted in selection of 70 quasi-linear clusters of micro-
 188 earthquakes. The respective clusters are shown in Figure 3, and individually in Figures 2
 189 and S1-S2. The composite focal mechanisms of the identified clusters are predominantly
 190 strike-slip, with approximately north-south P-axis, consistent with results of inversions for
 191 the principle stress and strain rate axes [Yang and Hauksson, 2013; Hauksson and Jones,
 192 2020; Fialko and Jin, 2021].

4. Distribution of dihedral angles

193 Using information from both the fault strike (constrained by seismicity lineations) and
 194 rake (constrained by the composite focal mechanisms) data, one can identify right- and
 195 left-lateral faults in the total fault population without any assumptions about the sense

196 of shear stress resolved on the respective faults due to regional tectonic loading. The
197 observed distribution of orientations of active faults in the Ridgecrest area prior to the
198 2019 earthquake sequence is shown in Figure 4. The two sets of conjugate faults form
199 distinct clusters in a polar histogram (red and blue sectors in Figure 4). Left-lateral faults
200 are well aligned with those ruptured during the July 4 2019 M6.4 foreshock [*Fialko and*
201 *Jin, 2021*]. Right-lateral faults trend somewhat more northerly compared to the main
202 rupture of the July 5 2019 mainshock, but similar to the initial rupture at the hypocenter
203 of the mainshock suggested by the first motion data [*Jin and Fialko, 2020*]. The axis of
204 the principal shortening rate [*Fialko and Jin, 2021*] approximately bisects the dihedral
205 angle formed by the conjugate fault planes (Figure 4). The principal compression axis is
206 oriented similar to the principal shortening rate axis (~ 5 degrees east of north) around
207 the hypocentral area of the M7.1 mainshock [*Hauksson and Jones, 2020; Fialko and Jin,*
208 *2021*].

209 To quantify the range of admissible relative orientations of conjugate faults, I calculate
210 a dihedral angle between every pair of the identified conjugate faults. Figure 5 shows
211 a histogram of dihedral angles 2θ , where θ is an angle between either fault plane and a
212 bisect. Uncertainties in the distribution of dihedral angles of conjugate faults (Figure 5)
213 are estimated using uncertainties in individual fault strikes. Suppose e_i is uncertainty in
214 the slope of a best linear fit for a cluster i , and m is a number of clusters in a given bin j
215 of dihedral angles, $a < 2\theta < b$, where a and b are the minimum and maximum values of
216 samples in a given bin. The standard error of the mean of m angles is $\epsilon_j = s/\sqrt{m}$, where
217 s is the standard deviation of e_1, e_2, \dots, e_m samples [*Hogg et al., 2005*].

218 Uncertainties on a number of conjugate pairs for a given bin of dihedral angles are
 219 estimated assuming a normal distribution of measured values of $2\theta_j$ with known mean
 220 and standard deviation. A probability $p_i(j)$ that a data point θ_i belongs to bin j is:

$$p_i(j) = \int_a^b \frac{1}{\sqrt{2\pi}s_i} \exp\left[-\frac{(\theta_i - z)^2}{2s_i^2}\right] dz. \quad (1)$$

221 The expected value of data points in a bin is given by a sum of the respective probabilities,

$$E_j = \sum_i p_i(j), \quad (2)$$

222 with the Bernoulli variance given by

$$V_j = \sum_i p_i(j)(1 - p_i(j)). \quad (3)$$

223 The standard deviation is the square root of variance [Hogg *et al.*, 2005],

$$s_j = \sqrt{V_j}. \quad (4)$$

224 The ratio of the standard deviation to the expected value, $\rho_j = s_j/E_j$, is a proxy for
 225 a relative error of the “unobserved count” of samples in each data bin. In Figure 5,
 226 uncertainties in the number of dihedral angles per bin are estimated by multiplying the
 227 actual bin counts by the respective values of ρ_j calculated using equations 1, 2, 3, and 4.

228 The distribution of dihedral angles shown in Figure 5 has a peak around 70 degrees,
 229 and lower and upper bounds around 30 and 100 degrees, respectively. Assuming a ho-
 230 mogeneous background stress, some of the conjugate faults are optimally oriented for
 231 failure given the laboratory values of the quasi-static coefficient of friction $\mu \sim 0.6 - 0.8$,
 232 while others are not optimally oriented for any reasonable value of μ . It follows that
 233 the observed fault orientations require some heterogeneity in the effective fault strength,
 234 ambient stress, or both.

5. Role of stress heterogeneity

235 A locally homogeneous background stress is commonly assumed in inversions for the
236 principal stress orientations [*Gephart and Forsyth, 1984; Michael, 1987*]. There is no
237 physically justified length scale behind this assumption as rock volumes thought to satisfy
238 the assumption of stress homogeneity are chosen based on the density of seismic events
239 (number of events per unit volume) [e.g., *Hardebeck and Hauksson, 2001*]. In the presence
240 of multiple faults and fractures, the assumption of a homogeneous stress is likely violated
241 at small scales ranging from micro-asperities on a fault surface to the macroscopic fault
242 roughness, as predicted by numerical models [*Mitchell et al., 2013; Dieterich and Smith,*
243 *2009*] and observed in deep boreholes intersecting natural faults [e.g., *Brudy et al., 1997*].
244 Stresses are also known to vary on spatial scales on the order of hundreds of kilometers,
245 as evidenced by regional inversions of the earthquake focal mechanisms [e.g., *Yang and*
246 *Hauksson, 2013*], presumably indicating transitions between different tectonic domains.
247 Other factors that may affect stress heterogeneity include e.g. 3-D variations in mechanical
248 properties of the host rocks [*Fialko et al., 2002; Barbot et al., 2009*].

249 It is not obvious if the assumption of a constant background stress might be applicable
250 at spatial scales on the order of $10^3 - 10^4$ m [*Iio et al., 2017; Alt and Zoback, 2017*]
251 that are sampled by faults considered in this study (Figures 3, 2, and S1-S2). To check
252 whether results presented in Figures 4 and 5 could be attributed to stress heterogeneity, I
253 perform several tests. In particular, I examine the distribution of angles between synthetic
254 faults (i.e., faults that have the same sense of slip) as a function of distance between the
255 respective faults. If a relatively broad distribution of dihedral angles (Figure 5) results
256 from spatial variations in the orientation of the principal stress axes, strikes of closely

257 spaced faults should be more similar to each other compared to strikes of more distant
258 faults having the same sense of slip. This would be expected e.g. if faults were optimally
259 oriented with respect to a local stress, but not necessarily to a regional stress. The
260 observed distribution of orientations of synthetic faults as a function of distance between
261 the faults is shown in the Supplementary Figure S3. The data indicate that (i) there is a
262 notable diversity in fault orientations at short (< 10 km) distances, (ii) there is little, if
263 any, systematic increase in the diversity of fault orientations with distance, and (iii) fault
264 orientations exhibit coherence at large (> 30 km) distances.

