

Local Mapping of Polar Ionospheric Electrodynamics

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Key Points:

- We present a technique to use disparate data types to produce local maps of polar ionospheric electrodynamics
- $\Delta\mathbf{B}$ and convection measurements are related via ionospheric Ohm's law and spherical elementary current systems
- We demonstrate the technique on real and synthetic data, and discuss limitations and future development

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Abstract

An accurate description of the state of the ionosphere is crucial for understanding the physics of Earth’s coupling to space, including many potentially hazardous space weather phenomena. To support this effort, ground networks of magnetometer stations, optical instruments, and radars have been deployed. However, the spatial coverage of such networks is naturally restricted by the distribution of land mass and access to necessary infrastructure. We present a new technique for local mapping of polar ionospheric electrodynamics, for use in regions with high data density, such as Fennoscandia and North America. The technique is based on spherical elementary current systems (SECS), which were originally developed to map ionospheric currents. We expand their use by linking magnetic field perturbations in space and on ground, convection measurements from space and ground, and conductance measurements, via the ionospheric Ohm’s law. The result is a technique that is similar to the Assimilative Mapping of Ionospheric Electrodynamics (AMIE) technique, but tailored for regional analyses of arbitrary spatial extent and resolution. We demonstrate our technique on synthetic data, and with real data from three different regions. We also discuss limitations of the technique, and potential areas for improvement.

Plain Language Summary

The ionosphere, where a small but significant fraction of the atmosphere is ionized, forms the edge of space. At only 100 km altitude, it is the region in space which is by far best monitored by human instruments. Space scientists routinely use measurements that inform about specific aspects of the dynamics in the ionosphere, but not the whole picture. For example, magnetometers on ground measure one part of the electric current system while magnetometers on satellites measure another part. Radars measure the flow of charged particles in the ionosphere, while optical images and particle measurements can be used to estimate electric conductivity. In this paper, we present a technique that combines all these different types of measurements to give a complete picture of what takes place in the ionosphere. The technique is tailored for use in regions where the data density is high, and the spatial resolution and extent of the analysis region are flexible.

1 Introduction

Polar ionospheric electrodynamics can be thought of as a focused image of what takes place much further away from the Earth, in the magnetosphere. However, this is overly simplistic since the ionosphere also resists and reacts to this forcing via collisions with neutrals. The tug-of-war between magnetospheric driving and ion-neutral collisions leads to complex patterns of magnetic field disturbance and electric currents, whose relation to the imposed plasma flow may be counter-intuitive and difficult to untangle. Nevertheless, measurements are much more abundant near the ionosphere than higher up, and therefore offer an invaluable source of information for understanding the coupling between the Earth and the solar wind. Ground magnetometer measurements have been used to chart ionospheric currents for more than a century (Birkeland, 1901; Vestine et al., 1947), and space magnetometers have been used since the early space age (Iijima & Potemra, 1978); and both have provided fundamental knowledge about how the Earth and Sun are coupled. In the last decades, satellite (Heppner & Maynard, 1987) and radar (Ruohoniemi & Baker, 1998) measurements have given us maps of ionospheric convection that reveal the Sun-Earth coupling in even greater detail.

Several statistical studies and empirical models exist that describe how ionospheric convection (or electric fields) (Weimer, 2005; Förster & Haaland, 2015; Pettigrew et al., 2010) and magnetic field perturbations (or currents) (Laundal et al., 2018; Weimer, 2013; Edwards et al., 2020) vary as a function of seasons and solar wind conditions. These sta-

64 tistical models are useful for helping us understand the coupling between the solar wind
 65 and geospace in steady state, but they almost never capture the dynamics of this cou-
 66 pling. Maps based on global networks of measurements offer a much better alternative
 67 for studies of ionospheric dynamics. For example, the SuperMAG network of magnetome-
 68 ters (Gjerloev, 2012) has been used to derive global maps of ground magnetic field per-
 69 turbations at 1 min time resolution (Waters et al., 2015); the network of SuperDARN
 70 radars have been used to derive global maps of ionospheric convection, also at 1-min time
 71 resolution (Ruohoniemi & Baker, 1998; Gjerloev et al., 2018); and the fleet of Iridium
 72 satellites carry magnetometers that are used to derive global maps of field-aligned cur-
 73 rents (FACs) with effectively 10-min time resolution (Anderson et al., 2000; Waters et
 74 al., 2020). To derive similar maps of ionospheric conductance at high time resolution,
 75 one can use global satellite images of the UV aurora (Frey et al., 2003), which were spo-
 76 radically available between 1996 and 2005 when NASA’s Polar and IMAGE satellite mis-
 77 sions were active. Unfortunately the availability of global maps of conductance, convec-
 78 tion, FACs, and ground magnetic field perturbations do not all overlap in time.

79 Even with these global maps we only achieve partial views of ionospheric electro-
 80 dynamics, one parameter at a time. Their utility can be increased through data assim-
 81 ilation, combining observations with theoretical models to obtain a more complete view
 82 of ionospheric electrodynamics. A pioneering step towards this end was made by Kamide
 83 et al. (1981), who presented what has become known as the “KRM technique.” The KRM
 84 technique uses ground magnetic field measurements in combination with conductance
 85 maps to calculate the ionospheric convection and electric field. They calculated the curl
 86 of the ionospheric Ohm’s law to derive a partial differential equation that relates ground
 87 magnetic field disturbances and the electric field. This approach is also at the founda-
 88 tion of the Assimilative Mapping of Ionospheric Electrodynamics (AMIE) technique in-
 89 troduced by Richmond & Kamide (1988). AMIE uses magnetic field measurements from
 90 ground and space, and ionospheric convection or electric field measurements in an in-
 91 version for the electric field. The electric field is represented with spherical cap harmo-
 92 nics (Haines, 1985), basis functions that cover the entire region poleward of some chosen
 93 latitude – typically 50° . AMIE also assumes that the ionospheric Ohm’s law is valid, and
 94 it requires that the ionospheric Hall and Pedersen conductances are known or solved for
 95 in a separate inversion (Lu, 2017). The AMIE technique has been successfully used for
 96 more than three decades, and is still being actively developed to ingest the global data
 97 sets mentioned above, and to improve error estimates and stability (Matsuo, 2020; AM-
 98 GeO Collaboration, 2019).

99 AMIE yields patterns of ionospheric electrodynamics that cover the entire region
 100 poleward of 50° . However, the observations used in the inversion are never evenly dis-
 101 tributed. This is illustrated in Figure 1, which shows data from SuperMAG, Iridium, and
 102 SuperDARN collected during a 4-min interval starting at 01:00 UT 5 April 2012. Su-
 103 perMAG horizontal magnetic field perturbations, rotated 90° to align with an equiva-
 104 lent overhead current are shown in orange. Iridium horizontal magnetic field measure-
 105 ments, provided via the Active Magnetosphere and Planetary Electrodynamics Response
 106 Experiment (AMPERE) (Anderson et al., 2017) are shown in blue. The green dots show
 107 the locations where the SuperDARN radars could estimate line-of-sight convection ve-
 108 locities during these minutes. We see that the data density is much higher in North Amer-
 109 ica and in Fennoscandia compared to the rest of the polar region. AMIE inversions there-
 110 fore have much stronger observational support in some regions of the map than others.
 111 The high data density in some regions could also support a better spatial resolution than
 112 can be justified in global analyses. This elicits the need for analysis techniques that are
 113 more flexible with respect to spatial scale and extent. In addition to the nonuniform data
 114 distribution on a global scale, there are certain measurements that can resolve very small-
 115 scale structures, which would also benefit from analysis techniques with high spatial res-
 116 olution. Examples include convection and conductivity measurements in the field of view
 117 of phased array incoherent scatter radars, and high-resolution scans of the mesospheric

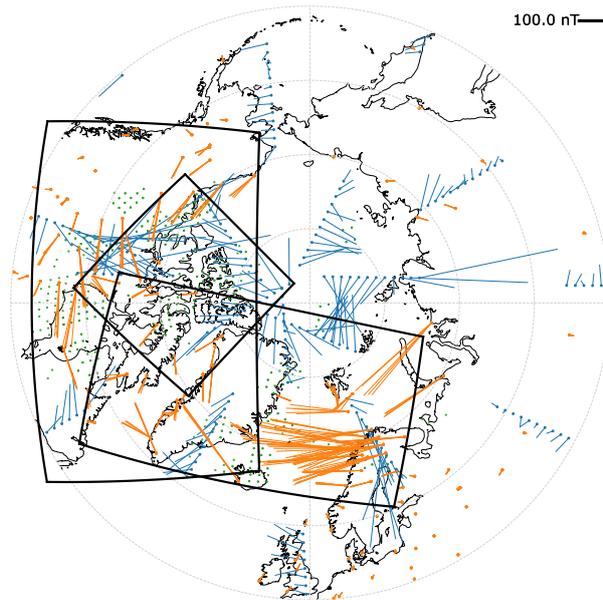


Figure 1. Example distribution of ionospheric electrodynamic measurements, from a 4-min period starting at 01:00 UT, 5 April 2012. The blue lines represent horizontal magnetic field disturbances measured from the fleet of Iridium satellites, provided by AMPERE. The orange lines represent horizontal magnetic field disturbances on ground, from SuperMAG. A scale for the Iridium and SuperMAG magnetic field vectors is shown in the top right corner. The green dots represent the locations of SuperDARN backscatter, which provides estimates of the line-of-sight plasma convection velocity. The frames show the extent of the grids used in example figures in Section 4.

118 magnetic field along the track of the the upcoming Electrojet Zeeman Imaging Explorer
119 (EZIE) satellites (Yee et al., 2017; Laundal et al., 2021).

120 Several alternatives to spherical harmonic analysis exist, which may be more suit-
121 able for regional analyses of ionospheric electrodynamics. Amm (1997) introduced spher-
122 ical elementary current systems (SECS), basis functions that describe vector fields on
123 a spherical shell that point either east-west or north-south relative to the pole at which
124 they are placed. The former type is divergence-free, and the latter type is curl-free. The
125 amplitude of the SECS functions falls off rapidly away from the pole, which makes them
126 well suited for regional modeling. A superposition of SECS functions can represent any
127 well-behaved vector field on a sphere, provided that they are placed sufficiently dense
128 and scaled appropriately.

129 Historically SECS analysis has been used mostly for regional studies of equivalent
130 currents (e.g., Amm & Viljanen, 1999; Amm et al., 2002; Amm, 1997; Weygand et al.,
131 2011; Laundal et al., 2021). However, global studies are also possible (Juusola et al., 2014).
132 SECS basis functions can also be used to represent ionospheric convection velocity (Amm
133 et al., 2010) or electric fields (Reistad, Laundal, Østgaard, Ohma, Haaland, et al., 2019;
134 Reistad, Laundal, Østgaard, Ohma, Thomas, et al., 2019). SECS play an important part
135 in the technique presented here, so we return to a detailed description of their definition
136 and key properties below. We note that there are other options for representing electric
137 fields or plasma flow in a regional grid: Nakano et al. (2020) presented an analysis tech-
138 nique for ionospheric plasma convection that uses basis functions similar to SECS, but
139 without a singularity at the pole. Nicolls et al. (2014) used radar line-of-sight convec-
140 tion measurements to constrain a grid of electric potential values. The measurements
141 and potential values were related via a matrix that numerically evaluates the gradient
142 of the potential, i.e., the electric field components. Bristow et al. (2016), instead of fit-
143 ting an electric potential (a curl-free vector function), fitted a divergence-free velocity
144 to a set of SuperDARN radar measurements in a limited region with high data density.

145 The regional studies mentioned above were all concerned with one quantity at the
146 time, and did not combine data as in the KRM or AMIE techniques. A SECS equiva-
147 lent to the KRM technique, calculating the electric field from the equivalent current and
148 ionospheric conductivity, was presented by Vanhamäki & Amm (2007), but it involves
149 a multi-step inversion technique which may be difficult to control.

150 In this paper we present a SECS equivalent to the AMIE technique, of which KRM
151 is a subset. Our technique has one single matrix that relates many different kinds of quan-
152 tities at any location to a single set of model parameters. To find the model parameters,
153 we can combine measurements of magnetic field perturbations on ground and in space,
154 plasma convection, ionospheric electric field, or even FACs, in an inversion. When the
155 model parameters are known, the same quantities can be calculated as output at any lo-
156 cation within the analysis region. That means that if we know one quantity (e.g., the
157 magnetic field on ground), and the ionospheric conductance, everything else can be cal-
158 culated. The extent of the analysis region and the spatial resolution are flexible.

159 We call this method “Local mapping of polar ionospheric electrodynamics”, or Lompe
160 (not to be confused with the Norwegian potato-based flatbread). The theoretical basis
161 for the Lompe technique, including how we use results from SECS analysis to relate elec-
162 tric and magnetic fields, is presented in Section 2. In Section 3 we describe in detail the
163 numerical implementation of the technique. Example results from synthetic and real datasets
164 are presented in Section 4. Some limitations and future prospects are discussed in Sec-
165 tion 5, and Section 6 concludes the paper. Python code to reproduce the figures in this
166 paper, and to use the Lompe technique for other events, is publicly available (Laundal
167 et al., 2022).

2 Theoretical background

In this section we describe the theoretical background for the Lompe technique. We seek to relate four different quantities: Ionospheric electric fields, F-region plasma convection velocities, ground magnetic field disturbances, and space magnetic field disturbances. The purpose of this discussion is to precisely describe the assumptions that we make and the associated theoretical limitations. The numerical implementation, and associated limitations, are discussed in Section 3.

2.1 Electric field

We choose to represent the ionospheric electric field as a sum of curl-free spherical elementary current systems (SECS) (Amm, 1997; Vanhamäki & Juusola, 2020) in a grid on a spherical shell with radius R_I . Physically, this corresponds to modelling the electric field in terms of electric charge densities on a set of discrete lines that extend radially from R_I to infinity (Reistad, Laundal, Østgaard, Ohma, Haaland, et al., 2019). The use of curl-free local basis functions to represent \mathbf{E} implies an assumption that, by Faraday's law, $\frac{\partial \mathbf{B}}{\partial t} = 0$.

Our task is to find the magnitudes of these vertical line charge densities that best fit the available measurements and prior knowledge. Mathematically, we express the electric field as

$$\mathbf{E} = \sum_i \frac{-m_i}{4\pi R_I} \cot\left(\frac{\pi/2 - \lambda_i}{2}\right) \hat{\mathbf{n}}_i, \quad (1)$$

where the sum is over a grid of SECS poles that will be discussed in detail in Section 3; λ_i is the latitude in a coordinate system where the i th SECS pole defines the north pole; $\hat{\mathbf{n}}_i$ is a unit vector that points northward in this local coordinate system; and m_i is the amplitude of the i th SECS pole. The product $m_i \epsilon_0$, where ϵ_0 is the vacuum permittivity, has a unit of line charge density C/m (Reistad, Laundal, Østgaard, Ohma, Haaland, et al., 2019). The negative sign in Equation (1) is included to make it consistent with the convention from earlier papers (e.g., Vanhamäki & Juusola, 2020), which refer to the $-\hat{\mathbf{n}}_i$ direction.

