High-performance system for monitoring ground deformation from RCM SAR data

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Abstract

Differential Interferometric Synthetic Aperture Radar (DInSAR) based mapping of surface deformation has proven valuable in a variety of geoscience applications. Conventional approaches to DInSAR analysis require significant expertise and are not suited to addressing the opportunities and challenges presented by the large multi-temporal SAR datasets generated by future radar constellations. As a result, the Canada Centre for Mapping and Earth Observation (CCMEO) developed, in support of Natural Resources Canada and Government of Canada priorities, a system for automatic generation of standard and advanced deformation products based on DInSAR technology from RADARSAT Constellation Mission (RCM) Synthetic Aperture Radar (SAR) data. Existing RADARSAT-2 processing algorithms were adapted to RCM specifications and novel advanced processing algorithms were developed to address the large data sets resulting from the constellation's four-day rapid revisit cycle. This permitted expanding the DInSAR functionality across a wide-range of spatial and temporal scales. The system architecture is scalable and can be expanded to serve a large number of clients; it can simultaneously address multiple application areas including natural and anthropogenic hazards, natural resource development, permafrost and glacier monitoring, coastal and environmental change and wetlands mapping.

G41B-0688 HIGH-PERFORMANCE SYSTEM FOR MONITORING GROUND DEFORMATION FROM RCM SAR DATA

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ABSTRACT

Differential Interferometric Synthetic Aperture Radar (DInSAR) based mapping of surface deformation has proven valuable in a variety of geoscience applications. Conventional approaches to DInSAR analysis require significant expertise and are not suited to addressing the opportunities and challenges presented by the large multi-temporal SAR datasets generated by future radar constellations. As a result, the Canada Centre for Mapping and Earth Observation (CCMEO) developed, in support of Natural Resources Canada and Government of Canada priorities, a system for automatic generation of standard and advanced deformation products based on DInSAR technology from RADARSAT Constellation Mission (RCM) Synthetic Aperture Radar (SAR) data. Existing RADARSAT-2 processing algorithms were adapted to RCM specifications and novel advanced processing algorithms were developed to address the large data sets resulting from the constellation's four-day rapid revisit cycle. This permitted expanding the DInSAR functionality across a wide-range of spatial and temporal scales. The system architecture is scalable and can be expanded to serve a large number of clients; it can simultaneously address multiple application areas including natural and anthropogenic hazards, natural resource development, permafrost and glacier monitoring, coastal and environmental change and wetlands mapping.





Table 1: RCM beam modes, where L is the slant range and azimuth spatial sampling, θ is the nominal incidence angle range, R and A are multi-looking numbers in range and azimuth respectively, and NESZ is the nominal Noise Equivalent Sigma Zero that describes the sensitivity of the SAR system.

Beam Name	Beam	Resolution (m)	Swath (Km)	Looks (R x A)	L (m)	θ°	NESZ (dB)
Ship Detection	ScanSAR	variable	350	5 x 1	1.4 x 34.4	40 - 58	variable
Low Noise	ScanSAR	100	350	4 x 2	8.7 x 69.1	19 - 58	-25
Low Resolution 100m	ScanSAR	100	500	8 x 1	4.2 x 69.1	19 - 54	-22
Medium Resolution 50m	ScanSAR	50	350	4 x 1	4.2 x 34.5	19 - 58	-22
Medium Resolution 30m	ScanSAR	30	125	2 x 2	4.2 x 23.0	19 - 47	-24
Medium Resolution 16m	Strip-map	16	30	1 x 4	6.3 x 2.2	19 - 47	-25
Quad-Polarization	Strip-map	9	20	1 x 1	3.1 x 2.9	24 - 44	-24
High Resolution 5m	Strip-map	5	30	1 x 1	2.1 x 2.2	19 - 54	-19
Very High Resolution 3m	Strip-map	3	20	1 x 1	1.4 x 1.9	19 - 54	-17
Spotlight	Spotlight	3 x 1	20 x 5	1 x 1	1.4 x 0.5	19 - 47	-17

Table 2: Supported applications.