265 Previous studies suggested a local rotation of the principal stress axes around the Coso
266 region (northings $N > 40$ km in a local coordinate system used in Figure 3) [*Hauksson*
267 *and Jones, 2020*]. To investigate the respective possibility, I divided the data into the
268 northern ($N > 40$ km) and southern ($N < 40$ km) sub-sets, and repeated the analysis for
269 each sub-set. Figures S4-S5 show variability in fault strikes vs distance between pairs of
270 synthetic faults, and Figures S6-S7 show the distribution of fault strikes. The northern
271 sub-set shows some correlation between the diversity of fault strikes and distance between
272 synthetic faults, suggesting a possible effect of stress heterogeneity (Figure S4). In part
273 such heterogeneity could be attributed to a long-term fluid pumping at the Coso geother-
274 mal plant [*Fialko and Simons, 2000; Tymofyeyeva and Fialko, 2015*]. Also, conjugate
275 faults in the northern sub-set exhibit smaller dihedral angles that are closer to optimal
276 orientations compared to faults in the southern sub-set (cf. Figures S6 and S7). However,
277 the mean of the left- and right-lateral fault strikes (i.e., the bisect) is not resolvably differ-
278 ent between the northern and southern sub-sets, suggesting that a constant regional stress
279 is a viable first-order approximation. The spatial resolution of stress inversions depends

280 on the distribution of seismicity; in areas with enough data (including the epicentral area
281 of the 2019 Ridgecrest earthquakes) the observed variations in the orientation of the prin-
282 cipal stress axes are smaller than 10-20 degrees [*Fialko and Jin, 2021*, see their figure 2],
283 insufficient to explain the observed distribution of dihedral angles (Figure 5) in terms of
284 regional variations in the stress field.

285 Given that the background tectonic loading is relatively uniform [*Floyd et al., 2020*;
286 *Fialko and Jin, 2021*], most of the local stress heterogeneity in the upper crust is likely
287 associated with brittle failure. To quantify effects of stress heterogeneity due to a complex
288 network of randomly oriented faults, I performed numerical simulations in which I varied
289 the fault distribution, the ambient stress, and the effective fault strength.

5.1. Rotation of the principal stress axes due to a complex system of interacting faults

290 Slip on faults ultimately reduces stress imposed by tectonic loading, but also results in a
291 re-distribution of stress within the brittle crust, with largest stress perturbations typically
292 concentrated around the fault edges [e.g., *Martel and Pollard, 1989*]. To quantify the
293 effects of stress heterogeneity (specifically, the amount of rotation of the principle stress
294 axes) due to a complex fault system, I simulate a network of randomly oriented two-
295 dimensional (plane strain) faults subject to a prescribed remotely applied stress (Figure 6).
296 Each fault is approximated by a linear array of dislocations. The boundary condition on
297 each dislocation is $\tau \leq \mu\sigma'_n$, where τ and σ'_n are respectively the shear and the effective
298 normal stress (normal stress minus the pore fluid pressure) resolved on a dislocation plane,
299 and μ is the local coefficient of friction. Both τ and σ'_n are total stresses that result from
300 the remotely applied stress as well as slip on faults in response to the remotely applied

301 stress. The boundary condition ensures that each fault locally does not violate the Mohr-
302 Coulomb failure criterion. Numerical simulations are performed using a boundary element
303 code TwoDD modified to handle non-linear stress-controlled boundary conditions [*Crouch*
304 *and Starfield, 1983; Fialko and Rubin, 1997*]. Fault lengths randomly vary in the interval
305 1-11 km, chosen to approximate the observed distribution of active faults in the Ridgecrest
306 area (Figures 1a and 3). Figure 6 shows an example of a modeled fault distribution. The
307 remotely applied stress has eigenvectors $\sigma_{E,N}$ aligned with the coordinate axes, “east” (E)
308 and “north” (N), such that $\sigma_E = -40$ MPa, and $\sigma_N = -160$ MPa, similar to the background
309 stress inferred from the observed fault orientations in Ridgecrest (see Discussion section).
310 The maximum compressive stress σ_N is somewhat increased compared to an equilibrium
311 principal stress at which the optimally oriented faults are on the verge of failure, to allow
312 for finite slip on the modeled faults.

313 Two sets of simulations were performed for each random realization of the fault system,
314 one assuming a constant coefficient of friction ($\mu = 0.6$, Figure 6a,c), and another assuming
315 a variable coefficient of friction ($0.3 < \mu < 0.6$, Figure 6b,d). The top panels in Figure
316 6 show the slip magnitude and the bottom panels show the orientation of the principal
317 compression axis (tick marks) and its rotation due to slip on faults (color). The modeled
318 faults essentially approximate shear cracks with a constant stress drop. In case of spatially
319 constant friction, only the faults that happened to be nearly optimally oriented for failure
320 become activated by the applied remote stress field, as expected (Figure 6a). In case of
321 variable friction, a more diverse population of faults is brought to failure (Figure 6b).
322 For the same remote stress, reductions in μ give rise to larger static stress drops and slip
323 magnitudes on pre-existing faults. Faults with a constant stress drop produce a weak stress

324 singularity at the fault tips [e.g., *Pollard and Segall*, 1987; *Fialko*, 2015]. Despite such a
325 singularity, only limited rotation of the principal stress axis is observed in the surrounding
326 medium. In case of constant friction, the stress rotation is essentially negligible (Figure
327 6c). In case of heterogeneous friction, the stress rotation on average does not exceed
328 ~ 10 degrees, and is limited to relatively small areas around the fault tips (Figure 6d).
329 Increases in the magnitude of the remotely applied deviatoric and mean stresses result in
330 stress rotations that are smaller still, as the ratio of stress perturbations due to fault slip
331 to the absolute background stress decreases.

332 Results presented above suggest that the observed distribution of orientations of active
333 faults in the Ridgecrest area (Figures 1a, 3, and 5) is unlikely explained in terms of spatial
334 heterogeneity of stresses acting in the seismogenic zone.

6. Role of strength heterogeneity

335 It may be argued that small earthquakes that comprise quasi-linear clusters (Figures 1a,
336 2, 3, and S1-S2) are primarily governed by the rate and state friction [*Dieterich*, 2015] and
337 are not subject to strong dynamic weakening, so that the peak yield stress is comparable
338 to the background stress [*Fialko*, 2015]. In this case, one can interpret the observed range
339 of fault orientations (Figure 5) in terms of activation ($\theta > \theta_1$) and de-activation ($\theta > \theta_2$) of
340 pre-existing or newly created faults. It is generally recognized that the continental Earth's
341 crust is pervasively faulted and contains cracks, fractures and other structural defects that
342 can serve as potential slip surfaces over a broad range of sizes and orientations [*Sykes*,
343 1978; *Sibson*, 1990].