We stick to the historical designation of spherical elementary *current system*, even though it is misleading in the context of electric fields. While most applications of SECS analysis have focused on electric currents, Amm et al. (2010) and Reistad, Laundal, Østgaard, Ohma, Haaland, et al. (2019) demonstrated its usefulness in analyses of ionospheric convection and associated electric field.

The electric field representation in Equation (1) is a starting point of the Lompe technique. In the following we will describe how we relate the electric field to F-region ion velocity and magnetic field disturbances on ground and in space, and in Section 3 we specify how we relate all quantities to the set of SECS amplitudes m_i .

2.2 F-region ion velocity

Electric fields and convection velocities are related by

$$\mathbf{v}_\perp = \mathbf{E} \times \mathbf{B} / B^2, \quad (2)$$

where \mathbf{B} is the magnetic field. Use of Equation (2) implies an assumption that the plasma is frozen-in. This is usually a good approximation in the upper F-region. It breaks down towards E-region altitudes where ion velocities become increasingly aligned with the neutral wind, while electrons remain frozen-in. Ion velocity measurements used in Lompe must be from a region where Equation (2) is valid. This is usually assumed to hold for SuperDARN (Chisham et al., 2007) radar measurements and ion velocity measurements from low Earth orbit satellites, such as *Swarm* (Knudsen et al., 2017) or Defense Me-

212 teorological Satellite Program (DMSP) (Rich, 1994). Convection data from these and
 213 similar sources could thus easily be incorporated in the Lompe technique.

214 The frozen-in approximation implies that $\mathbf{B} \cdot \mathbf{E} = 0$. This equation can in prin-
 215 ciple be used to retrieve the vertical component of \mathbf{E} if its horizontal components are spec-
 216 ified via Equation (1). However, for simplicity we neglect horizontal components in \mathbf{B} ,
 217 and thus also any vertical component in \mathbf{E} . This approximation simplifies the relation-
 218 ship between electric currents and the magnetic field discussed below, and it leads to only
 219 small errors in polar regions (e.g., Untiedt & Baumjohann, 1993). This approximation
 220 implies that Equation (2) becomes

$$\mathbf{v}_\perp = \mathbf{E} \times \hat{\mathbf{u}} \frac{B_u}{B^2}, \quad (3)$$

221 where $\hat{\mathbf{u}}$ is an upward unit vector, B_u the upward component of the magnetic field, and
 222 B is its magnitude. We believe that the effects of magnetic field inclination on polar iono-
 223 spheric electrodynamics is an interesting and underexplored research topic, but it is be-
 224 yond the scope of this study. Note that \mathbf{v}_\perp is only the component of the velocity that
 225 is perpendicular to \mathbf{B} . Any parallel component should be subtracted before using Equa-
 226 tion (3) to relate \mathbf{v} and \mathbf{E} .

227 2.3 Magnetic field disturbances

228 In order to relate electric fields and conductances to magnetic field disturbances,
 229 we use the ionospheric Ohm’s law integrated over the height of the ionosphere:

$$\mathbf{J} = \Sigma_P \mathbf{E}' - \Sigma_H \mathbf{E}' \times \mathbf{B}/B. \quad (4)$$

230 \mathbf{J} is the height-integrated electric current, which we model as a surface-current density
 231 on the spherical shell at radius R_I . \mathbf{E}' is the electric field in the reference frame of the
 232 neutral wind. In the following, we make the assumption that the neutral wind is known,
 233 and skip the primes. Σ_P (P for Pedersen) and Σ_H (H for Hall) are height-integrated con-
 234 ductivities, referred to as conductances. Equation (4) is a steady-state solution of the
 235 set of momentum equations for ions and electrons, moving through an unaffected neu-
 236 tral fluid (e.g., Dreher, 1997). Only the collision and Lorentz force terms are included
 237 in the momentum equation. Inertia and all other forces are neglected. The Lompe parametriza-
 238 tion thus assumes that these approximations are valid.

239 We also assume that the conductances are known. The great advantage of this is
 240 that it ensures that all other quantities can be related to the electric field model param-
 241 eters by linear equations. The disadvantage is that it is difficult to know the conductances
 242 precisely. The main reason for this is the contribution to ionization from auroral pre-
 243 cipitation, which can be highly variable and difficult to measure. The solar EUV con-
 244 tribution to conductances is more stable. In Section 2.4 we present a novel approach to
 245 calculate solar EUV conductances, which avoids the problem of infinite gradients at the
 246 sunlight terminator that is present in some earlier work.

247 In its basic form, Equation (4) is not very useful to us, since we never really mea-
 248 sure \mathbf{J} directly. Instead, we measure magnetic field disturbances $\Delta\mathbf{B}$ on ground and in
 249 space. To relate $\Delta\mathbf{B}$ and \mathbf{E} we calculate the magnetic field disturbances associated with
 250 \mathbf{J} in Equation (4). One possible approach could be to perform a Biot-Savart integral over
 251 a sufficiently large part of the ionospheric shell, but this would be numerically expen-
 252 sive. Instead, we use results from SECS analysis.

253 First of all, we note that Helmholtz’s theorem implies that any well-behaved vec-
 254 tor field on a 2D spherical shell can be represented as a sum of curl-free (superscript \star)
 255 and divergence-free (superscript \circ) vector fields. Consequently, we can write $\mathbf{J} = \mathbf{J}^\star +$
 256 \mathbf{J}° . \mathbf{J}^\star and \mathbf{J}° can be represented as sums of curl-free and divergence-free spherical el-

257 elementary current systems:

$$\mathbf{J}^*(\lambda, \phi) = \sum_i \frac{-S_i^*}{4\pi R_I} \cot\left(\frac{\pi/2 - \lambda_i}{2}\right) \hat{\mathbf{n}}_i \quad (5)$$

$$\mathbf{J}^\circ(\lambda, \phi) = \sum_i \frac{S_i^\circ}{4\pi R_I} \cot\left(\frac{\pi/2 - \lambda_i}{2}\right) \hat{\mathbf{e}}_i \quad (6)$$

258 where the summation index i is over a grid of SECS nodes (to be specified in Section 3).
 259 These basis functions are complete in that their sum can describe any 2D vector field
 260 on the sphere provided that they are placed densely enough that all relevant spatial scales
 261 are resolved. λ_i and $\hat{\mathbf{n}}_i$ have the same meaning as in Equation (1). $\hat{\mathbf{e}}_i$ is an eastward unit
 262 vector in a coordinate system with the i th SECS pole in the north pole. The scalars S_i^*
 263 and S_i° represent the amplitudes of the i th curl-free and divergence-free basis functions,
 264 respectively.

265 Given the representation of \mathbf{J} in terms of curl-free and divergence-free spherical el-
 266 elementary current systems, we can calculate magnetic field disturbances analytically: Amm
 267 & Viljanen (1999) showed that the magnetic field of a single curl-free SECS is (follow-
 268 ing notation from Vanhamäki & Juusola (2020), and using the co-latitude $\theta = \pi/2 - \lambda$):

$$\Delta B_{n_i}(\theta_i, r) = 0 \quad (7)$$

$$\Delta B_{e_i}(\theta_i, r) = -\frac{S_i^* \mu_0}{4\pi r} \begin{cases} 0 & r < R_I \\ \cot(\theta_i/2) & r > R_I \end{cases} \quad (8)$$

$$\Delta B_u(\theta_i, r) = 0 \quad (9)$$

269 and the magnetic field of a single divergence-free SECS is

$$\Delta B_{n_i}(\theta_i, r) = \frac{\mu_0 S_i^\circ}{4\pi r \sin \theta_i} \begin{cases} \frac{s - \cos \theta_i}{\sqrt{1+s^2-2s \cos \theta_i}} + \cos \theta_i & r < R_I \\ \frac{1-s \cos \theta_i}{\sqrt{1+s^2-2s \cos \theta_i}} - 1 & r > R_I \end{cases} \quad (10)$$

$$\Delta B_{e_i}(\theta_i, r) = 0 \quad (11)$$

$$\Delta B_u(\theta_i, r) = \frac{\mu_0 S_i^\circ}{4\pi r} \begin{cases} \frac{1}{\sqrt{1+s^2-2s \cos \theta_i}} - 1 & r < R_I \\ \frac{s}{\sqrt{1+s^2-2s \cos \theta_i}} - s & r > R_I \end{cases} \quad (12)$$

$$s = \min(r, R_I) / \max(r, R_I). \quad (13)$$

270 The magnetic field of several curl-free and divergence-free elementary current systems
 271 is the sum of the contribution from each current.

272 Given \mathbf{E} , Σ_H , and Σ_P , we could use the ionospheric Ohm's law in Equation (4) to
 273 find a SECS representation of \mathbf{J} , and Equations (7)–(13) to find the associated magnetic
 274 field disturbances. However, our task here is the opposite: To find \mathbf{E} , given Σ_H , Σ_P , and
 275 a set of measured magnetic field disturbances. To do that, we must find a relationship
 276 between the electric field model parameters m_i (Equation (1)) and the amplitudes in a
 277 SECS representation of \mathbf{J} .

278 To do this, we calculate the divergence and curl of Equation (4). Starting with the
 279 divergence, we get

$$\nabla \cdot \mathbf{J} = \nabla \cdot \mathbf{J}^* = \nabla \Sigma_P \cdot \mathbf{E} + \Sigma_P \nabla \cdot \mathbf{E} \mp \hat{\mathbf{u}} \cdot (\mathbf{E} \times \nabla \Sigma_H) \quad (14)$$

280 where we have used the assumption $\nabla \times \mathbf{E} = 0$ made in Section 2.1. Here \mp refers to
 281 the northern (–) and southern (+) hemispheres due to the different orientations of the
 282 Earth's main magnetic field. This is a differential equation that relates the electric field
 283 to the curl-free part of the horizontal current. Current continuity implies that the di-
 284 vergence of the horizontal current is equal to the downward magnetic field-aligned cur-
 285 rent. The combined magnetic effect of horizontal curl-free current and radial FACs is zero

286 below the ionosphere according to Fukushima's theorem (Fukushima, 1976) and Equa-
 287 tions (7)–(9).

288 Equation (14) is fundamental in most schemes to couple the magnetosphere with
 289 the ionosphere in global magnetohydrodynamic (MHD) simulations (e.g., Wiltberger et
 290 al., 2004). MHD simulations give the field-aligned current density at the top of the iono-
 291 sphere, which must be equal to the divergence of the horizontal ionospheric current given
 292 by Equation (14), or else charges would pile up. The resulting current continuity equa-
 293 tion can be solved for \mathbf{E} , which is used as a boundary condition for the MHD simula-
 294 tion. In Section 3.4 we show how the Lompe framework can be used to solve the cur-
 295 rent continuity equation.

296 The curl-free spherical elementary current systems have the property that (Van-
 297 hamäki & Juusola, 2020)

$$\nabla \cdot \mathbf{J}_i^* = S_i^* \left(\delta(\lambda_i, \phi_i) - \frac{1}{4\pi R_I^2} \right), \quad (15)$$

298 where $\delta(\lambda_i, \phi_i)$ is the Dirac delta function. This property can help us to relate Equation (14)
 299 directly to a set of amplitudes S_i^* of SECS basis functions. To achieve this, we place the
 300 basis functions in a grid with cells denoted Ω_i . Integrating $\nabla \cdot \mathbf{J}$ over the j th cell, we
 301 obtain

$$\int_{\Omega_j} \nabla \cdot \mathbf{J} dA = \int_{\Omega_j} \nabla \cdot \sum_i \frac{S_i^*}{4\pi R_I} \cot(\pi/4 - \lambda_i/2) \hat{\mathbf{e}}_i dA \quad (16)$$

$$= \int_{\Omega_j} \sum_i S_i^* \left(\delta(\lambda_i, \phi_i) - \frac{1}{4\pi R_I^2} \right) dA \quad (17)$$

$$= S_j^* - A_j \sum_i \frac{S_i^*}{4\pi R_I^2}, \quad (18)$$

302 where A_j is the area of Ω_j . The sums are over all cells in a global grid. If we choose a
 303 grid with cells that are small compared to the scale size of \mathbf{J} , we can approximate the
 304 integral on the left hand side to get

$$\nabla \cdot \mathbf{J} \Big|_{\Omega_j} A_j = S_j^* - A_j \sum_i \frac{S_i^*}{4\pi R_I^2}. \quad (19)$$

305 Equation (19) relates the divergence of \mathbf{J} in Equation (14), evaluated on a discrete set
 306 of points, to the amplitudes S_i^* . These amplitudes are in turn related to the magnetic
 307 field disturbances via the equations presented above. This relationship can then be used
 308 to find a linear relationship between magnetic field disturbances associated with curl-
 309 free currents and the electric field model parameters m_i . In Section 3 we introduce our
 310 choice of grid and describe how we use Equation (19) to construct matrix equations that
 311 relate magnetic and electric fields.

312 The other part of the magnetic field relates to divergence-free currents. We calcu-
 313 late the curl of the ionospheric Ohm's law to get an expression that only depends on this
 314 part of the current:

$$(\nabla \times \mathbf{J})_u = (\nabla \times \mathbf{J}^o)_u = \nabla \Sigma_P \times \mathbf{E} \mp (\nabla \Sigma_H \cdot \mathbf{E}) \hat{\mathbf{u}} \mp \Sigma_H (\nabla \cdot \mathbf{E}) \hat{\mathbf{u}}, \quad (20)$$

315 again using the assumption that $\nabla \times \mathbf{E} = 0$. This is a differential equation that re-
 316 lates the electric field to the divergence-free part of the current. The divergence-free cur-
 317 rent is often treated as synonymous with the so-called equivalent current (e.g., Laundal
 318 et al., 2015), a theoretical 2D current in the ionosphere that is equivalent with magnetic
 319 field disturbances on the ground. Equation (20) is the foundation of the KRM technique
 320 (Kamide et al., 1981) which is used to infer ionospheric electrodynamic parameters from
 321 ground magnetometer measurements. We use the same principle here, applied to SECS

322 instead of the spherical harmonic representation used by Kamide et al. (1981), or the
 323 spherical cap harmonic representation used in AMIE (Richmond & Kamide, 1988). Van-
 324 hamäki & Amm (2007) were the first to use the KRM technique with SECS, but their
 325 approach is different from what we propose here.

326 The divergence-free spherical elementary current systems have the property that

$$(\nabla \times \mathbf{J}_i^\circ)_u = S_i^\circ \left(\delta(\lambda_i, \phi_i) - \frac{1}{4\pi R_I^2} \right). \quad (21)$$

327 Following the same procedure as with $\nabla \cdot \mathbf{J}$, integrating over the grid cell Ω_j , we find
 328 that

$$(\nabla \times \mathbf{J})_u|_j A_j = S_j^\circ - A_j \sum_i \frac{S_i^\circ}{4\pi R_I^2}, \quad (22)$$

329 which will be used in Section 3, together with Equation (19), to find matrix equations
 330 that relate magnetic field measurements to the electric field model parameters m_i .