Applications	Duration	Displacement Magnitude	DInSAR	SBAS- DInSAR	Offset- tracking	MAI	RSLC
Earthquakes	Abrupt	Small to very large	Х		х	х	
Volcanoes	Gradual and abrupt	Small to very large	х	х			
Landslides	Gradual and abrupt	Small to very large	х	х			
Inter-seismic tectonics	Gradual	Predominantly small	х	х			
Permafrost	Gradual	Predominantly small		х			
Glacial motion	Gradual	Predominantly very large	х		х	Х	
Anthropogenic (mining, groundwater, carbon capture and storage-CCS)	Gradual and abrupt	Predominantly small	х	x			
Change detection	Gradual and abrupt	N/A (Coherence and intensity only)					х

Table 3: Supported products.

Product	Description	Format
Footprint	Image footprint for displaying in Google Earth	kmz
Digital elevation model (DEM)	Digital Elevation Model extracted from the source specified through EODMS interface	Float
Multi-looked intensity (RMLI)	Coregistered intensity images	Float
Unfiltered coherence	Cross-correlation coefficient of the SAR image pair estimated over a small window	Float
Filtered coherence	Unfiltered coherence after applying adaptive filtering	Float
Wrapped unfiltered phase	Differential interferogram of the SAR image pair, flattened and topographic phase removed	Float
Wrapped filtered phase	Differential interferogram after applying adaptive filtering	Float
Unwrapped filtered phase	Unwrapped filtered differential interferogram	Float
Displacement (DInSAR)	Ground displacement along the satellite line of sight (LOS)	Float
Multi-temporal displacements (SBAS DInSAR)	Time series of ground displacements for each SLC epoch	Float
Offset-tracking	Range and azimuth offset maps	Float
Multi-aperture interferometry (MAI)	MAI differential interferogram	Float

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RCM launch date February 2019

RMLI	Coherence
v	

Unit
m
dB
rad
rad
rad
m
m
m
m

Subsidence in Mexico City



Subsidence in Mexico City

20081029-20101211 EW and UD



SCHEMATICS OF THE PROCESSING SYSTEM



ABOUT THE PROCESSING SYSTEM

- Supports processing of RADARSAT-2, RCM and Sentinel-1 data;
- Based on GAMMA Remote Sensing software controlled with BASH scripts; • Time series analysis is performed with the Multidimensional Small Baseline Subset (MSBASv3) software written in C++;
- Runs on a high performance computer (HPC) Linux cluster with over 2000 cores;
- Graphical user interface (GUI) is integrated into the Earth Observation Data Management System (EODMS);
- Processing is parallelized: SAR images and DInSAR interferograms are processed in parallel (sort of MPI), sub-processes are parallelized with OpenMP;
- Output products are produced in geotiff format;

hours.

8.

• The system is accessible to the Government of Canada employees only, accounting information is managed by EODMS system;

• Real time processing is not guaranteed but an estimated latency is only a few





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EXAMPLES OF PRODUCTS PRODUCED BY THE SYSTEM FROM RADARSAT-2 DATA

Piton de la Fournaise Volcanic eruption and landslide



InSAR set	Time span	θ°	ϕ°	N	M
R2-F0W2 (asc)	20120211-20160402	346	36	30	162
R2-F5 (dsc)	20110908-20160414	-165	47	27	118
R2-FQ28 (dsc)	20140519-20150701	-165	47	9	33
Total:	20120211-20160402			64	313

Piton de la Fournaise Volcanic eruption and landslide









227 20 220108 220147 22

The 28 Sept, 2018 M7.5 Indonesia earthquake 20180702-20181006

Cerro Prieto Geothermal Field and 2010 M7.2 El Mayor-Cucapah



RADARSAT-2, MF1 RADARSAT-2. MF4N dsc 13:36 20111001-20160811 -170.3 44.0 58 344

Cerro Prieto Geothermal Field and 2010 M7.2 El Mayor-Cucapah



Subsidence in downtown Seattle





Table 1: DInSAR data sets used in this study: RADARSAT-2 Spotlight 9 and 23 (SLA9, SLA23); time spa (in YYYYMMDD format), range-azimuth resolution, azimuth θ and incidence ϕ angles, number of available

SAR images N, and number of calculated interferograms M for each data se DInSAR set Time span Resolution, m θ° ϕ° N M R2-SLA9 (asc) 20120606-20150816 1.6 - 0.8 349 37 49 549 R2-SLA23 (dsc) 20120606-20150816 1.6 - 0.8 -172 47 46 539 20120606-20150816

50 1088

Subsidence in downtown Seattle



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