6.1. Slip on immature sub-optimally oriented faults: Theory

Given a stress field with axes of the effective principal stresses σ'_1 and σ'_3 parallel to the Earth's surface, a condition for activation of pre-existing strike-slip faults is [Sibson, 1985, 1990]:

$$R = \frac{\sigma'_1}{\sigma'_3} = \frac{1 + \mu \cot \theta}{1 - \mu \tan \theta}, \quad (5)$$

where R is the effective stress ratio, σ'_1 is the effective maximum compressive stress (maximum compressive stress minus the pore pressure P), σ'_3 is the effective minimum compressive stress, μ is the coefficient of friction, and θ is the angle between a fault plane and the maximum compression axis. Equation 5 assumes the Mohr-Coulomb failure criterion, vertical orientation of the intermediate principal stress, and negligible (compared to friction) cohesion on a potential slip plane.

Equation 5 is typically under-determined as the number of unknowns (e.g., σ'_1 , σ'_3 and μ) is greater than the number of observables (such as angles between conjugate faults or between faults and the principal stress axes). In case of the Ridgecrest seismicity, several unique conditions may allow one to resolve this uncertainty. First, a transtensional stress regime manifested by a mix of strike-slip and normal focal mechanisms [Hauksson and Jones, 2020], including spatially overlapping strike-slip and normal earthquake ruptures [Jin and Fialko, 2020] indicates that the maximum compressive (σ'_1) and intermediate (σ'_2) principle stresses are essentially of the same magnitude. In this case, both should approximately equal the effective lithostatic stress, $\rho_c g z - P$, where ρ_c is the average density of the upper crust, g is the gravitational acceleration, and z is depth. Second, assuming that the lower and upper bounds of the observed distribution of dihedral angles (Figure 5) correspond to activation (θ_1) and de-activation (θ_2) of pre-existing faults, one

365 can estimate a possible range of variations in the coefficient of friction on activated faults,
 366 $\mu_1 < \mu < \mu_0$. The lower bound on μ is given by

$$\mu_1 = \frac{1}{\tan(\theta_1 + \theta_2)}. \quad (6)$$

367 The minimum failure envelope $\tau = \mu_1 \sigma'_n$, where σ'_n and τ are respectively the effective nor-
 368 mal and shear stresses resolved on a fault, intersects the Mohr circle [*Twiss and Moores*,
 369 1992, p. 141] at points corresponding to fault orientations $2\theta_1$ and $2\theta_2$. A fault orien-
 370 tation that maximizes an excursion beyond the minimum failure envelope is given by an
 371 average of the activation and de-activation angles θ_1 and θ_2 . Substituting equation 6 into
 372 equation 5, and taking θ to be equal to either θ_1 or θ_2 , one obtains expressions for the
 373 critical stress ratio R^* and the effective minimum compressive stress σ'_3 :

$$R^* = \frac{1 + \mu_1 \cot \theta_1}{1 - \mu_1 \tan \theta_1} = \frac{1 + \mu_1 \cot \theta_2}{1 - \mu_1 \tan \theta_2}, \quad (7)$$

$$\sigma'_3 = \sigma'_1 / R^*. \quad (8)$$

375 The coefficient of friction μ_1 provides a lower bound on the frictional strength of activated
 376 sub-optimally oriented faults. Faults that are oriented at more acute angles with respect to
 377 the principal compression axis can be on the verge of failure if they have a higher coefficient
 378 of friction, with an upper bound μ_0 that corresponds to an optimal fault orientation. The
 379 upper bound on μ can be found from the following relationship between the stress ratio
 380 R and the coefficient of friction that corresponds to an optimal orientation [*Sibson*, 1985]:

$$R = \left(\sqrt{1 + \mu_0^2} + \mu_0 \right)^2. \quad (9)$$

381 Solving for real non-negative values of μ_0 gives rise to

$$\mu_0 = \frac{R - 1}{2\sqrt{R}}. \quad (10)$$

382 Figure 7 shows a Mohr circle diagram for the state of stress that satisfies the above
383 constraints as well as the assumption of a hydrostatic pore pressure [*Townend and Zoback,*
384 2000] ($P = \rho_w g z$, where ρ_w is the density of water), at a reference depth of 7 km. The latter
385 is within the estimated range of the hypocentral depth of the M7.1 Ridgecrest earthquake
386 (3-8 km) [*Hauksson and Jones, 2020*]. It also approximately corresponds to the middle of
387 the seismogenic layer, so that the absolute stresses shown in Figure 7 represent stresses
388 averaged over the thickness of the seismogenic layer. As one can see from Figure 7, the
389 estimated stress ratio is $R^* \approx 3$, the depth-averaged shear stresses resolved on seismically
390 active faults are 25-40 MPa, and the inferred range of in situ coefficient of friction is
391 $0.4 < \mu < 0.6$.

7. Discussion

392 High-end values of the estimated coefficient of friction are in agreement with labora-
393 tory measurements of quasi-static friction of most rock types [*Byerlee, 1978*], and may
394 correspond to the formation of new faults or activation of pre-existing suitably oriented
395 faults in the ECSZ (Figure 7). The value of $\mu \sim 0.6$ is also consistent with models sug-
396 gesting that faults ruptured in the 2019 sequence were initiated at or near to an optimal
397 orientation of $\sim 30^\circ$ with respect to the principal compression axis at the inception of
398 the ECSZ, and subsequently rotated to their current (sub-optimal) orientations [*Fialko*
399 *and Jin, 2021*]. The model of *Fialko and Jin* [2021] implies that the newly formed or
400 activated faults progressively weakened as they continued to accumulate slip and rotate
401 away from their optimal orientation due to the long-term tectonic motion. *Hauksson and*
402 *Jones* [2020] proposed that the orientation of the 2019 earthquake ruptures with respect
403 to the present-day principal compression axis might be explained assuming higher values

404 of the stress ratio ($R > 5$) and the coefficient of friction ($\mu = 0.75$). Such high values
405 however appear to be inconsistent with the observed transtensional stress regime in the
406 Ridgecrest-Coso area, and would require pore fluid pressures close to the least compressive
407 stress. Also, a high coefficient of friction would imply a peak in dihedral angles of the
408 regional fault population around the respective optimal value (~ 55 degrees for $\mu = 0.75$)
409 which is not observed (Figure 5). Note that orientations of the 2019 ruptures (Figures 1b
410 and 4) are within the documented range of a regional data set (Figure 5), so that results
411 presented in this study apply to the observed geometry of the 2019 earthquakes.