331 2.4 Solar EUV conductances

332 The Lompe technique requires that ionospheric conductances are known. The con-
 333 ductance is a sum of contributions from precipitation by ionizing particles (auroral con-
 334 ductance) and ionization by solar EUV radiation. Many empirical formulas for the so-
 335 lar EUV contribution to ionospheric Pedersen and Hall conductances, hereafter Σ_P^{EUV}
 336 and Σ_H^{EUV} , express this contribution as a function of the solar zenith angle χ that is pro-
 337 portional to $\cos \chi$ or a linear combination of powers thereof (Ieda et al., 2014). The un-
 338 derlying assumption is that Σ_P^{EUV} and Σ_H^{EUV} are related to the maximum ionospheric
 339 plasma production along the path traveled by solar radiation (i.e., along the line defined
 340 by a particular value of χ). The maximum ionospheric plasma production for a partic-
 341 ular species is, in turn, proportional to $\cos \chi$ under some simplifying assumptions, in-
 342 cluding that (i) the neutral atmosphere is vertically stratified (i.e., the earth is flat), and
 343 (ii) the neutral atmosphere density height profile is exponential (e.g., Schunk & Nagy,
 344 2009; Ieda et al., 2014).

345 For our purposes the chief shortcoming of these formulations is that the derivatives
 346 of Σ_P^{EUV} and Σ_H^{EUV} are discontinuous at $\chi = 90^\circ$. We have therefore developed an al-
 347 ternative procedure for calculating Σ_P^{EUV} and Σ_H^{EUV} by instead assuming that the neu-
 348 tral atmosphere is radially rather than vertically stratified (i.e., the earth is round). In
 349 summary, setting to zero the derivative of the plasma production function (e.g., Equa-
 350 tion 9.21 in Schunk & Nagy, 2009)

$$q(z, \chi) = q_0 n(z) e^{-\tau(z, \chi)} \quad (23)$$

351 with respect to altitude z yields the transcendental equation

$$\frac{d}{dz} \left[e^{-(z-z_0)/H} \text{Ch}(z, \chi) \right] = -\frac{1}{\sigma H^2 n_0}, \quad (24)$$

352 which can be solved numerically to obtain the height of maximum plasma production
 353 $z_m(\chi)$ for a given value of χ . In the preceding equations $\tau(z, \chi)$ is the optical depth, $n(z) =$
 354 $n_0 e^{-(z-z_0)/H}$ is the atmospheric neutral density profile, H is a constant scale height, σ
 355 is the absorption cross section, and

$$\text{Ch}(z, \chi) = \frac{1}{H} \int_z^\infty e^{-(z'-z)/H} \left[1 - \left(\frac{R_E + z}{R_E + z'} \right)^2 \sin^2 \chi \right]^{-1/2} dz' \quad (25)$$

356 is the Chapman function (e.g., Huestis, 2001). We then calculate the relative maximum
 357 production

$$q'(\chi) = \frac{q(z_m(\chi), \chi)}{q(z_m(0^\circ), 0^\circ)} \quad (26)$$

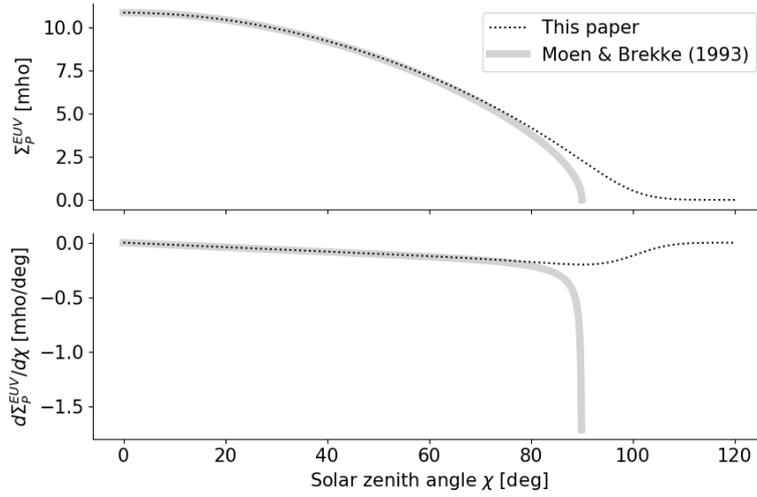


Figure 2. Solar EUV contribution to Pedersen conductance (top) and its derivative (bottom) calculated using Equation (28) (thick gray line) and Equation (6) in Moen & Brekke (1993) (dotted black line). Here $z_m(\chi)$ in Equation (28) is calculated by solving Equation (24) with $n_0 = 10^{13} \text{ m}^{-3}$, $z_0 = 500 \text{ km}$, $H = 50 \text{ km}$, and absorption cross section $\sigma = 10^{-20} \text{ m}^2$.

358 for all χ in $[0^\circ, 120^\circ]$.

359 The function $q'(\chi)$ is directly analogous to $\cos \chi$, such that $q'(\chi) \rightarrow \cos \chi$ as $R_E \rightarrow$
 360 ∞ in Equation (25). To calculate Σ_P^{EUV} and Σ_H^{EUV} in the Lompe model we therefore re-
 361 place $\cos \chi$ with $q'(\chi)$ in the empirical formulas presented by Moen & Brekke (1993):

$$\Sigma_H^{\text{EUV}} = F10.7^{0.53} \left(0.81q'(\chi) + 0.54\sqrt{q'(\chi)} \right); \quad (27)$$

362

$$\Sigma_P^{\text{EUV}} = F10.7^{0.49} \left(0.34q'(\chi) + 0.93\sqrt{q'(\chi)} \right). \quad (28)$$

363 Figure 2 shows Σ_P^{EUV} both as given by Equation (6) in Moen & Brekke (1993) and as
 364 given here in Equation (28), as well as their derivatives with respect to χ .

365 3 Numerical implementation

366 In this section we present how we formulate the theory of Section 2 in terms of matrix
 367 equations that relate the electric field model parameters m_i in Equation (1) to mea-
 368 surements of the electric field, ionospheric convection, ground magnetic field disturbances,
 369 and space magnetic field disturbances. We start by introducing the grid, before we go
 370 through the matrix equations for each type of measurement. In Section 3.3 we discuss
 371 how the resulting set of equations is solved.

372 3.1 The grid

373 The basis of the matrix formulations below is a regular grid in a cubed sphere pro-
 374 jection (Ronchi et al., 1996). A cubed sphere projection maps every point on the Earth
 375 onto a circumscribed cube by extending the line that connects the center of the Earth
 376 and the position on the sphere until it intersects the cube. To minimize distortion, we
 377 rotate the cube such that one of the faces intersects the center of our region of interest.
 378 In our current implementation, we use only coordinates on this intersecting cube face.

379 Figure 3 shows an example grid in red, with electric field SECS poles with ampli-
 380 tudes m_i (Equation (1)) at the center of each cell. This example grid is intentionally very
 381 coarse for illustration purposes; in reality it can be placed at any location, with any ori-
 382 entation, aspect ratio, and resolution. It can cover regions of any size as long as all points
 383 map to a single cube face.

384 Figure 3 also shows an interior grid, in black, whose cells are centered on the in-
 385 ner vertices of the red grid. As will be explained in more detail below, these points are
 386 where the divergence (labeled d_i in the figure) and curl (labeled c_i) of \mathbf{J} will be evalu-
 387 ated in order to relate m_i to magnetic field measurements. The outer grid has K_E grid
 388 cells and the inner cell has K_J grid cells. In this example, $K_E = 20$ and $K_J = 12$.

389 Before we proceed, we note that the relationships between \mathbf{E} (expressed in terms
 390 of m_i) and the curl/divergence of \mathbf{J} involve horizontal gradients of Σ_H and Σ_P . We there-
 391 fore introduce $K_J \times K_J$ matrices $\mathbb{D}_{\mathbf{e}, \nabla}$ and $\mathbb{D}_{\mathbf{n}, \nabla}$ (we use this “blackboard-bold” nota-
 392 tion for matrices throughout the paper) which produces the eastward and northward com-
 393 ponents of the gradient of a scalar field defined on the inner K_J grid cells. That is, if Σ_H
 394 is a $K_J \times 1$ vector containing the values of Σ_H at the centers of the inner grid cells, $\mathbb{D}_{\mathbf{e}, \nabla} \Sigma_H$
 395 yields another $K_J \times 1$ vector with $\hat{\mathbf{e}} \cdot \nabla \Sigma_H$ evaluated at the same points. The differen-
 396 tiation is carried out using a finite difference scheme, and the elements of the differen-
 397 tiation matrices depend on the stencil used, distortion effects to take into account Earth’s
 398 spherical shape (Ronchi et al., 1996), and on the orientation and position of the grid with
 399 respect to the underlying global coordinate system.

400 Equations (14) and (20) also involve the divergence of \mathbf{E} itself. We therefore also
 401 define a $K_J \times 2K_J$ matrix $\mathbb{D}_{\nabla, \cdot}$, which calculates the divergence of \mathbf{E} evaluated at the
 402 center of the K_J grid cells. This matrix is also implemented using a finite difference scheme.
 403 In Section 3.2.1 it will be made clearer how this matrix is used.

404 The SECS definitions include a cot function that approaches infinity towards the
 405 node. This singularity is a main reason why we use two grids that are offset from each
 406 other. For example, we evaluate the curl and divergence of \mathbf{J} at the centers of the in-
 407 ner grid cells, away from the electric field nodes. Our data points, however, are not nec-
 408 essarily optimally placed with respect to the nodes. We handle this by modifying the SECS
 409 function definitions near the node as proposed by Vanhamäki & Juusola (2020). The mod-
 410 ification is applied in the region closer than half the extent of a grid cell.

411 3.2 Matrix formulation

412 The model parameters, the electric field SECS amplitudes m_i , are organized in a
 413 $K_E \times 1$ vector \mathbf{m} . We use the notation $\tilde{\mathbf{y}}$ to denote an $N \times 1$ vector of N predictions
 414 of some general quantity y , in practice either the electric field, F-region ion velocity, ground
 415 magnetic field perturbation, or space magnetic field perturbation. In the following sub-
 416 sections we go through the matrices that relate each of these quantities to the model vec-
 417 tor \mathbf{m} . Our aim is to describe the $N \times K_E$ matrix \mathbb{G} in the linear system

$$\tilde{\mathbf{y}} = \mathbb{G}\mathbf{m}, \tag{29}$$

418 which relates $\tilde{\mathbf{y}}$ and \mathbf{m} . This section (Section 3.2) describes the forward problem, how
 419 to calculate \mathbb{G} . Section 3.3 describes how we solve the inverse problem: Finding \mathbf{m} given
 420 a set of measurements $\tilde{\mathbf{y}}$.

421 3.2.1 Electric field

422 As described in Section 2.1, the electric field is represented as a sum of curl-free
 423 spherical elementary current systems with amplitudes m_i , $i = 1, 2, \dots, K_E$, forming the
 424 elements of the vector \mathbf{m} . We can relate N_E predictions of the electric field eastward and

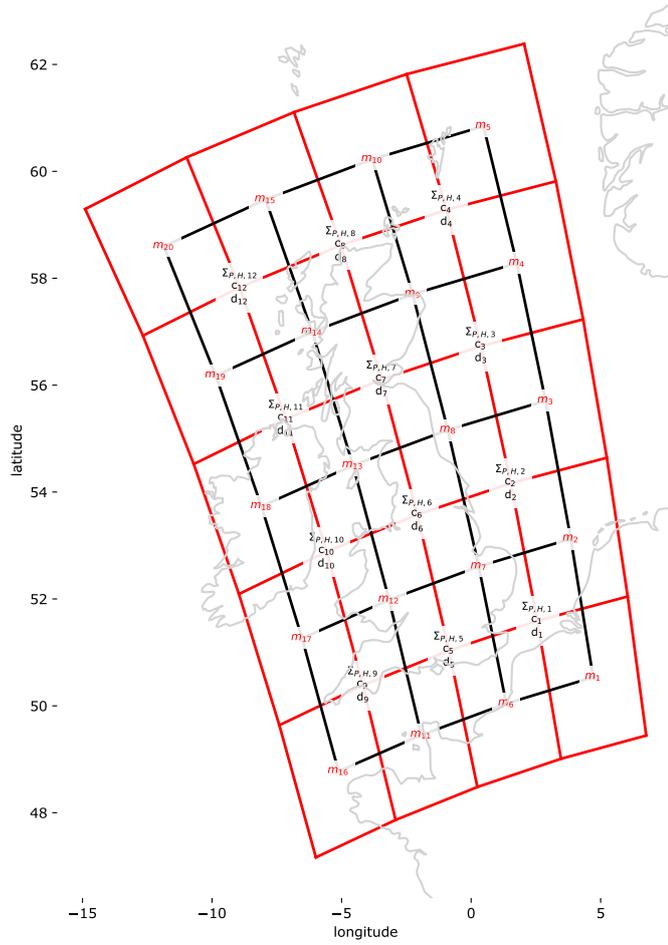


Figure 3. Example of the cubed sphere grid used in Lompe, in this case covering the British Isles. For illustration purposes, this grid is much coarser than the grids used for actual calculations. Shown in a cylindrical projection.

425 northward components to \mathbf{m} via a $2N_E \times K_E$ system of equations,

$$\begin{pmatrix} \tilde{\mathbf{E}}_e \\ \tilde{\mathbf{E}}_n \end{pmatrix} = \begin{pmatrix} \mathbb{E}_e \\ \mathbb{E}_n \end{pmatrix} \mathbf{m} \quad (30a)$$

$$\tilde{\mathbf{E}} = \mathbb{E} \mathbf{m} \quad (30b)$$

426 where $\tilde{\mathbf{E}}_e$ and $\tilde{\mathbf{E}}_n$ are $N_E \times 1$ column vectors with eastward and northward electric field
 427 components, stacked to form the $2N_E \times 1$ vector $\tilde{\mathbf{E}}$. \mathbb{E}_e is a $N_E \times K_E$ matrix whose j th
 428 row relates the j th element of $\tilde{\mathbf{E}}_e$ to \mathbf{m} . The elements of this row are the terms in the
 429 sum in Equation (1), projected on the eastward unit vector. That is, the (j, i) th element
 430 of \mathbb{E}_e is

$$\mathbb{E}_{e_{j,i}} = \frac{-1}{4\pi R_I} \cot\left(\frac{\pi/2 - \lambda_{j,i}}{2}\right) \hat{\mathbf{n}}_{j,i} \cdot \hat{\mathbf{e}}, \quad (31)$$

431 where $\lambda_{j,i}$ is the latitude of the j th element in $\tilde{\mathbf{E}}_e$, expressed in a local coordinate sys-
 432 tem where the i th SECS node is at the north pole. $\hat{\mathbf{n}}_{j,i}$ is a unit vector pointing tangen-
 433 tially to the sphere from the j th prediction to the i th SECS node (a northward unit vec-
 434 tor in the coordinate system centered on the i th node). \mathbb{E}_n is defined analogously, relat-
 435 ing the northward components to \mathbf{m} .

436 3.2.2 Velocity

437 The velocity is related to the electric field via Equation (3), given the assumptions
 438 outlined in Section 2.2. Equation (3) includes the magnetic field, which is strongly dom-
 439 inated by sources internal to the Earth, the ‘‘main magnetic field,’’ described by the In-
 440 ternational Geomagnetic Reference Field (IGRF) (Alken et al., 2021). Let \mathbb{B}_0 be an $N_v \times$
 441 N_v diagonal matrix formed by B_u/B^2 , where B_u is the upward component and B the
 442 total magnitude of the main field at N_v velocity vector locations. N_v predictions of the
 443 eastward and northward components of the velocity are related to \mathbf{m} via a $2N_v \times K_E$
 444 system of equations,

$$\begin{pmatrix} \tilde{\mathbf{v}}_e \\ \tilde{\mathbf{v}}_n \end{pmatrix} = \begin{pmatrix} \mathbb{V}_e \\ \mathbb{V}_n \end{pmatrix} \mathbf{m} \quad (32a)$$

$$= \begin{pmatrix} \mathbb{B}_0 & \mathbb{0} \\ \mathbb{0} & \mathbb{B}_0 \end{pmatrix} \begin{pmatrix} \mathbb{E}_n \\ -\mathbb{E}_e \end{pmatrix} \mathbf{m} \quad (32b)$$

$$\tilde{\mathbf{v}} = \mathbb{V} \mathbf{m} \quad (32c)$$

445 where $\mathbb{0}$ is an $N_v \times N_v$ zero matrix. Here \mathbb{V}_e , \mathbb{V}_n , \mathbb{E}_e and \mathbb{E}_n are $N_v \times K_E$ matrices.

446 Very often the ion velocity is only measured along one direction. For example, Su-
 447 perDARN gives measurements of \mathbf{v} along the line-of-sight direction of the radars. If we
 448 have N_v line-of-sight measurements, the matrix \mathbb{V}_{los} , which relates the line-of-sight mea-
 449 surements to \mathbf{m} , has dimensions $N_v \times K_E$ and can be expressed in terms of unit vec-
 450 tors in the line-of-sight direction, $\mathbf{l} = l_e \mathbf{e} + l_n \mathbf{n}$:

$$\tilde{\mathbf{v}}_{\text{los}} = \mathbb{V}_{\text{los}} \mathbf{m} = \mathbb{B}_0 (\mathbb{l}_e \mathbb{E}_n - \mathbb{l}_n \mathbb{E}_e) \mathbf{m} \quad (33)$$

451 where \mathbb{l}_e and \mathbb{l}_n are $N_v \times N_v$ diagonal matrices formed by the N_v line-of-sight vector com-
 452 ponents l_e and l_n , respectively.

453 3.2.3 Ground magnetic field

454 As discussed in Section 2.3, the combined magnetic field of FACs and curl-free cur-
 455 rents cancel on ground, so only the divergence-free currents are relevant when model-
 456 ing ground magnetic field perturbations.

457 In this classical application of spherical elementary current systems, the divergence-
 458 free part of the horizontal ionospheric current is represented as a weighted sum of ele-
 459 mentary currents, Equation (6), and ground magnetic field disturbances are related to

460 these currents via Equations (10)–(12). Let \mathbf{S}° be a $K_J \times 1$ vector of divergence-free SECS
 461 amplitudes, defined on the K_J interior grid points. We can write the relationship between
 462 \mathbf{S}° and a set of ground magnetic field disturbance vector components $\Delta\tilde{\mathbf{B}}_{ge}$, $\Delta\tilde{\mathbf{B}}_{gn}$ and
 463 $\Delta\tilde{\mathbf{B}}_{gu}$ (subscripts referring to east, north, up) as

$$\begin{pmatrix} \Delta\tilde{\mathbf{B}}_{ge} \\ \Delta\tilde{\mathbf{B}}_{gn} \\ \Delta\tilde{\mathbf{B}}_{gu} \end{pmatrix} = \begin{pmatrix} \mathbb{H}_{ge}^\circ \\ \mathbb{H}_{gn}^\circ \\ \mathbb{H}_{gu}^\circ \end{pmatrix} \mathbf{S}^\circ \quad (34a)$$

$$\Delta\tilde{\mathbf{B}}_g = \mathbb{H}_g^\circ \mathbf{S}^\circ \quad (34b)$$

464 where the elements of the matrices \mathbb{H}_{ge}° , \mathbb{H}_{gn}° and \mathbb{H}_{gu}° are given by Equations (10)–(12).
 465 With a total of N_{B_g} 3D vector predictions, \mathbb{H}_g° has shape $3N_{B_g} \times K_J$.

466 Our aim is to relate the magnetic field vector components to the electric field model
 467 vector \mathbf{m} . To do that, we use the curl of the ionospheric Ohm’s law, Equation (20). We
 468 define a column vector \mathbf{c} formed by the curl of the ionospheric current evaluated at the
 469 center of the K_J interior grid points. Equation (22) can be used to construct a matrix
 470 equation that relates \mathbf{c} and \mathbf{S}° :

$$\mathbb{A}\mathbf{c} = \mathbb{Q}\mathbf{S}^\circ \quad (35)$$

471 where \mathbb{A} is a $K_J \times K_J$ diagonal matrix formed by the areas of the K_J cells. \mathbb{Q} is a $K_J \times$
 472 K_J matrix with elements

$$Q_{ji} = \delta_{ji} - A_{jj}/4\pi R_I^2 \quad (36)$$

473 where δ_{ji} is the Kronecker delta, defined to be 0 when $j \neq i$ and 1 when $j = i$, not
 474 to be confused with the Dirac delta function used in Equations (15) and (21).

475 The last term in Equation (36) comes from the sum in Equation (22). This sum
 476 is the contribution to the curl in the j th cell (i.e., Ω_j) from all elementary current sys-
 477 tems. In theory, this should include current systems that are outside our grid. We ig-
 478 nore this here, noting that their contributions to the curl are scaled by a very small num-
 479 ber: The area of the local grid cell A_{jj} divided by the total area of the sphere. Their net
 480 amplitude would have to be very large to make a significant contribution to the curl in
 481 cell Ω_j .

482 Equations (34b) and (35) can be combined to give

$$\Delta\tilde{\mathbf{B}}_g = \mathbb{H}_g^\circ \mathbb{Q}^{-1} \mathbb{A} \mathbf{c}. \quad (37)$$

483 The vector \mathbf{c} can be expressed in terms of the electric field model vector \mathbf{m} by using Equa-
 484 tion (20):

$$\begin{aligned} \mathbf{c} = & [-\text{diag}(\mathbb{D}_{\hat{\mathbf{n}} \cdot \nabla} \boldsymbol{\Sigma}_P) \mathbb{E}_e + \text{diag}(\mathbb{D}_{\hat{\mathbf{e}} \cdot \nabla} \boldsymbol{\Sigma}_P) \mathbb{E}_n \\ & \mp \text{diag}(\mathbb{D}_{\hat{\mathbf{n}} \cdot \nabla} \boldsymbol{\Sigma}_H) \mathbb{E}_n \mp \text{diag}(\mathbb{D}_{\hat{\mathbf{e}} \cdot \nabla} \boldsymbol{\Sigma}_H) \mathbb{E}_e \\ & \mp \text{diag}(\boldsymbol{\Sigma}_H) \mathbb{D}_{\nabla \cdot \mathbb{E}}] \mathbf{m} = \mathbb{C} \mathbf{m}, \end{aligned} \quad (38)$$

485 where the “diag” function produces a diagonal matrix with the elements of the argument
 486 vector on the diagonal. $\boldsymbol{\Sigma}_H$ and $\boldsymbol{\Sigma}_P$ are $K_J \times 1$ column vectors that contain the Hall
 487 and Pedersen conductances, respectively, in the K_J interior grid cells. Recall that the
 488 matrices $\mathbb{D}_{\hat{\mathbf{e}} \cdot \nabla}$ and $\mathbb{D}_{\hat{\mathbf{n}} \cdot \nabla}$, multiplied by $\boldsymbol{\Sigma}_H$, produces K_J values of the gradient of the
 489 Hall conductance in the eastward and northward directions, respectively.

490 In Equation (38), \mathbb{E} is a $2K_J \times K_E$ matrix composed of the two $K_J \times K_E$ block
 491 matrices \mathbb{E}_e and \mathbb{E}_n that map the K_E electric field SECS amplitudes in \mathbf{m} to K_J val-
 492 ues of eastward and northward electric field components at the centers of the interior grid
 493 cells. With this definition, the divergence matrix $\mathbb{D}_{\nabla \cdot}$ from Section 3.1 can be used to
 494 directly map \mathbf{m} to the electric field divergences at the centers of the K_J interior grid cells:
 495 $\mathbb{D}_{\nabla \cdot} \mathbb{E} \mathbf{m}$.

496 The sum of all the terms in square brackets is a $K_J \times K_E$ matrix \mathbf{c} . This gives the
 497 following relationship between $\Delta\tilde{\mathbf{B}}_g$ and \mathbf{m} :

$$\begin{aligned}\Delta\tilde{\mathbf{B}}_g &= \mathbb{H}_g^\circ \mathbb{Q}^{-1} \mathbb{A} \mathbf{c} \mathbf{m} \\ &= \mathbb{B}_g^\circ \mathbf{m} = \mathbb{B}_g \mathbf{m}\end{aligned}\quad (39)$$

498 The divergence-free SECS amplitudes \mathbf{S}° are not directly involved in Equation (39),
 499 but can be calculated if needed by combining Equations (35) and (39):

$$\mathbf{S}^\circ = \mathbb{Q}^{-1} \mathbb{A} \mathbf{c} \mathbf{m}.\quad (40)$$

500 3.2.4 Space magnetic field

501 The magnetic field in space is often assumed to be dominated by the curl-free part
 502 of the ionospheric current system, including the field-aligned currents which represents
 503 its divergence. If this assumption is true, the magnetic field in space can be related to
 504 a set of K_J curl-free currents with amplitudes \mathbf{S}^* via Equation (5):

$$\begin{pmatrix} \Delta\tilde{\mathbf{B}}_e^* \\ \Delta\tilde{\mathbf{B}}_n^* \\ \Delta\tilde{\mathbf{B}}_u^* \end{pmatrix} = \begin{pmatrix} \mathbb{H}_e^* \\ \mathbb{H}_n^* \\ \mathbb{H}_u^* \end{pmatrix} \mathbf{S}^* \quad (41a)$$

$$\Delta\tilde{\mathbf{B}}^* = \mathbb{H}^* \mathbf{S}^* \quad (41b)$$

505 The first step in relating \mathbf{S}^* to the model vector \mathbf{m} is to relate it to the divergence
 506 of the ionospheric Ohm's law. Let \mathbf{d} be a column vector with the divergence of the cur-
 507 rent evaluated in the center of the K_J interior grid cells. Equation (19) gives the follow-
 508 ing relationship:

$$\mathbb{A} \mathbf{d} = \mathbb{Q} \mathbf{S}^* \quad (42)$$

509 where \mathbb{A} and \mathbb{Q} are the same as in Equation (35).

510 The vector \mathbf{d} , the divergence of the electric current evaluated in the interior grid
 511 cells, can be expressed from the divergence of the ionospheric Ohm's law, Equation (14):

$$\begin{aligned}\mathbf{d} &= [\mp \text{diag}(\mathbb{D}_{\hat{\mathbf{n}} \cdot \nabla} \boldsymbol{\Sigma}_H) \mathbb{E}_e \pm \text{diag}(\mathbb{D}_{\hat{\mathbf{e}} \cdot \nabla} \boldsymbol{\Sigma}_H) \mathbb{E}_n \\ &\quad + \text{diag}(\mathbb{D}_{\hat{\mathbf{e}} \cdot \nabla} \boldsymbol{\Sigma}_P) \mathbb{E}_e + \text{diag}(\mathbb{D}_{\hat{\mathbf{n}} \cdot \nabla} \boldsymbol{\Sigma}_P) \mathbb{E}_n \\ &\quad + \text{diag}(\boldsymbol{\Sigma}_P) \mathbb{D}_{\nabla} \cdot \mathbb{E}] \mathbf{m} = \mathbf{d} \mathbf{m},\end{aligned}\quad (43)$$

512 where \mathbb{E}_e , \mathbb{E}_n , and \mathbb{E} are defined as in Equation (38). Now we can combine Equations (41b),
 513 (42), and (43) to find a matrix \mathbb{B}^* that relates the magnetic field of curl-free currents to
 514 the model vector \mathbf{m} :

$$\Delta\tilde{\mathbf{B}}^* = \mathbb{H}^* \mathbb{Q}^{-1} \mathbb{A} \mathbf{d} \mathbf{m} = \mathbb{B}^* \mathbf{m}.\quad (44)$$

515 This set of equations is quite often sufficient to model magnetic field perturbations
 516 in space, especially when observed at high altitudes. However, satellites in lower orbits,
 517 like *Swarm*, also sense the magnetic field of the divergence-free currents. In that case,
 518 the full magnetic field is a sum of two contributions. We get

$$\Delta\tilde{\mathbf{B}} = \Delta\tilde{\mathbf{B}}^\circ + \Delta\tilde{\mathbf{B}}^* = (\mathbb{H}_s^\circ \mathbb{Q}^{-1} \mathbb{A} \mathbf{c} + \mathbb{H}^* \mathbb{Q}^{-1} \mathbb{A} \mathbf{d}) \mathbf{m} = (\mathbb{B}_s^\circ + \mathbb{B}^*) \mathbf{m} = \mathbb{B}_s \mathbf{m}, \quad (45)$$

519 where the matrix \mathbb{H}_s° is analogous to \mathbb{H}_g° from equation (39), except that it is calculated
 520 with the versions of Equations (10)–(12) for $r > R_I$.

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3.2.5 The full forward problem

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Equations (30b), (32c), (39), and (45) relate model predictions of the electric field, F-region plasma velocity, ground magnetic field perturbations, and space magnetic field perturbations, to the same set of model parameters, \mathbf{m} . The full set of linear equations can be written as

$$\begin{pmatrix} \tilde{\mathbf{E}} \\ \tilde{\mathbf{v}} \\ \tilde{\mathbf{B}}_g \\ \tilde{\mathbf{B}}_s \end{pmatrix} = \tilde{\mathbf{y}} = \begin{pmatrix} \mathbb{E} \\ \mathbb{V} \\ \mathbb{B}_g \\ \mathbb{B}_s \end{pmatrix} \mathbf{m} = \mathbb{G}\mathbf{m}. \quad (46)$$

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\mathbb{G} has dimensions $(2N_E + 2N_v + 3N_{B_g} + 3N_{B_s}) \times K_E$, possibly with fewer rows if not all vector components are calculated. \mathbb{G} depends on the conductance and on the geometry of the problem: The choice of grids, and the coordinates of the model predictions $\tilde{\mathbf{y}}$. When \mathbf{m} is known, all the parameters on the left hand side of Equation (46) can be estimated.