412 The inferred value of μ_0 (Figure 7) is also in agreement with observations of injection-
413 induced seismicity in the central US that reveal ubiquitous dihedral angles of $\sim 60^\circ$
414 [*Schoenball and Ellsworth, 2017; Alt and Zoback, 2017; Skoumal et al., 2019*]. Such obser-
415 vations are consistent with the idea that stable continental interiors can support stresses
416 on the order of hundreds of megapascals predicted by the strong fault theory. A relatively
417 broad distribution of dihedral angles in the Ridgecrest area with a peak around $\sim 70-75^\circ$
418 (Figure 5) is however markedly different from a highly clustered distribution observed in
419 the central US [*Schoenball and Ellsworth, 2017; Skoumal et al., 2019*], suggesting differ-
420 ences in the stress regime and the effective strength of the bulk of the seismogenic crust.
421 In part such differences could be attributed to different tectonic settings and loading con-
422 ditions. Specifically, seismicity in the central US exemplifies a stable continental interior
423 responding to the anthropogenically induced increases in pore fluid pressure [e.g., *Wein-*
424 *garten et al., 2015*]. In contrast, seismicity in the Ridgecrest area (Figure 1) is associated
425 with a nascent plate boundary responding to increases in tectonic strain [*Nur et al., 1993;*
426 *Fialko and Jin, 2021*]. The “developing plate boundary” environment is arguably more

427 relevant for investigating the evolution of fault strength as a function of fault maturity,
428 and may provide useful insights into a poorly understood transition from “strong” to
429 “weak” faults.

430 The low-end values of the estimated range of the coefficient of friction (μ_1 , see equa-
431 tion 6 and Figures 5 and 7) provide some quantitative measure of the degree of weakening
432 associated with fault evolution as a function of tectonic strain. The average shear strain ε
433 accommodated by the ECSZ since its inception 6-10 Ma is on the order of 10-20% [*Fialko*
434 *and Jin*, 2021]. In a continuum representation of brittle failure such as “seismic flow”
435 of rocks [*Riznichenko*, 1965], one can define an average rate of tectonic strain softening,
436 $\partial\mu/\partial\varepsilon$. Taking $\partial\mu \approx \mu_0 - \mu_1$, $\partial\mu/\partial\varepsilon$ is estimated to be on the order of unity. A moderate
437 reduction in the coefficient of friction suggested by the analysis of fault orientations (Fig-
438 ures 4, 5 and 7) may be indicative of an onset of various weakening mechanisms with an
439 increasing cumulative fault slip, such as mineral alteration, ultra-comminution, pressur-
440 ization of fault zone fluids, etc. [e.g., *Imber et al.*, 1997; *Reches and Lockner*, 2010; *Lacroix*
441 *et al.*, 2015]. Largest faults in the system might also experience dynamic weakening [*Jin*
442 *and Fialko*, 2020].

443 Note that some variability in the coefficient of friction that could contribute to the
444 observed diversity of fault orientations (Figures 3 and 5) is naturally expected due to
445 dependence of friction on composition, normal stress, temperature, and other environ-
446 mental variables [*Stesky et al.*, 1974; *Byerlee*, 1978; *Mitchell et al.*, 2013, 2015, 2016]. A
447 key distinction with the “cumulative slip-weakening” model is that the latter predicts a
448 systematic dependence of the effective fault strength on fault maturity. In particular,
449 faults in the ECSZ that are currently less optimally oriented for slip were likely acti-

450 vated before faults that are currently well oriented with respect to the present-day stress
451 field. While it may be difficult to determine the fault age or a cumulative offset, espe-
452 cially for small faults that are only expressed in micro-seismicity and don't yet have a
453 surface expression (Figure 1a), we note that faults that produced the 2019 sequence are
454 on the "long/less well-oriented" end of the distribution of active faults in the study area
455 (Figures 1b and 5), consistent with a notion that for developing faults, the fault length
456 correlates with the fault age [e.g., *Cowie and Scholz*, 1992].

457 Estimates of deviatoric stress based on the Mohr-Coulomb theory are upper bounds in
458 that they define the maximum shear stress the upper crust can support before new faults
459 are formed. In the presence of mature well-slipped faults, the average shear stress resolved
460 on the respective faults can be well below the static Mohr-Coulomb failure envelope due to
461 the effects of dynamic rupture [e.g., *Noda et al.*, 2009; *Thomas et al.*, 2014; *Fialko*, 2015].
462 The long-term reduction in strength depends on the magnitude of stress concentration
463 ahead of the rupture front, and dynamic weakening behind the rupture front during
464 individual seismic events [*Kirkpatrick and Shipton*, 2009; *Di Toro et al.*, 2011; *Rubino*
465 *et al.*, 2017]. Both factors are expected to scale with the rupture size. Over geologic time,
466 mature faults localize tectonic strain and may not be oriented with respect to the principal
467 stress axes in any predictable fashion, other than the sense of shear stress resolved on a
468 fault should be the same as the sense of fault slip.

469 The method proposed in this study relies on relative orientations of small developing
470 immature faults distributed throughout the seismogenic layer, so that the effects of stress
471 concentration and dynamic weakening, if any, should be minimal. It should be mentioned
472 that dihedral angles between conjugate faults are uniquely related to the coefficient of

473 friction only in case of newly formed faults; a re-activation of pre-existing faults depends
474 on other factors that affect the effective fault strength, such as e.g. the pore fluid pressure.
475 The lower bound on the coefficient of friction μ_1 (Figures 5 and 7) should therefore be
476 considered an effective residual friction that accounts for all relevant weakening mecha-
477 nisms. Estimation of the magnitude of deviatoric stress further requires special conditions
478 such as a 2-D state of stress (equal magnitudes of two of the principal stress components).

479 The above conditions appear to be met in the area around Ridgecrest (Figures 1 and 3),
480 allowing a unique estimate of the magnitude of absolute stresses in the seismogenic crust.
481 The depth-averaged shear stress S is on the order of a few tens of megapascals (see
482 Figure 7). This is well below the values of shear stress measured in deep boreholes
483 and suggested by seismic observations in the stable continental crust [e.g., *Brudy et al.*,
484 1997; *Townend and Zoback*, 2000; *Schoenball and Ellsworth*, 2017], but similar to values
485 suggested for the San Andreas Fault (SAF) based on the borehole measurements [*Lockner*
486 *et al.*, 2011] and independent constraints such as the heat flow data [*Lachenbruch and Sass*,
487 1980] and stress perturbations due to topography [*Fialko et al.*, 2005]. Despite similar
488 values of the driving shear stress, active faults in the Ridgecrest area may be considered
489 to be relatively strong compared to the SAF because of the transtensional stress regime in
490 the ECSZ versus transpressional regime on the SAF. The magnitude of deviatoric stress
491 in the study area thus falls in between predictions of the strong and weak fault theories.