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3.3 Inversion

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Here we describe our approach for solving the set of Equations (46) for \mathbf{m} , given a set of measurements $\tilde{\mathbf{y}}$. Naively, this could be done by minimizing the sum of squared errors, which can be written as

$$\chi^2 = (\tilde{\mathbf{y}} - \mathbb{G}\mathbf{m})^\top (\tilde{\mathbf{y}} - \mathbb{G}\mathbf{m}). \quad (47)$$

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However, there are several problems with this, which we outline below, along with our approach to solve them.

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First, in SI units the magnetic field variance σ_B^2 is several orders of magnitude less than the electric field variance σ_E^2 , and even less than the convection velocity variance σ_v^2 . If we formulate the equations in SI units, which we do in our implementation, the misfit will be dominated by convection velocities. If we just minimize χ^2 , any magnetic field measurement would be practically neglected because of this mismatch. We solve this problem by scaling χ^2 using the matrix \mathbb{C} :

$$\chi^2 = (\tilde{\mathbf{y}} - \mathbb{G}\mathbf{m})^\top \mathbb{C} (\tilde{\mathbf{y}} - \mathbb{G}\mathbf{m}), \quad (48)$$

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where the diagonal elements of \mathbb{C} are $w_i/(\sigma_B + \epsilon_i)^2$, $w_i/(\sigma_v + \epsilon_i)^2$, or $w_i/(\sigma_E + \epsilon_i)^2$, depending on which measurement that element corresponds to. Here, ϵ_i is the measurement error of the i th data point. For example, if $\sigma_B = 100$ nT, equations that involve *Swarm* magnetometer data (sub nT precision) would be weighted by $w_i/(100 \cdot 10^{-9})$, while an Iridium data point with, say, 50 nT error would be weighted by $w_i/(50 \cdot 10^{-9})$.

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Second, the measurements are almost always highly non-uniform. If no correction is applied, we risk that an isolated good data point is overshadowed because of a nearby cluster of data points. Our solution to this problem is to introduce spatial weights w_i , defined as 1 divided by the number of measurements in the grid cell in which the measurement belongs.

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Finally, even with these adjustments to the cost function (Equation (48)), the inverse problem is almost always ill-posed. The reason for this is that the number, type, and distribution of measurements rarely is sufficient to robustly determine \mathbf{m} . This leads to overfitting and large variations in \mathbf{m} for small changes in the measurements. We solve this by adding a priori information to the cost function. Specifically, we (i) add a penalty for large model vectors to ensure relatively smooth spatial structures and (ii) add a penalty for large gradients in m_i in the magnetic eastward direction. The latter is justified by the fact that auroral electrodynamics tends to be aligned in the magnetic east-west direction. However, in the polar cap, poleward of the auroral oval, this constraint may be less suitable. We can control the balance between the two constraints using two regularization parameters λ'_1 and λ'_2 . The total cost function is then:

$$f = (\tilde{\mathbf{y}} - \mathbb{G}\mathbf{m})^\top \mathbb{C} (\tilde{\mathbf{y}} - \mathbb{G}\mathbf{m}) + \lambda'_1 \|\mathbf{m}\|^2 + \lambda'_2 \|\mathbb{D}_{\hat{\mathbf{e}}_m} \cdot \nabla \mathbf{m}\|^2 \quad (49)$$

563 where $\mathbb{D}_{\hat{\mathbf{e}}_m \cdot \nabla}$ is a $K_E \times K_E$ differentiation matrix, as defined in Section 3.1, except that
 564 it gives the gradient in the *magnetic* eastward direction. We seek the model vector \mathbf{m}
 565 that minimizes f . This can be found by solving the equation $\partial f / \partial \mathbf{m} = 0$ for \mathbf{m} . The
 566 solution is:

$$\mathbf{m} = (\mathbb{G}^\top \mathbb{C} \mathbb{G} + \lambda'_1 \mathbb{I} + \lambda'_2 \mathbb{D}_{\hat{\mathbf{e}}_m \cdot \nabla}^\top \mathbb{D}_{\hat{\mathbf{e}}_m \cdot \nabla})^{-1} (\mathbb{G}^\top \mathbb{C} \tilde{\mathbf{y}}), \quad (50)$$

567 where \mathbb{I} is the $K_E \times K_E$ identity matrix. Since the magnitude of the elements in $\mathbb{G}^\top \mathbb{C} \mathbb{G}$
 568 depends on the amount of data, λ'_1 and λ'_2 must be different in different events even with
 569 the same degree of regularization. To make the numbers more comparable between events,
 570 we will instead refer to the unprimed λ_1 and λ_2 , which relate to the primed variables as

$$\lambda'_1 = \alpha_1 \lambda_1, \quad \lambda'_2 = \alpha_2 \lambda_2, \quad (51)$$

571 where α_1 is the median diagonal element of $\mathbb{G}^\top \mathbb{C} \mathbb{G}$, and α_2 is the same number divided
 572 by the median diagonal element of $\mathbb{D}_{\hat{\mathbf{e}}_m \cdot \nabla}^\top \mathbb{D}_{\hat{\mathbf{e}}_m \cdot \nabla}$. This normalization ensures that if λ_1
 573 and λ_2 are 1, the corresponding scaled regularization matrices will have elements that
 574 are of similar magnitude as the diagonal elements in $\mathbb{G}^\top \mathbb{C} \mathbb{G}$. In this paper, we find a suit-
 575 able set of regularization parameters by visual inspection, looking for (approximately)
 576 the smallest possible values that prevent over-fitting. A more unbiased approach would
 577 be preferable, and we will explore different methods in future studies.

578 This regularization technique was also used in the Observing System Simulation
 579 Experiment carried out for the Electrojet Zeeman Imaging Explorer (Laundal et al., 2021),
 580 a NASA mission planned for launch in 2024. We plan to explore alternative methods in
 581 future applications of the Lompe technique. For example, instead of damping variation
 582 in the magnetic east-west direction, more complex spatial structures could be promoted
 583 by changing the regularization matrix accordingly. For example, one could use the spa-
 584 tial structure of empirical models or, as demonstrated by Clayton et al. (2019) with a
 585 different technique, use auroral images to derive the dominant direction of variation.

586 3.4 Solving the current continuity equation

587 Before we present example applications, we mention an alternative use of the ma-
 588 trices described above: Solving the current continuity equation for the electric field, given
 589 a pattern of vertical currents. As mentioned in Section 2, this is a standard way to cou-
 590 ple global MHD simulations of the magnetosphere to the ionosphere. The upward cur-
 591 rent density, from the MHD simulation, is set equal to the negative divergence of the hor-
 592 izontal ionospheric current (Equation (14)), and the resulting equation is solved for the
 593 electric field, which then serves as the inner boundary condition for the magnetosphere
 594 simulation.

595 With the matrices defined above, we can formulate the following matrix equation
 596 relating electric field amplitudes \mathbf{m} and vertical current densities $\tilde{\mathbf{j}}_u$:

$$\tilde{\mathbf{j}}_u = \mathbb{D}_{\nabla} \cdot \left[\begin{pmatrix} \text{diag}(\boldsymbol{\Sigma}_P) \mathbb{E}_e \\ \text{diag}(\boldsymbol{\Sigma}_P) \mathbb{E}_n \end{pmatrix} + \begin{pmatrix} \pm \text{diag}(\boldsymbol{\Sigma}_H) \mathbb{E}_n \\ \mp \text{diag}(\boldsymbol{\Sigma}_H) \mathbb{E}_e \end{pmatrix} \right] \mathbf{m}, \quad (52)$$

597 where, as earlier, the two signs apply to the northern (top) and southern (bottom) hemi-
 598 spheres. The quantity in square brackets, when multiplied by \mathbf{m} , gives the sum of Ped-
 599 ersen and Hall current densities defined on the K_J interior grid points, with the east-
 600 ward components stacked on top of the northward components. The matrix in square
 601 brackets has shape $2K_J \times K_E$. \mathbb{D}_{∇} has shape $K_J \times 2K_J$ as before.

602 In this equation, unlike Equation (46), the data vector on the left hand side, $\tilde{\mathbf{j}}_u$,
 603 does not represent measurements at arbitrary positions, but specifically K_J vertical cur-
 604 rent densities at the internal grid points. In theory, the right hand side could be mul-
 605 tiplied by an appropriate interpolation matrix to relate vertical current densities at ar-
 606 bitrary positions to \mathbf{m} .

In the current form, given a set of vertical currents across the analysis domain, Equation (52) can be inverted to find \mathbf{m} , and thus the electric field. The electric potential, convection velocity, horizontal current densities, and magnetic field disturbances at any altitude can then be calculated from the equations presented earlier in this section. Below we demonstrate this with field-aligned current densities from an MHD simulation. AMPERE field-aligned currents can also be used as input for this procedure, as recently demonstrated by Robinson et al. (2021) and Chartier et al. (2022), using two different techniques.

3.5 Note about coordinate systems

In our implementation of the Lompe technique we use geographic coordinates by default. This is because geographic coordinates are orthogonal, unlike some magnetic coordinate systems (Laundal & Richmond, 2017), and therefore easier to work with. This choice also avoids ambiguities related to secular variations in the magnetic field, and confusion about which type of magnetic coordinate systems is used. The apexpy Python module (van der Meer et al., 2021; Emmert et al., 2010) is used to find the magnetic eastward direction in Quasi-Dipole coordinates (Richmond, 1995), which we use to calculate $\mathbb{D}_{\hat{\mathbf{e}}_m}$ in Equation (50). Our code also has an option to make all calculations in centered dipole coordinates, which is convenient in some cases, like the examples shown in Section 4.1 which are based on synthetic data from simulations performed with a dipole magnetic field.

4 Results

In this section we present a set of example applications of the Lompe technique. First we demonstrate the technique with synthetic data based on a magnetohydrodynamic simulation (Section 4.1). We also use the simulation output to give an example of how boundary effects influence the inversion. Then we present three examples with real data: In Section 4.2 we show an example using Iridium, SuperMAG, and SuperDARN data in a large grid that covers North America, with auroral conductance specified using a relatively simple empirical model. In Section 4.3 we show an example with conductance based on auroral imaging, but with no Iridium magnetometer data. In Section 4.4, we zoom in on a region with good coverage by SuperDARN. In all the examples with real data, we include measurements within a grid extended by 10 grid cells in each direction. Data further away would have very little influence due to the sharp decrease of the SECS functions (Equation (1)).

4.1 Synthetic test

Here we present an example of applying the Lompe technique with synthetic simulated data, which means that we have perfect coverage and no uncertainty in the input, and we know what the output should be. To produce the synthetic data, we simulate the magnetospheric response to a solar wind pressure increase using the the Grid Agnostic MHD for Extended Research Applications (GAMERA) code (B. Zhang et al., 2019; Sorathia et al., 2020). For our purposes, the specifics of the simulation is not very important, except that some structure in the ionospheric electrodynamics is preferred. The important point is that all the different quantities are consistently related. GAMERA ionospheric electric field and currents are calculated as described in Section 3.4, but with a different numerical scheme than used in the Lompe technique (Merkin & Lyon, 2010).

Figure 4 shows the GAMERA output in the first column, shown on a cubed sphere projection. The top row shows electric potential (black contours), and Pedersen conductance in color. The Hall conductance is similar, but not shown. The next rows show, from

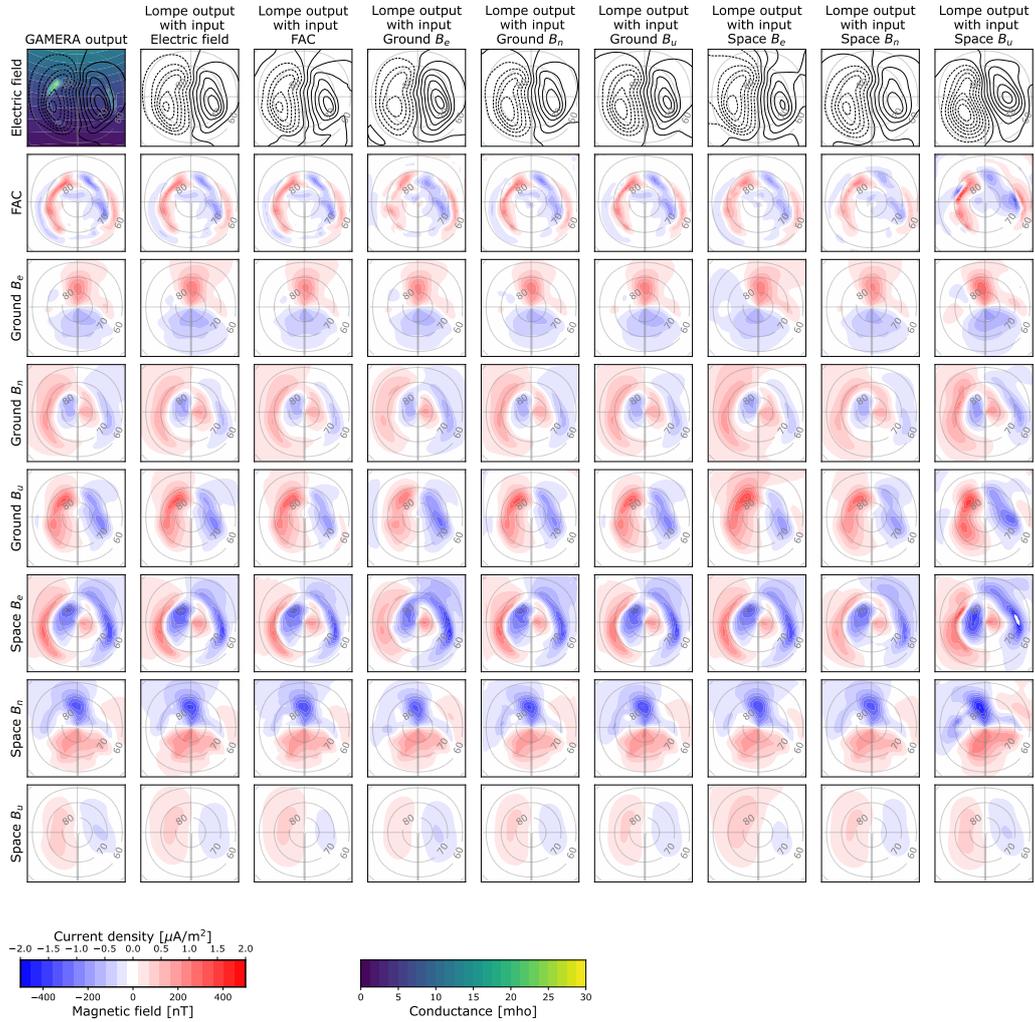


Figure 4. Results of Lompe inversions with synthetic data. The synthetic data comes from GAMERA MHD simulations, and the output is shown in the left column. Each row shows one quantity, indicated to the left. All plots, except for the left column, show Lompe inversion outputs. The eight rows correspond to eight different inputs to the inversion, indicated above the top row. The inversion result can be assessed by comparing the plots to the left column with GAMERA output, which can be considered to be the ground truth in this experiment.

655 top to bottom, the field-aligned current, the eastward, northward, and upward compo-
 656 nents of the magnetic field disturbances on ground, and the eastward, northward, and
 657 upward components of the magnetic field disturbances at an altitude of 1000 km, well
 658 above the horizontal current layer which is placed at 120 km. Except for the first col-
 659 umn, all plots show Lompe output, when the input is the parameter indicated at the top.
 660 For example, the plot in the fifth column, second row, shows the Lompe field-aligned cur-
 661 rent density when the northward magnetic field on ground is the only input to the in-
 662 version. Comparing this to the first column, which is the “ground truth” in this case,
 663 we see that it is faithfully reproduced.

664 In Figure 4, the regularization parameters are zero when the input is electric po-
 665 tential and field-aligned current. That is, the solution is just a minimization of the least-
 666 squares difference between input and model output. For the other columns, where the
 667 input is magnetic field components, we used $\lambda_1 = 0.1$ and $\lambda_2 = 0$ in Equation (50).
 668 With $\lambda_1 = 0$, all parameters except for the input were not well represented. The need
 669 for a tiny damping parameter shows that there are many electric fields which, given the
 670 conductance pattern, can produce the same pattern of magnetic field disturbances. That
 671 is, the inverse problem is ill-posed even with perfect data.

672 Figure 5 has the same format and the same simulated input data as in Figure 4,
 673 but a smaller analysis region. We have zoomed in on a region that contains the spot with
 674 high conductance in the post-noon local time sector. We see that in general the retrieved
 675 patterns are similar to the original input data, but with some clear deviations. For ex-
 676 ample, the Lompe output FAC for magnetic field input has features at the boundary of
 677 the analysis region which are wrong. This result is expected: The magnetic field is a func-
 678 tion of the global current system, not only the current within the analysis region; when
 679 we seek a current that is represented by spherical elementary current systems entirely
 680 within the analysis region, artificial edge structures emerge to account for remote cur-
 681 rents. There is not much we can do about this except to be careful in the interpretation
 682 of the output patterns, unless we can add more information to constrain the electric field.
 683 The overall good fit in the interior region is encouraging, and shows that the Lompe out-
 684 put is useful if handled with some care. We discuss edge effects in more detail in Sec-
 685 tion 5.

686 In the rightmost columns of Figures 4 and 5, the input is the vertical magnetic field
 687 disturbances at 1000 km altitude. In both figures, the Lompe output in this column is
 688 particularly poor compared to the other columns. Since the Lompe technique assumes
 689 a vertical main field, the vertical magnetic field disturbances are not linked to FACs (Equa-
 690 tion (9)), but solely to divergence-free currents 880 km below (Equation (12)). At this
 691 distance, small-scale structures in the ionospheric shell at 120 km contribute very little
 692 to the magnetic field. This is likely the reason for the notable deviations seen in the right
 693 columns. In the Lompe code (Laundal et al., 2022), there is an option to use space mag-
 694 netometer data only to constrain FACs, intended for use with satellites at relatively high
 695 orbit and/or with relatively imprecise measurements.

696 4.2 North America grid with Hardy model conductance

697 Figure 6 shows an example of the Lompe technique applied with real data. The
 698 analysis region covers much of North America and Greenland. Its extent is shown in black
 699 in Figure 1 in geographic coordinates, and in the top right panel of Figure 6 in magnetic
 700 apex coordinates (Richmond, 1995). The grid cell dimension is 100×100 km in the cen-
 701 ter and slightly larger towards the edges due to the cubed sphere projection.

702 The input data to the Lompe inversion in this example are SuperDARN line-of-
 703 sight convection measurements (Chisham et al., 2007), Iridium magnetometer measure-
 704 ments provided via AMPERE (Anderson et al., 2000; Waters et al., 2020), and ground
 705 magnetometer data provided via SuperMAG (Gjerloev, 2012). All data are from the four

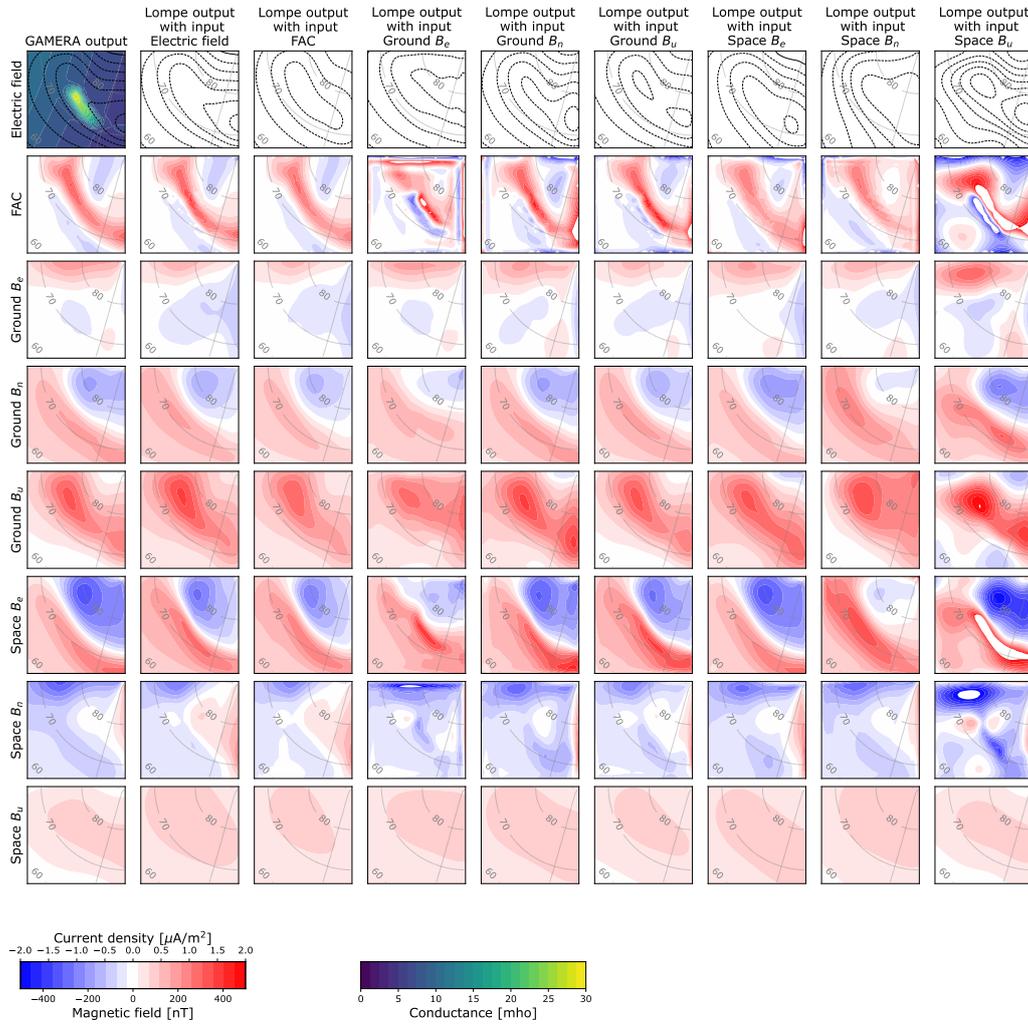


Figure 5. Results of Lompe inversions with synthetic data. The format and simulation data is the same as in Figure 4, except that this figure is based on input from, and shows output from, a much smaller region.

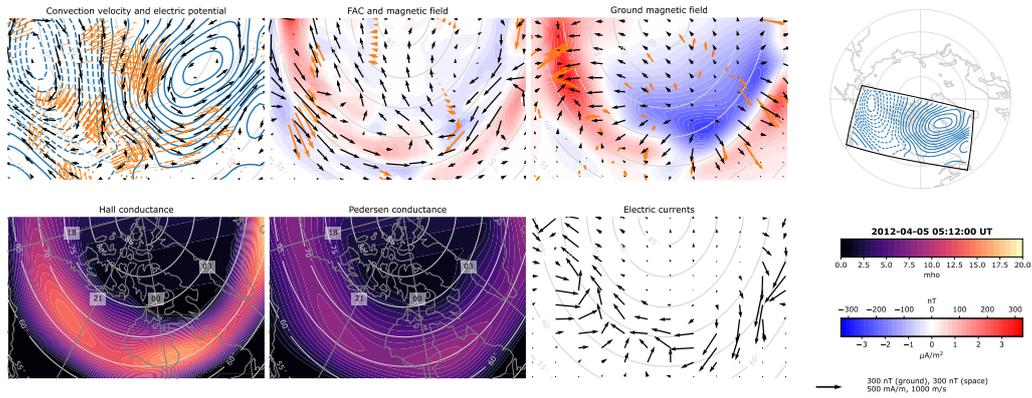


Figure 6. Lompe input and output for a 4 min time period centered at 5 April 2012 05:12 UT. The top row shows, from left to right: Convection flow field (SuperDARN line-of-sight measurements in orange) and electric potential contours; horizontal magnetic field disturbances 110 km above the ionosphere as black arrows and radial current density as color contours (Iridium horizontal magnetic field measurements in orange); horizontal ground magnetic field perturbations as black arrows and radial magnetic field perturbations as color contours (SuperMAG horizontal magnetic field perturbations as orange arrows); and a map that shows the grid’s position and orientation with respect to apex magnetic latitude and local time. The bold grid edge corresponds to the lower edge of the projections shown in the other plots. The bottom row shows, from left to right: Pedersen conductance; Hall conductance; horizontal height-integrated ionospheric currents based on Lompe output; and color scale / vector scales.

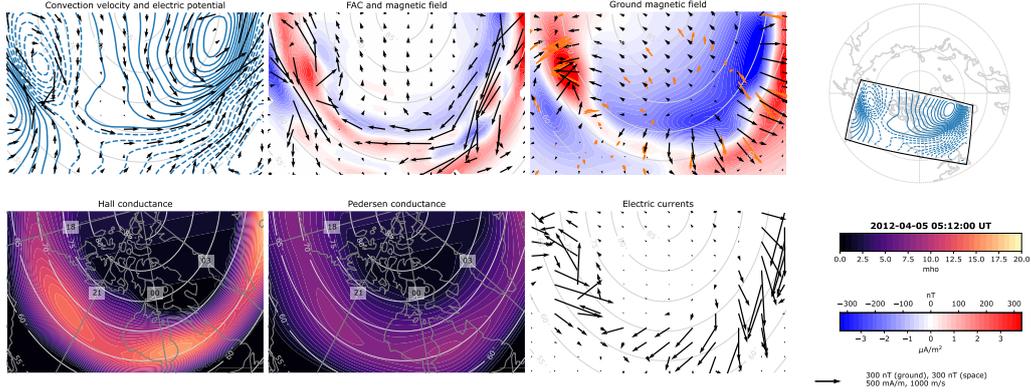


Figure 7. Same as Figure 6, except that we only use ground magnetometer data in the inversion.

706 minutes starting at 05:12 UT on 5 April 2012. The input data are shown as orange vec-
 707 tors in the three top left panels, except for the vertical component of the ground mag-
 708 netic field. The data are related to the electric field via the equations described in Sec-
 709 tions 2 and 3 and the conductance maps shown in the bottom left panels. The conduc-
 710 tances are a combination of auroral and EUV contributions; the EUV contribution is cal-
 711 culated as described in Section 2.4, and the auroral contribution is calculated with the
 712 relatively crude Hardy et al. (1987) empirical model with $K_p = 4$. The ionosphere is
 713 placed at 110 km altitude in this and the following examples.

714 The model parameters \mathbf{m} were found from Equation (50) with $\lambda_1 = 1$ and $\lambda_2 = 10$.
 715 The corresponding convection pattern and electric potential are shown in the top left
 716 panel, together with the input data, all in a reference frame that rotates with the Earth.
 717 The black arrows in the next panel show the magnetic field in space, 110 km *above* the
 718 ionosphere, and the color contours show the vertical current density. The third panel from
 719 the left shows the ground magnetic field disturbances horizontal components as black
 720 vectors and vertical component as color contours. The panel below shows the horizon-
 721 tal height-integrated ionospheric currents.

722 We see that the inversion yields the night-side portion of a two-cell convection pat-
 723 tern with the dusk cell slightly wrapped around the dawn cell, so that plasma that leaves
 724 the polar cap on the dusk cell goes south-east and then west. This is the Harang rever-
 725 sal (Harang, 1946). Looking at the data (orange arrows), we see that the reversal in con-
 726 vection pattern has observational support. Beyond this qualitative statement, it is chal-
 727 lenging to compare the input to the output in the convection map since the input is only
 728 in the line-of-sight direction. The field-aligned current map is dominated by Region 1
 729 and Region 2 currents as defined by Iijima & Potemra (1978), but some finer-scale struc-
 730 tures are seen near the Harang reversal region. The radial magnetic field disturbance on
 731 ground is smooth and large-scale. The horizontal field exhibits sharp reversals in the left
 732 part of the map, which is seen in both the data and the inversion output.

733 To elucidate the effect of combining datasets in Figure 6, we show a contrasting
 734 example in Figure 7, where we have used the same setup as in Figure 6, but removed Su-
 735 perDARN and Iridium data. The inversion in this figure is based only on ground mag-
 736 netometer data, and is thus similar to the KRM technique (Kamide et al., 1981; Van-
 737 hamäki & Amm, 2007). We see that the dawn cell structure is largely similar, but the

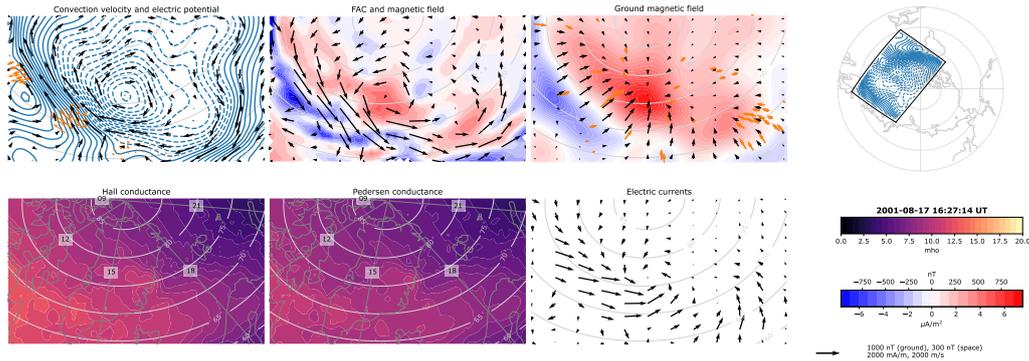


Figure 8. Lompe inversion results from 17 August 2001, using data from a four min interval starting at 16:27:14 UT. This was two min before a WIC image was taken, which we use to estimate auroral conductance. The format of this figure is the same as for Figure 6.