8. Conclusions

492 Precisely determined relative locations of small and intermediate size earthquakes often
493 reveal lineated structures likely illuminating active faults at depth. Quasi-linear clusters
494 of earthquakes can be used to constrain fault orientations (e.g., strike and dip angles),

495 which, in combination with information provided by the composite focal mechanisms,
496 may allow one to quantify relative orientations of active conjugate faults. Dihedral an-
497 gles formed by the conjugate fault planes carry information about the heterogeneity in
498 the ambient stress field and the fault strength, as well as the orientation and (under
499 certain conditions) the magnitude of the principal stresses. I demonstrate the proposed
500 method using data from the Eastern California Shear Zone near the town of Ridgecrest
501 that hosted a series of strong earthquakes in July of 2019. The data analysis indicates
502 that the attitudes of small- to medium-sized faults (that sample in situ stresses on spatial
503 wavelengths on the order of kilometers) are essentially the same as those of the M6-M7
504 earthquakes of the 2019 Ridgecrest sequence that ruptured the entire seismogenic layer
505 (thereby sampling stresses on spatial wavelengths on the order of tens of kilometers). I
506 use statistics of dihedral angles between active faults expressed in the background (prior
507 to July 2019) seismicity to estimate the effective fault strength and the absolute shear
508 stress acting at seismogenic depths. The inferred range of the coefficient of friction is
509 $0.4 < \mu < 0.6$, and the depth-average shear stress is 25-40 MPa. A possible interpreta-
510 tion of the observed distribution of dihedral angles is that the new faults are formed (or
511 existing faults are activated) at optimal angles with respect to the maximum compression
512 axis, and are progressively weakened as they continue to accumulate slip and rotate away
513 from the optimal orientation due to a long-term tectonic motion. Results presented in
514 this study suggest that a transition from “strong” to “weak” faults may initiate at the
515 early stages of formation of a plate boundary, and involve relatively low total offsets. The
516 proposed method can be used to assess the magnitude of deviatoric stress acting at seis-
517 mogenic depths in other actively deforming areas expressed in abundant microseismicity,

518 but lacking well-developed mature faults. Quasi-linear clusters of earthquakes and their
519 composite focal mechanisms can also be used to improve robustness of inversions for the
520 orientation of the principal stress axes.

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Data Availability Statement

524 The data that support the findings of this study are openly available in the South-
525 ern California Earthquake Data Center (SCEDC) repository (doi: 10.7909/C3WD3xH1)
526 at <https://scedc.caltech.edu/data/alt-2011-yang-hauksson-shearer.html> and
527 <https://scedc.caltech.edu/data/alt-2011-dd-hauksson-yang-shearer.html>. Data
528 are available through Yang *et al.* [2012] and Hauksson *et al.* [2012].

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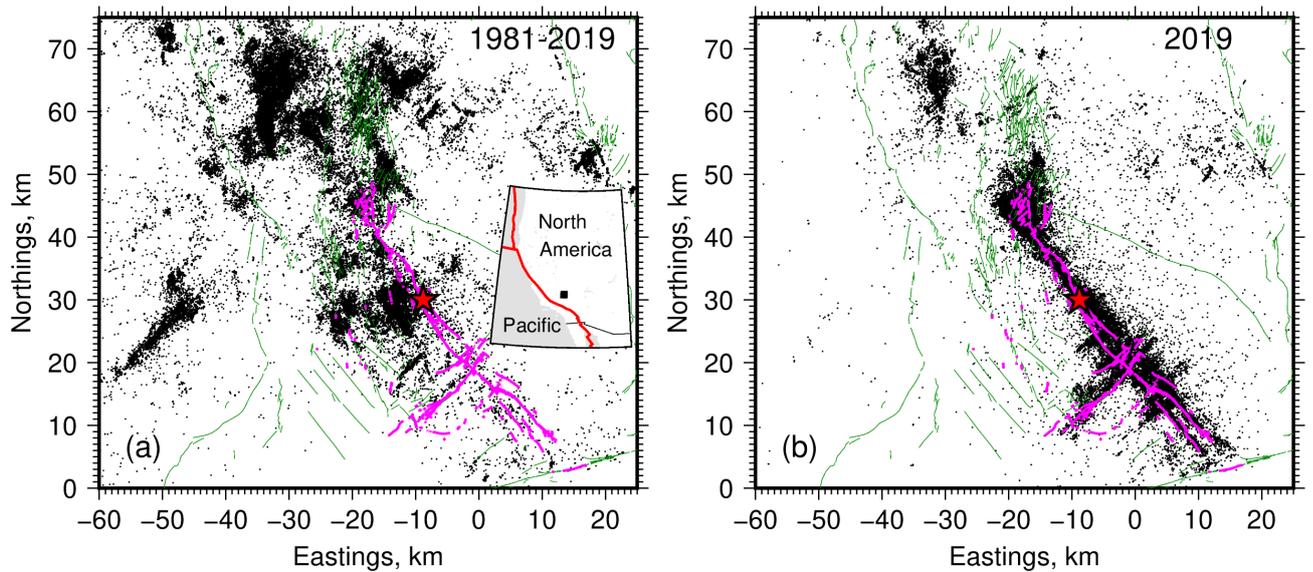


Figure 1. (a) Precisely relocated seismicity in the Ridgecrest-Coso area over a time period 1981-July 2019 [Hauksson *et al.*, 2012]. Thin green lines denote Quaternary faults [Jennings and Bryant, 2010]. Magenta lines denote surface traces of the 2019 ruptures [DuRoss *et al.*, 2020]. Red star denotes the epicenter of the 2019 M7.1 earthquake. Inset shows the location of the study area. (b) Precisely relocated seismicity over 6 months following the July 2019 M7.1 event [Ross *et al.*, 2019]. Local origin is at 117.5°W , 35.5°N .