738 convection is stronger in the KRM version. The most striking difference between the fig-
 739 ures is in the Harang reversal region, which is not well resolved with ground magnetome-
 740 ter data alone. We note again that the Hardy et al. (1987) auroral conductance model
 741 is crude, and that a better conductance estimate would improve the inversion results in
 742 both cases.

743 4.3 A High-Latitude Dayside Aurora event

744 Figure 8 shows an example of the Lompe technique used with SuperMAG ground
 745 magnetic field data and SuperDARN line-of-sight convection measurements taken dur-
 746 ing a 4 min interval starting at 16:27 UT 17 August 2001. In this example the auroral
 747 conductances were estimated based on a UV image of the aurora, taken by the Wide-
 748 band Imaging Camera (WIC) (Mende et al., 2000) on the Imager for Magnetopause-to-
 749 Aurora Global Exploration (IMAGE) satellite (Burch, 2000). The full auroral image is
 750 shown in Figure 9. We have removed contamination from sunlight using a model that
 751 is based on viewing geometry (Ohma et al., 2018). The corrected WIC intensity was con-
 752 verted to energy flux via relationships presented by Frey et al. (2003), assuming an av-
 753 erage electron energy of 2.56 keV, and no contribution from protons. The estimated en-
 754 ergy flux and assumed average energy were then used in the Robinson et al. (1987) for-
 755 mulae to obtain Hall and Pedersen conductances. Our assumed average energy, which
 756 is close to that observed in particle measurements by a nearby DMSP satellite, gives a
 757 Hall-to-Pedersen ratio of 1. This method, despite large uncertainties, presumably yields
 758 much better representations of the auroral conductance and its gradients than the Hardy
 759 et al. (1987) model used in the example in Section 4.2. The solar EUV-induced conduc-
 760 tance was added using the method described in Section 2.4. The result, displayed in Fig-
 761 ure 8, show that the EUV conductance dominates. The Lompe inversion was done with
 762 data taken ± 2 min relative to the time of the WIC image. In this inversion, $\lambda_1 = 1$ and
 763 $\lambda_2 = 10$ in Equation (50). The grid cells in the center are 75×75 km.

764 The Challenging Mini-satellite Payload (CHAMP) satellite passed over the anal-
 765 ysis region at about 440 km altitude during the same time interval (green line in Fig-
 766 ure 9, left). CHAMP carried a very accurate fluxgate magnetometer (Rother & Michaelis,
 767 2019), and its 1 Hz measurements of the eastward, northward, and upward components
 768 of the magnetic field, with the main magnetic field (Alken et al., 2021) subtracted, are
 769 shown as solid lines in Figure 9 (right). The Lompe magnetic field, evaluated at the same

positions as the CHAMP measurements, is shown as dashed lines. Although it would have been possible to include it (see Section 3.2.4), the CHAMP data was not used in the Lompe inversion. The good match demonstrates that the combination of ground magnetometer measurements, SuperDARN radar measurements, and reasonable conductance estimates, is sufficient to retrieve the magnetic field in space. Notice also that the steep decrease in the eastward magnetic field after it peaks matches well between CHAMP measurements and Lompe estimates. This is the very strong ($\approx 7 \mu\text{A}/\text{m}^2$) downward field-aligned current which appears as a blue strip in Figure 8.

The data analyzed in this example is part of an event that was analyzed in detail by both Longley et al. (2016) and Østgaard et al. (2018). They conclude that the spot in the middle of the analysis region, which was present for several hours, is a so-called High-Latitude Dayside Aurora (HiLDA), (Frey, 2007). Recently Q.-H. Zhang et al. (2021) presented detailed images of what was presumably a HiLDA spot, and coined the term *space hurricane* since the spot had spiral arms like atmospheric hurricanes. The HiLDA spot / space hurricane is clearly visible in the WIC image displayed in Figure 9. It is a signature of lobe reconnection during times when the interplanetary magnetic field has a strong positive B_y component (or negative, if observed in the Southern hemisphere) (Reistad et al., 2021).

Østgaard et al. (2018) also sketched a convection pattern for this event based on a qualitative assessment of the available data and knowledge about statistical models. In agreement with our results, they suggested that ionospheric plasma circles clockwise around the auroral spot when viewed from above. Also in agreement with our results, they suggested that the polar cap plasma enters the auroral oval at around 18–21 magnetic local time (MLT), signifying closure of magnetic flux via tail reconnection in this region (e.g., Laundal, Østgaard, Snekvik, & Frey, 2010). However, Figure 8 also refines the pattern suggested by Østgaard et al. (2018), and reveals some unexpected features: On the night side of the spot, the convection is strongly reduced, and the polar cap plasma appears to go quite far towards dawn before turning back towards dusk, circling a large region of almost stagnant plasma. In addition to this, the Lompe results show much more channeled flows than suggested in the sketch by Østgaard et al. (2018): On the dayside, Lompe estimates reach flows of about 2000 m/s, presumably driven by a combination of dayside and lobe reconnection. Return flows near 18 MLT reach almost the same level.

The Lompe inversion allows us to calculate the frictional heating rate from ions colliding with neutrals, often misleadingly referred to as Joule heating (Vasyliunas & Song, 2005). When the ionospheric Ohm’s law is valid (see discussion of Equation (4)) the heating rate is $W = \mathbf{E} \cdot \mathbf{J}$. Integrated over the analysis region, we find that it was more than 400 GW in this event. Most of this heating rate is concentrated in the convection channel just equatorward of the space hurricane. It is three times the maximum *global* heating rate reported by Weimer (2005) for average conditions with an IMF magnitude of 5 nT and solar wind velocity of 450 m/s. The Average Magnetic field and Polar current System (AMPS) model, presented by Laundal et al. (2018), shows that the strongest horizontal ionospheric currents occur near the dayside during conditions that are favorable for the space hurricane to occur. The AMPS model output and the strong heating rate reported here emphasize the importance of dayside dynamics in the total energy budget for magnetosphere-ionosphere coupling.

4.4 A zoomed-in view with convection input during quiet conditions

Figure 10 shows the Lompe output on the same format as Figures 6–8 from an event on December 15 2014, at 01:19 UT. The purpose of displaying this event is to further demonstrate the ability to resolve mesoscale structures of the ionospheric electrodynamics in a limited spatial region when only line-of-sight convection measurements and precipitation characteristics are present, during typical quiet conditions. The grid used in

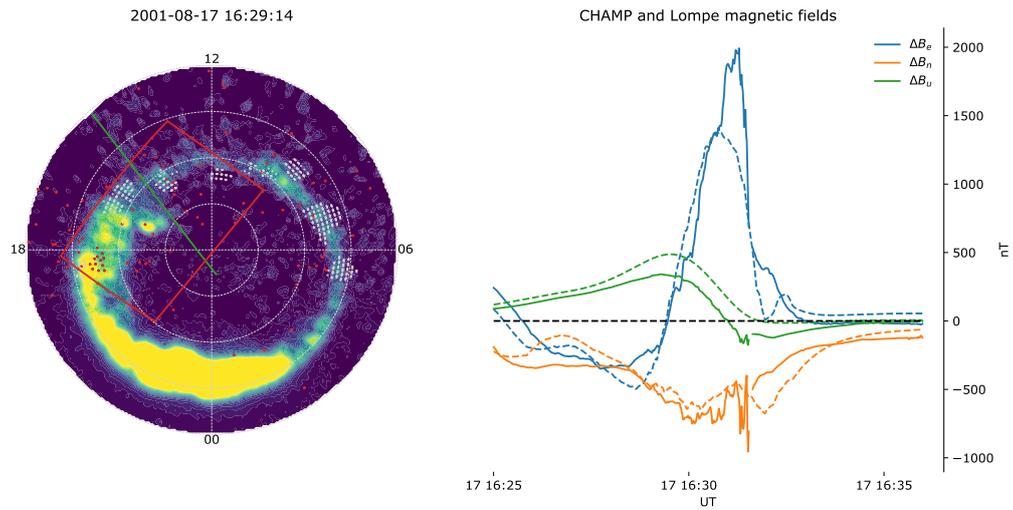


Figure 9. Left: The IMAGE WIC image used to estimate auroral conductance for the Lompe inversion discussed in Section 4.3 and displayed in Figure 8. The red dots show SuperMAG magnetometers, and grey dots show SuperDARN backscatter locations during the four min interval used in the inversion. The red frame shows the analysis region used in the Lompe inversion, and the green line shows the trajectory of the CHAMP satellite in a 10 min interval around the time of our analysis. Right: The magnetic field components measured by CHAMP (with the IGRF main magnetic field subtracted), as solid lines. The dashed lines show the Lompe magnetic field evaluated at the same coordinates. The CHAMP data was not used as input in the Lompe inversion.

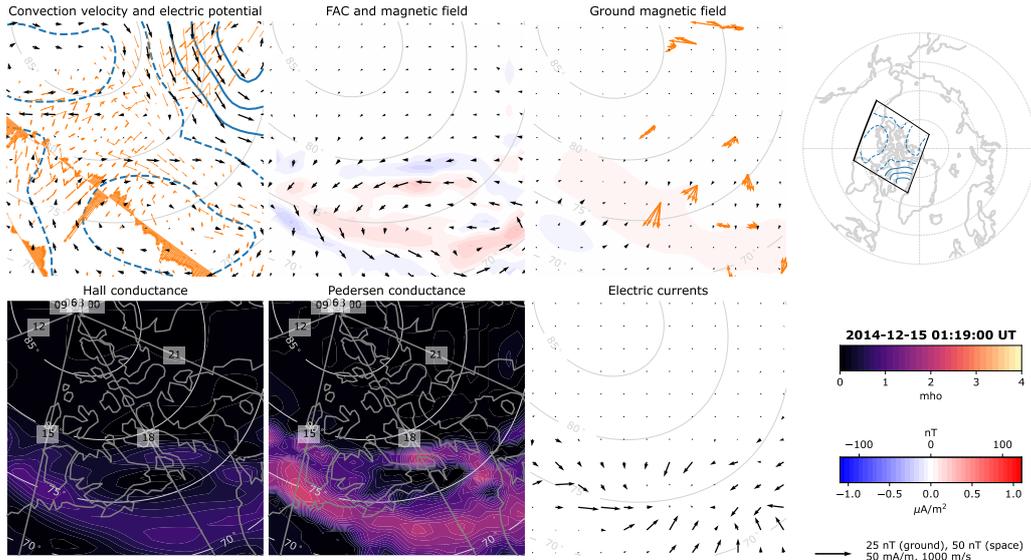


Figure 10. Event on December 15 2014, at 01:19 UT during quiet conditions and northward IMF. Here Lompe is used on a grid covering a region with good convection data coverage on the dusk side of the polar cap and auroral oval. The figure is on the same format as Figures 6–8. Conductance is estimated from simultaneous SSUSI LBHs emissions. Note the different magnitudes of the color scales and reference arrows compared to the previous test cases.

821 Figure 10 has a resolution of 70 km in the horizontal directions and spans a region of
 822 about 2500 km \times 2500 km. The conductance needed for the Lompe inversion is derived
 823 from the observed UV brightness of Lyman-Birge-Hopfield short (LBHs) wavelength (140–
 824 160 nm) emissions from the Special Sensor Ultraviolet Spectrographic Imager (SSUSI)
 825 (Paxton et al., 1992) on-board the DMSP F18 satellite. As in the previous example using
 826 global FUV imaging, we assume a characteristic energy of the electron precipitation
 827 in the analysis region. Based on particle data from the in situ Special Sensor J (SSJ) in-
 828 strument on DMSP F18, we find that a characteristic electron energy of 1 keV is rep-
 829 resentative. Further, using the estimated energy fluxes provided in the SSUSI Environ-
 830 mental Data Record Aurora files in regions of > 500 R LBHs brightness within the grid,
 831 we find that a conversion factor of 472 R/(mWm $^{-2}$) can be used as a crude conversion
 832 from the LBHs irradiances to electron energy flux. From the estimated electron char-
 833 acteristic energy and energy flux, we use the empirical relationships presented by Robin-
 834 son et al. (1987) to estimate Hall and Pedersen conductances. The median filtered binned
 835 averaged conductances based on SSUSI LBHs irradiances on the Lompe grid is seen in
 836 the two bottom panels in Figure 10. Note the difference in color scale compared to the
 837 previous examples. Furthermore, the EUV induced solar conductance is very low through-
 838 out the entire analysis region.

839 SuperDARN gridded line-of-sight measurements from the interval 01:17–01:21 UT
 840 are used in the inversion. In addition, cross track ion drift measurements from the Spe-
 841 cial Sensor for Ions and Electrons and Scintillation (SSIES) instrument on simultane-
 842 ous DMSP F17 and F18 passes are included, seen as orange stripes in the upper left panel
 843 in Figure 10. To obtain data across the entire analysis grid, DMSP data from the time
 844 interval 01:16–01:22 UT is used. This is the same time interval used to sample the LBHs

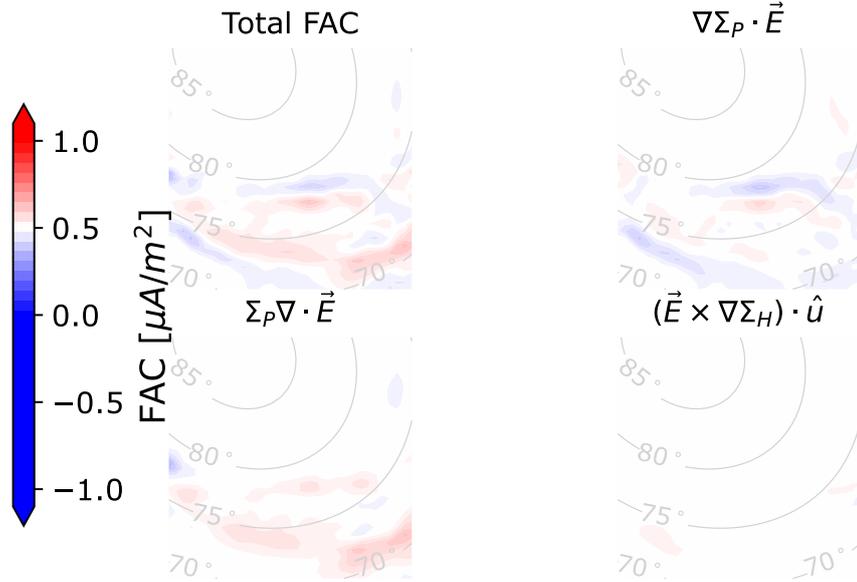


Figure 11. Separation of the three terms contributing to the field-aligned currents in Equation (14). The upper left panel is the same as the FAC panel in Figure 10.

845 emissions by SSUSI. We here use the same regularization parameters in the inversion as
 846 used in the above events, namely $\lambda_1 = 1$ and $\lambda_2 = 10$. On the western edge of the grid
 847 we see convection towards the dayside inside the polar cap. The IMF B_z is positive (and
 848 small positive IMF B_y) at the time of the observations, after a northward turning at around
 849 00:55 UT. We therefore suggest that the clockwise plasma circulation seen in the top left
 850 corner of the top left panel in Figure 10 is part of the dawn lobe cell. Sunward return
 851 flow within the oval at around 18 MLT is also seen, and anti-sunward convection pole-
 852 ward of the oval at the same local time.

853 The ionospheric currents and their associated perturbations in space and on ground,
 854 as estimated with the Lompe technique, are fairly weak due to the modest conductance
 855 values. Although not used in the inversion, ground magnetometer observations are il-
 856 lustrated in the third panel in the top row in Figure 10. It can be seen that the Lompe
 857 estimates of $\Delta \mathbf{B}$ on ground are much smaller than what is observed. This could be an
 858 effect of ground observatories being sensitive to disturbances from sources outside the
 859 analysis grid. This will be discussed in more detail in Section 5. It is also possible that
 860 our crude conductance estimates are too low. However, such an offset would largely af-
 861 fect the magnitude of the perturbations and not their spatial variation.

862 One advantage with the Lompe representation of the regional ionospheric electro-
 863 dynamics is the ability to separate the different terms in Equation (14) contributing to
 864 the field-aligned currents. This decomposition is shown in Figure 11, showing how the
 865 three terms contribute to the total FAC. We can see that the main contributor is the term
 866 associated with the $\Sigma_P \nabla \cdot \mathbf{E}$ term, which is proportional with the Pedersen conductance
 867 and with the divergence of \mathbf{E} , or equivalently, using Equation (2), the flow vorticity. This
 868 is normally the dominating term in Equation (14) (e.g. Chisham et al., 2009; Reistad,
 869 Laundal, Østgaard, Ohma, Haaland, et al., 2019). However, significant contributions es-
 870 pecially to the downward currents (blue) is linked to Pedersen currents that flow across

871 gradients in Σ_P . The third term, which describes the divergence of Hall currents as they
 872 flow across gradients in Σ_H is small in this case. This separation may be relevant to get
 873 further insights into the what controls the morphology of the ionospheric current sys-
 874 tem. We emphasize that a realistic conductance must be provided to perform a reliable
 875 decomposition of the FACs.

876 5 Discussion

877 We have presented a new method for ionospheric data assimilation, combining dif-
 878 ferent types of measurements via the ionospheric Ohm's law. The output of the method
 879 is a complete picture of ionospheric electrodynamics in an analysis region with flexible
 880 extent and spatial resolution. This technique for local mapping of polar ionospheric elec-
 881 trodynamics (Lompe) uses SECS as a basis. The short reach of these functions makes
 882 the Lompe technique potentially more suitable for regional analyses than existing tech-
 883 niques like AMIE. However, by choosing the analysis region large enough, as in the ex-
 884 ample shown in Figure 4, the Lompe technique can be seen as equivalent with AMIE,
 885 except with different basis functions. If we use only ground magnetometers as input, the
 886 Lompe technique is equivalent with the KRM technique (Kamide et al., 1981; Vanhamäki
 887 & Amm, 2007); and, if we use only ionospheric convection measurements as input, it is
 888 equivalent with the SECS analysis presented by Reistad, Laundal, Østgaard, Ohma, Haa-
 889 land, et al. (2019), and almost equivalent with both the SECS analysis presented by Amm
 890 et al. (2010) and the Local Divergence-Free Fitting technique by Bristow et al. (2016).

891 We foresee that the main use case of the Lompe technique will be to produce maps
 892 of ionospheric electrodynamics in regions where the data density is high. We have shown
 893 two different examples from North America where we used grids with 100 and 75 km res-
 894 olution. It is likely that high data density in certain regions in North America and Fennoscand-
 895 ia could support analyses with even higher resolutions. Analyses in regions with high
 896 data density could resolve ionospheric dynamics at higher time resolutions than what
 897 is possible globally. This could help us understand the time-dependent ionospheric re-
 898 sponse to changes in the solar wind and the magnetosphere. For example, we know that
 899 substorms excite ionospheric convection (Grocott et al., 2009; Provan et al., 2004), but
 900 we do not know how fast it happens, or how the flow is organized with respect to the
 901 substorm bulge (e.g., Laundal, Østgaard, Frey, & Weygand, 2010). Understanding this
 902 coupling could also help us to understand how the ionospheric reaction may alter the im-
 903 posed flows and influence magnetospheric dynamics (e.g., Lotko et al., 2014; Elhawary
 904 et al., 2021). Furthermore, as demonstrated in Section 4.3, the Lompe technique can be
 905 used to estimate frictional heating rates, which is an important driver of dynamics in the
 906 upper atmosphere (e.g., Ridley et al., 2006).

907 The Lompe technique could also be useful to increase the utility of certain mea-
 908 surement instruments, such as phased array incoherent scatter radars. For example the
 909 EISCAT3D radar system (McCrea et al., 2015), which will be operational soon, will give
 910 ion flow measurements and ionospheric density in a volume above the field of view of the
 911 measurement sites. The ion flow measurements from the F region can be used to derive
 912 the electric field, and the plasma density can be used to derive conductances. Combin-
 913 ing this with data from surrounding magnetometer measurements with the Lompe tech-
 914 nique can yield a more detailed view of the dynamics. Another example is the upcom-
 915 ing EZIE satellites, which will scan the magnetic field disturbances in the mesosphere
 916 as the satellites move. EZIE alone gives the equivalent divergence-free current (Laun-
 917 dal et al., 2021), and the Lompe technique can be used to combine EZIE data with other
 918 data sources to find the convection and field-aligned currents. Yet another use case could
 919 be for theoretical analyses and interpretations.

920 The Lompe technique uses a grid that is regular in a cubed-sphere projection (Ronchi
 921 et al., 1996). The grid can have arbitrary resolution, and arbitrary extent up to a point;

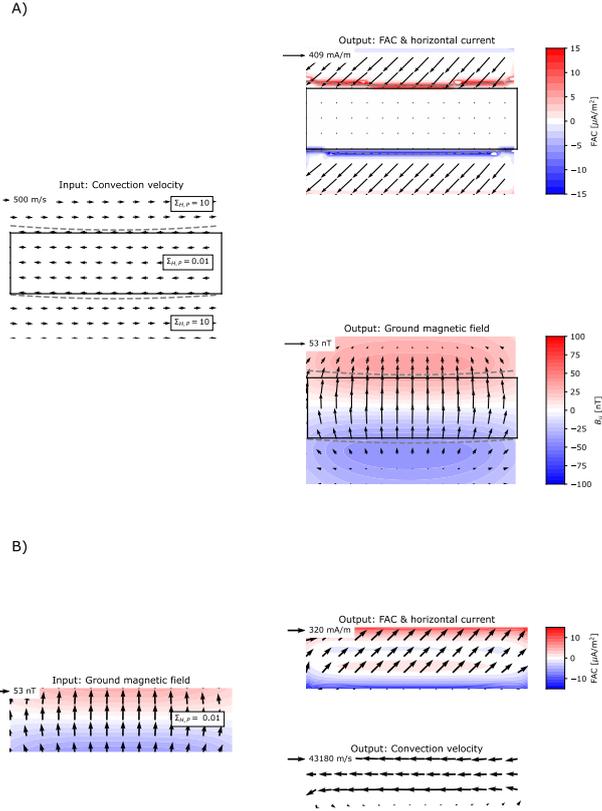


Figure 12. Two theoretical examples of how the Lompe inversion can give misleading results. A) The input (left) is a flow field that is eastward except for in a confined latitude band (dashed gray lines) where it is westward. The conductance is 10 mho outside and 0.01 mho inside the band. The right plots show the current and ground magnetic field implied by Lompe inversion results. B) The analysis region is the rectangle indicated in A, and the input is the magnetic field from A (shown to the left). The right plots show current densities and flow field implied by the Lompe inversion.

922 our implementation currently only uses one face of a cube that circumscribes the Earth.
 923 However, we have limited freedom beyond this, unlike some earlier studies using SECS,
 924 where the nodes have been placed on an irregular grid (e.g., Weygand et al., 2011). This
 925 is not an option in our analysis, since the differentiation matrices $\mathbb{D}_{\mathbf{e},\nabla}$, $\mathbb{D}_{\mathbf{n},\nabla}$, and \mathbb{D}_{∇} .
 926 require regular grids.

927 The matrix equations presented in Section 3 essentially transform partial differ-
 928 ential equations to algebraic equations (Vanhamäki & Juusola, 2020), which are solved
 929 by inversion. The partial differential equations are solved for \mathbf{E} via the SECS amplitudes
 930 \mathbf{m} . Since we do not know how \mathbf{E} varies on the boundary, we would not be able to find
 931 it via a boundary value problem. Instead, we use the data and a priori information to
 932 constrain the solution. We seek an electric field that fits the data, *and* which has a cer-
 933 tain structure which we impose by regularization; the electric field should be relatively
 934 smooth, especially in the magnetic east-west direction. This information is not always
 935 sufficient to give meaningful results, however.

936 Figure 12 shows two examples to give some intuition for potential pitfalls when ap-
 937 plying the Lompe technique. The left panel of Figure 12A shows an idealized input: An
 938 eastward flow field of 500 m/s everywhere except in a confined latitude band, indicated
 939 by dashed gray lines, where the flow field is 500 m/s in the westward direction. The con-
 940 ductance in the outer and inner regions is 10 mho and 0.01 mho, respectively. The cur-
 941 rent density and ground magnetic field implied by the Lompe inversion is shown to the
 942 right. The current density is as expected everywhere except at the boundary of the anal-
 943 ysis domain where we see (relatively weak) field-aligned currents that are not consistent
 944 with uniform convection and conductance. These FACs reflect electric field SECS am-
 945 plitudes that are needed to produce a uniform flow field in the inner region. It shows that
 946 one should be careful when interpreting the current densities near the boundaries of the
 947 analysis domain. The magnetic field perturbations shown in the panel below emphasize
 948 this point. They represent the magnetic field of *only* the currents that are in the anal-
 949 ysis region. We would expect that, if the given flow field continued to be uniform in the
 950 east-west direction, the magnetic field perturbations only varied in the north-south di-
 951 rection. Instead, we see that the magnetic field changes towards the edges. This is be-
 952 cause currents outside the domain are not accounted for.

953 Figure 12B illustrates how using the magnetic field as input can lead to wrong re-
 954 sults. Here our analysis region is confined to the rectangles in Figure 12A, where the con-
 955 ductance is low. Our input is the ground magnetic field in the output of Figure 12A. This
 956 magnetic field was mostly associated with currents in the high conductance surround-
 957 ing region. Since we do not include that region in this analysis, the Lompe technique gives
 958 electric fields that are strong enough that currents inside the domain can explain the mag-
 959 netic field perturbations. We see to the right that the current and flow field is completely
 960 wrong compared to the situation in Figure 12A. The flow field is two orders of magni-
 961 tude too large. A realistic situation in which this could happen is if the analysis is con-
 962 fined to the dark polar cap, where the conductivity is extremely low due to the absence
 963 of sunlight and ionizing particle precipitation. Any non-zero magnetic field perturbation
 964 there must be associated with currents that are outside the analysis region. The Lompe
 965 technique would account for the magnetic field perturbations by amplifying the electric
 966 field to unrealistic levels. The problem can be reduced by increasing the size of the anal-
 967 ysis region, and by using more data sources.

968 The latter example illustrates that the error can become quite large. The uncer-
 969 tainty in the Lompe estimates depends on the distribution of the data, measurement er-
 970 ror, and on how the data is related to electric field amplitudes via the ionospheric Ohm's
 971 law. That means that the model error also depends on errors in the conductance, vari-
 972 ations in the neutral wind (which we assume is zero), and the method by which unmod-
 973 eled contributions to the measurements have been accounted for (e.g., contributions to
 974 the magnetic field from magnetospheric sources, the main magnetic field, or ground in-
 975 duction effects). In addition, regularization bias complicates the interpretation of model
 976 variance in terms of uncertainty (Aster et al., 2013). Quantifying the error is thus non-
 977 trivial, and something that we plan to return to in later development of the technique.
 978 It is likely that a Bayesian approach to the inversion would be fruitful in this respect,
 979 since it results in a distribution of solutions instead of one fixed vector \mathbf{m} .

980 A Bayesian approach could also help stabilize the solution in consecutive time steps.
 981 The later time step would be described by a probability distribution of model vectors,
 982 given any new data and a priori information which includes the model probability dis-
 983 tribution from the previous time step. A dependence on the previous time step could also
 984 be implemented with the current inversion scheme by adding a term to the cost func-
 985 tion f (Equation (49)) that penalizes deviations from a prior model. Another potentially
 986 time-stabilizing addition could be to link the conductance to the FAC of the previous
 987 time step; MHD simulations often use the Knight (1973) relation and Robinson et al.
 988 (1987) formulae to estimate how an upward current, carried by downward electrons, trans-

lates to auroral conductance. Another compelling solution is to co-estimate the electric field amplitudes and conductances in one single inversion. This, however, is a non-linear problem that requires a considerable change in how the inverse problem is solved.

The Lompe technique, as described in this paper, has been implemented in Python, and the code is available on Zenodo (Laundal et al., 2022). The inversion code includes tools for working with spherical elementary current systems and their magnetic fields, and a module for working with cubed sphere grids (Ronchi et al., 1996). In addition the repository includes tools to treat SuperDARN, SuperMAG, and AMPERE’s Iridium magnetometer data; visualization tools; a pure Python forward code for calculating International Geomagnetic Reference Field (IGRF) values; a Python implementation of the Hardy et al. (1987) auroral conductance model; functions that calculate the EUV produced conductance as described in Section 2.4; and Jupyter notebooks which serve as examples of how to use the code. All of the figures in this paper except Figure 2 are outputs from notebooks that can be found in the same code repository.

6 Conclusions

We have presented a new technique, called Lompe (Local mapping of polar ionospheric electrodynamics), to combine different types of measurements to yield a complete picture of ionospheric electrodynamics in a limited region. The technique combines magnetic field and convection measurements via the ionospheric Ohm’s law. The technical implementation is based on spherical elementary current systems (Amm, 1997). Example applications presented in this paper show that the Lompe technique can be used to give a better understanding of the dynamics than what can be achieved with any individual data set alone. The Lompe technique is conceptually similar to the Assimilative Mapping of Ionospheric Electrodynamics (AMIE) technique (Richmond & Kamide, 1988; Lu, 2017; Matsuo, 2020), but the use of spherical elementary current systems makes it arguably more flexible with respect to spatial extent and resolution.

A Python module that implements everything that is presented in this paper has been published (Laundal et al., 2022). This code also includes the novel method presented in Section 2.4 to calculate the EUV conductance, which does not lead to infinite gradients at the sunlight terminator. The technique and the code are being actively developed, and we plan to make improvements in error estimation, make the inversion more robust, and explore methods to stabilize the solution to give more reliable estimates of the spatiotemporal distribution of ionospheric electrodynamics.

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1038 All data that have been used in this study are included in the Lompe code repos-
 1039 itory (Laundal et al., 2022) as sample datasets. For using Lompe in any other event, we
 1040 refer to the original sources quoted below.

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