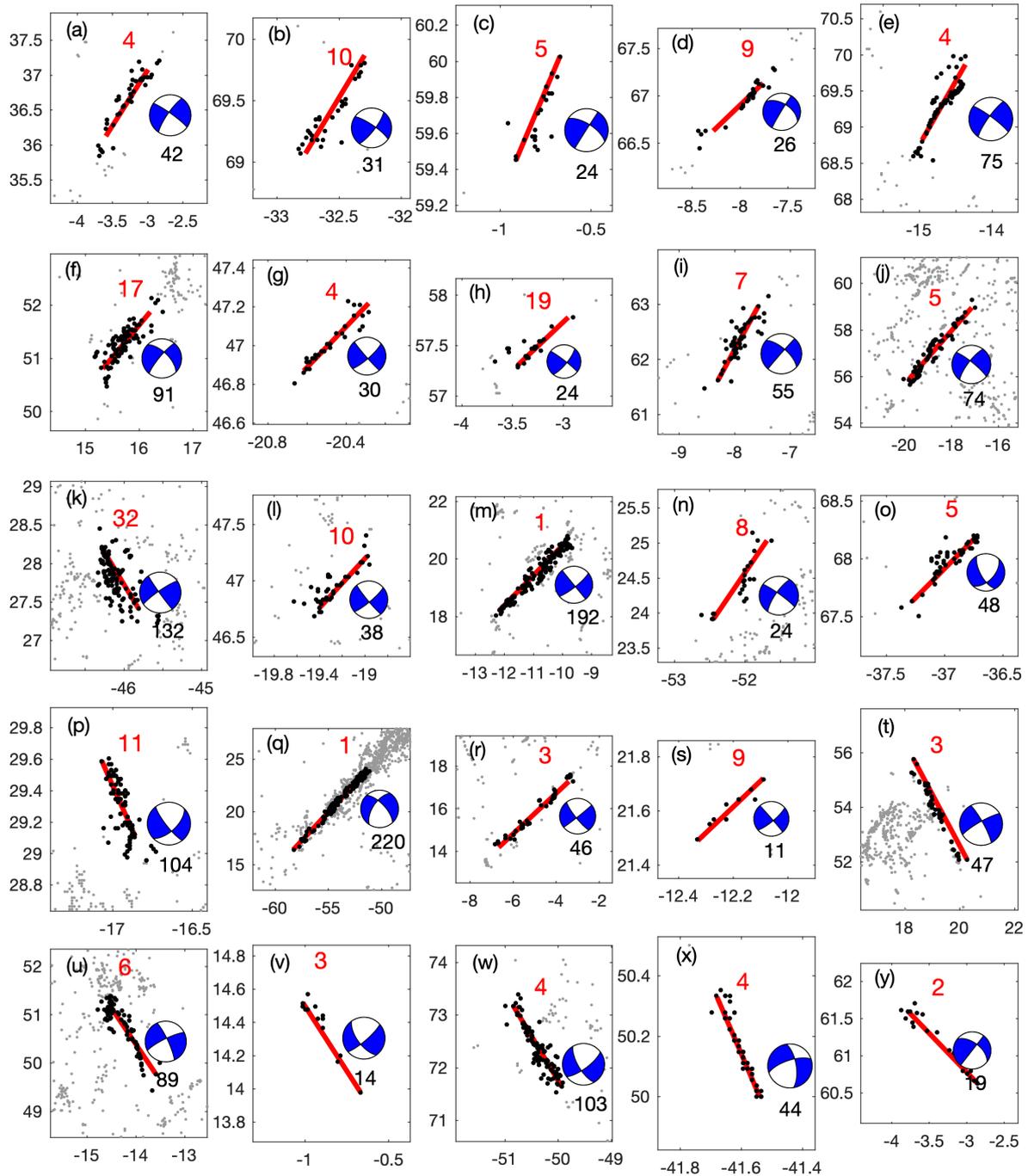


Figure 2. Seismicity lineations identified by the clustering algorithm. Grey dots denote the background seismicity, black dots denote events included in a cluster. The local UTM coordinate system is the same as in Figure 1. Red lines denote the best linear fits. White and blue “beach balls” denote the composite focal mechanisms for the respective clusters. Black numerical labels below the beach balls indicate the number of events in a cluster. Red numerical labels above the beach balls indicate uncertainty in the estimated strike angle, in degrees.

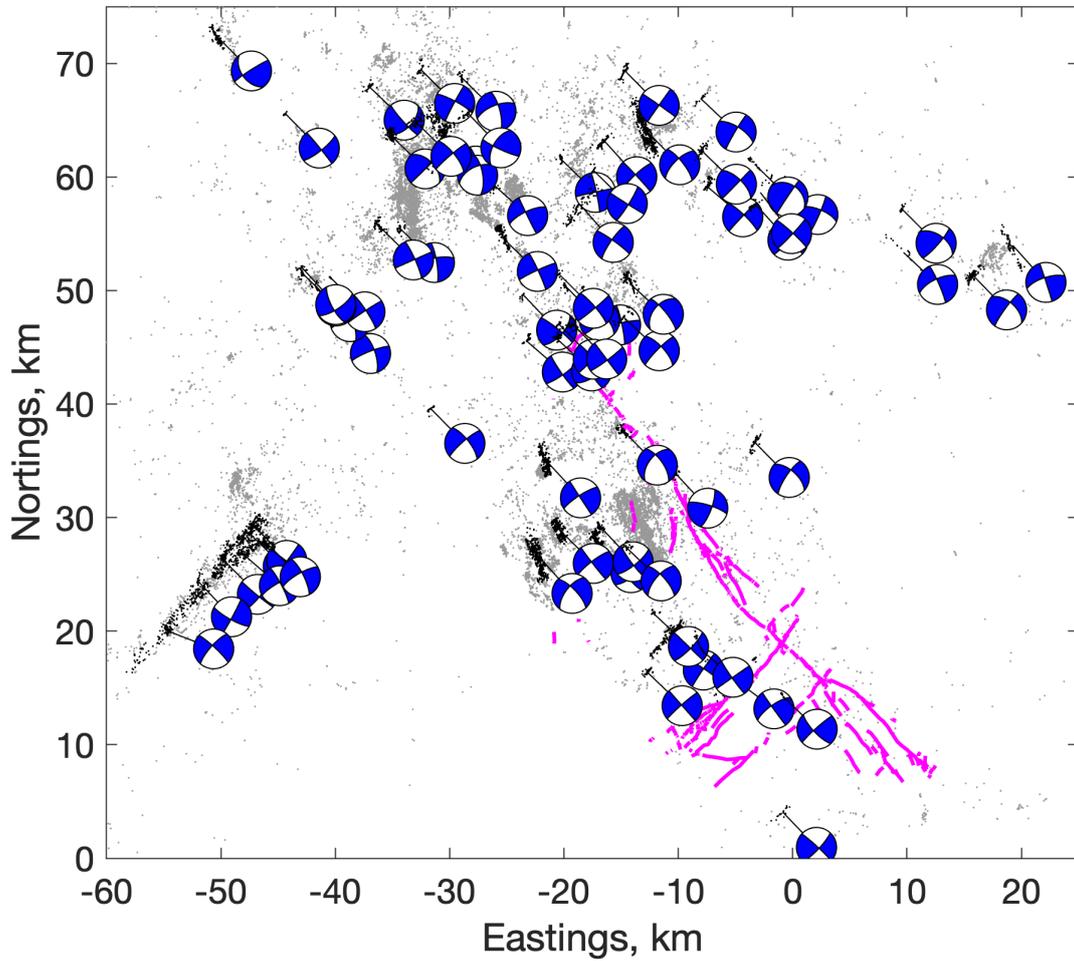


Figure 3. Map of the Ridgecrest-Coso area. Magenta wavy lines denote surface traces of the 2019 ruptures mapped by field surveys [DuRoss *et al.*, 2020]. Grey dots denote pre-earthquake (1981-2019) seismicity from the focal mechanism catalog [Yang *et al.*, 2012]. Black dots denote seismicity lineations selected by the clustering algorithm (see Supplementary Materials and Figures S2-S4 for details). White and blue “beach balls” denote the best-fitting double-couple composite focal mechanism for the respective linear clusters of earthquakes. Coordinates the same as in Figure 1.

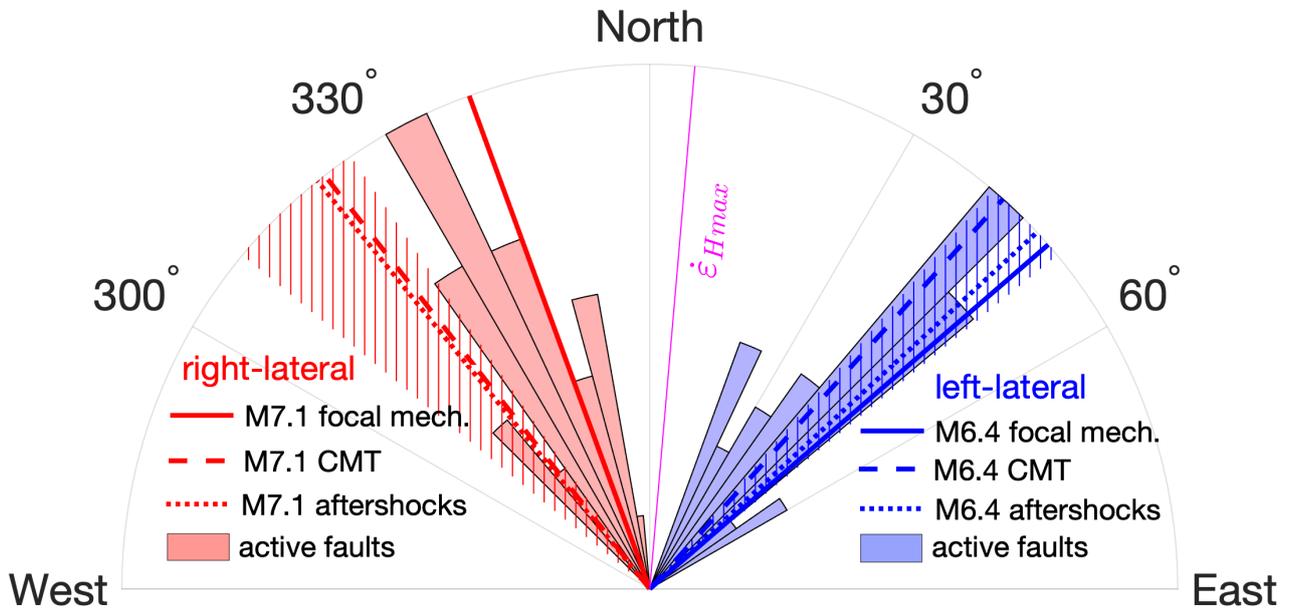


Figure 4. A distribution of strikes of 70 active fault segments shown in Figure 3. Red histogram corresponds to right-lateral faults (total of 30 samples, maximum number of samples per bin: 7), and blue histogram corresponds to left-lateral faults (total of 40 samples, maximum number of samples per bin: 10). Hatched areas denote orientation of faults ruptured by the M6.4 foreshock and M7.1 mainshock of the 2019 sequence [Jin and Fialko, 2020; Fialko and Jin, 2021]. Thin magenta line denotes the principal shortening rate axis derived from geodetic data [Fialko and Jin, 2021].

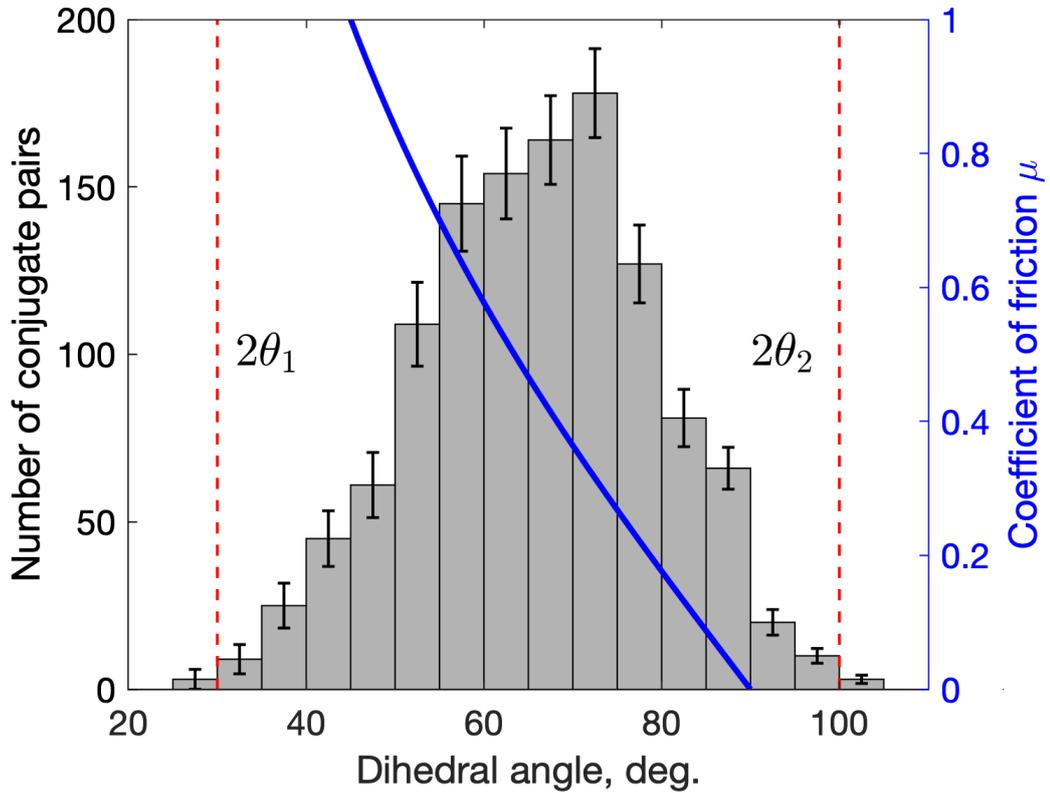


Figure 5. A histogram of dihedral angles between the conjugate strike-slip faults identified in Figure 3. Red vertical lines denote the lower ($2\theta_1$) and upper ($2\theta_2$) bounds on the observed distribution. Blue line (right axis) denotes the coefficient of friction corresponding to conjugate faults that are optimally oriented for failure according to the Mohr-Coulomb criterion, $\mu = 1/\tan(2\theta)$ [Sibson, 1990].

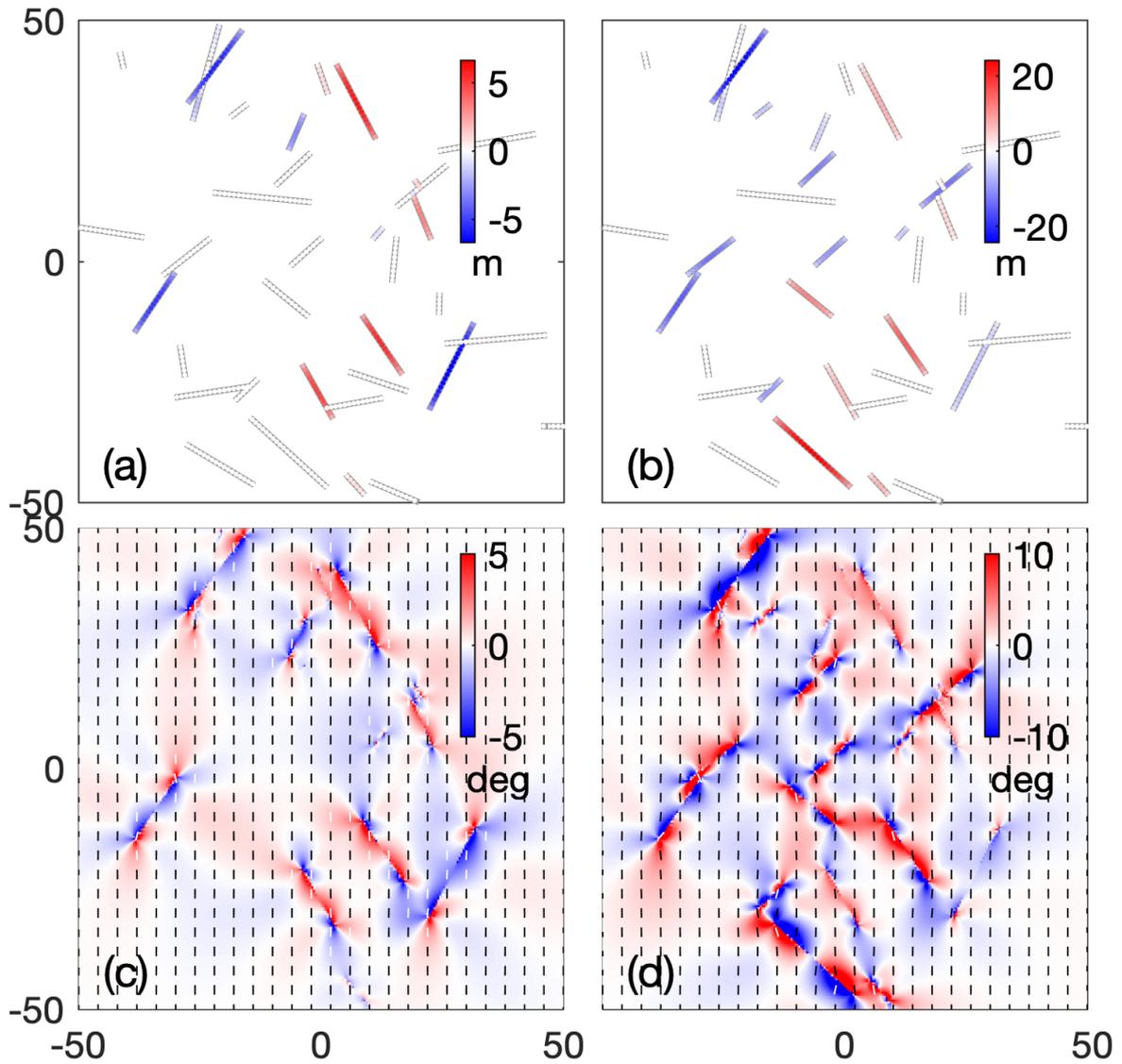


Figure 6. Numerical simulations of a system of randomly oriented faults activated by the applied remote stress field. (a,c) Geometry of the fault network. Color denotes the slip magnitude. Right-lateral slip is positive and left-lateral slip is negative. (b,d) Orientation of the maximum compression axis (tickmarks) and rotation caused by fault slip (color). Counterclockwise rotation is deemed positive. (a,c) Constant coefficient of friction, $\mu = 0.6$. (b,d) Variable coefficient of friction, $0.3 < \mu < 0.6$. Calculations assume the Young's modulus of 50 GPa, and the Poisson ratio of 0.25. Coordinate axes are in km.

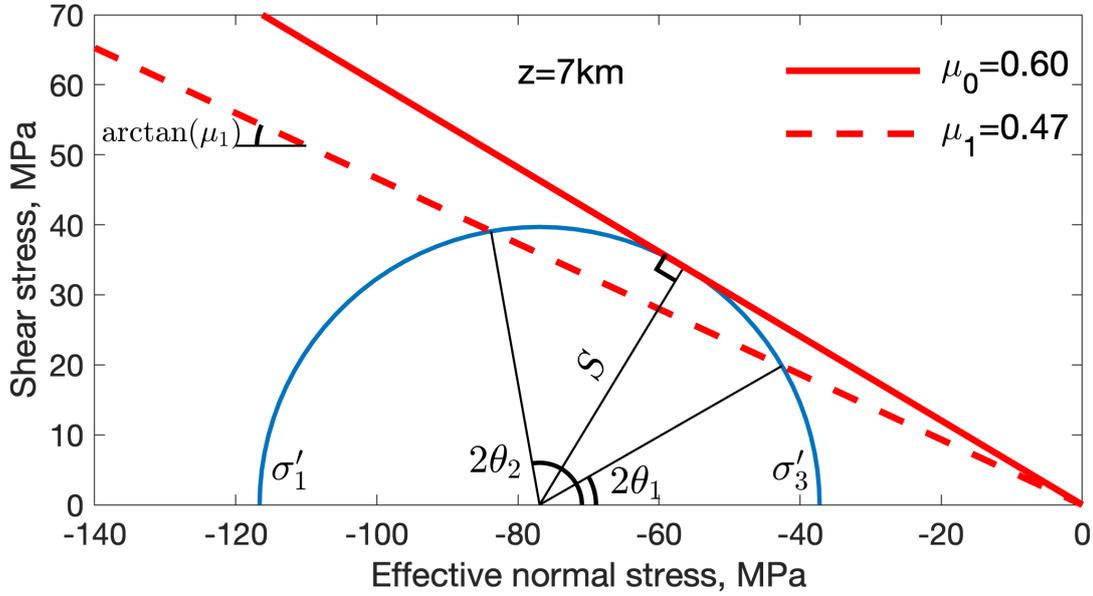


Figure 7. The estimated state of stress in the hypocentral region of the 2019 Ridgecrest earthquakes. Blue curve (the Mohr circle) denotes variations in shear stress on potential slip planes as a function of a dihedral angle 2θ between conjugate slip planes (or angle θ between a slip plane and the maximum compression axis). Radius of the Mohr circle represents the maximum shear stress, $S = |\sigma'_1 - \sigma'_3|/2$. Red lines are the Mohr-Coulomb failure envelopes corresponding to activation of pre-existing faults (μ_1 , dashed line), and generation of new faults (μ_0 , solid line). Calculations assume $\rho_c = 2.7 \times 10^3 \text{ kg/m}^3$, $\rho_w = 10^3 \text{ kg/m}^3$, and $g = 9.8 \text{ m/s}^2$.